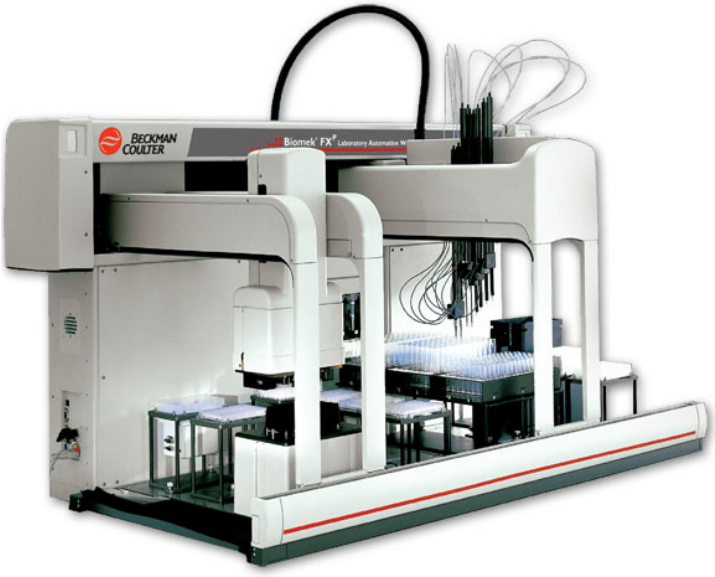
Hardware Manual

Biomek FX and Biomek FX^{P}

Laboratory Automation Workstation



PN 987834AF
September 2014

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BECKMAN COULTER

Biomek FX and Biomek FX^{P} Hardware Manual
PN 987834AF (September 2014)

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Revision History

This document applies to the latest software listed and higher versions. When a subsequent software version changes the information in this document, a new issue will be released.

Issue AE, 9/14

Changes:

- Updated the *Liquid System* section.
- Updated the format of this document.

Safety Notice

Overview

Read all product manuals and consult with Beckman Coulter-trained personnel before attempting to operate the instrument. Do not attempt to perform any procedure before carefully reading all instructions. Always follow product labeling and manufacturer's recommendations. If in doubt as to how to proceed in any situation, contact your Beckman Coulter Representative.

Beckman Coulter, Inc. urges its customers and employees to comply with all national health and safety standards such as the use of barrier protection. This may include, but is not limited to, protective eyewear, gloves, and suitable laboratory attire when operating or maintaining this or any other automated laboratory instrumentation.

⚠ WARNING

If the equipment is used in a manner not specified by Beckman Coulter, Inc., the protection provided by the equipment may be impaired.

Alerts for Warning, Caution, Important, and Note

All Warnings and Cautions in this document include an exclamation point, framed within a triangle.

The exclamation point symbol is an international symbol which serves as a reminder that all safety instructions should be read and understood before installation, use, maintenance, and servicing are attempted.

⚠ WARNING

WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

⚠ CAUTION

CAUTION indicates a potentially hazardous situation, which, if not avoided, may result in minor or moderate injury. It may also be used to alert against unsafe practices.

IMPORTANT IMPORTANT is used for comments that add value to the step or procedure being performed. Following the advice in the Important adds benefit to the performance of a piece of equipment or to a process.

NOTE NOTE is used to call attention to notable information that should be followed during installation, use, or servicing of this equipment.

Instrument Safety Precautions

⚠ WARNING

Risk of operator injury if:

- **All doors, covers and panels are not closed and secured in place prior to and during instrument operation.**
- **The integrity of safety interlocks and sensors is compromised.**
- **You contact moving parts.**
- **You mishandle broken parts.**
- **Doors, covers and panels are not opened, closed, removed and/or replaced with care.**
- **Improper tools are used for troubleshooting.**

To avoid injury:

- **Keep doors, covers and panels closed and secured in place while the instrument in use.**
- **Take full advantage of the safety features of the instrument. Do not defeat safety interlocks and sensors.**
- **Acknowledge and act upon instrument alarms and error messages.**
- **Keep away from moving parts.**
- **Report any broken parts to your Beckman Coulter Representative.**
- **Use the proper tools when troubleshooting.**

⚠ CAUTION

System integrity could be compromised and operational failures could occur if:

- **This equipment is used in a manner other than specified. Operate the instrument as instructed in the Product Manuals.**
- **You introduce software that is not authorized by Beckman Coulter into your computer. Only operate your system's computer with software authorized by Beckman Coulter.**
- **You install software that is not an original copyrighted version. Only use software that is an original copyrighted version to prevent virus contamination.**

⚠ CAUTION

If you purchased this product from anyone other than Beckman Coulter or an authorized Beckman Coulter distributor, and, if it is not presently under a Beckman Coulter Service Maintenance Agreement, Beckman Coulter cannot guarantee that the product is fitted with the most current mandatory engineering revisions or that you will receive the most current information bulletins

concerning the product. If you purchased this product from a third party and would like further information concerning this topic, contact your Beckman Coulter Representative.

Electrical Safety

To prevent electrically related injuries and property damage, properly inspect all electrical equipment prior to use and immediately report any electrical deficiencies. Contact a Beckman Coulter Representative for any servicing of equipment requiring the removal of covers or panels.

High Voltage

This symbol indicates the potential of an electrical shock hazard existing from a high-voltage source and that all safety instructions should be read and understood before proceeding with the installation, maintenance, and servicing of all modules.

Do not remove system covers. To avoid electrical shock, use supplied power cords only and connect to properly grounded (three-holed) outlets.

Laser Light

This symbol indicates that a potential hazard to personal safety exists from a laser source. When this symbol is displayed in this manual, pay special attention to the specific safety information associated with the symbol.

Laser Specifications

- **Laser Type:** Class II Laser Diode
- **Maximum Output:** 11 mW
- **Wavelength:** 670 nm

Disposal of Electronic Equipment

It is important to understand and follow all laws regarding the safe and proper disposal of electrical instrumentation.

The symbol of a crossed-out wheeled bin on the product is required in accordance with the Waste Electrical and Electronic Equipment (WEEE) Directive of the European Union. The presence of this marking on the product indicates:

- That the device was put on the European Market after August 13, 2005 and
- That the device is not to be disposed via the municipal waste collection system of any member state of the European Union.

For products under the requirement of WEEE directive, please contact your dealer or local Beckman Coulter office for the proper decontamination information and take back program which will facilitate the proper collection, treatment, recovery, recycling, and safe disposal of device.

Chemical and Biological Safety

If a hazardous substance such as blood is spilled onto the instrument, ALPs, or accessories, clean up the spill by using a 10% bleach solution, or use your laboratory decontamination solution. Then follow your laboratory procedure for disposal of hazardous materials. If the instrument, ALPs, or accessories need to be decontaminated, contact your Beckman Coulter Representative.

⚠ WARNING

Risk of chemical injury from bleach. To avoid contact with the bleach, use barrier protection, including protective eyewear, gloves, and suitable laboratory attire. Refer to the Safety Data Sheet for details about chemical exposure before using the chemical.

⚠ WARNING

Before running with chemistry or any biological samples, new labware types will require testing to determine if labware offsets are necessary to move to or from the Peltier ALP, or to access the labware during pipetting operations while on the Peltier ALP. If you do not do the required testing, the labware could crash and the contents could spill if the offset is incorrect.

Normal operation of the instrument may involve the use of materials that are toxic, flammable, or otherwise biologically harmful. When using such materials, observe the following precautions:

- **Handle infectious samples according to good laboratory procedures and methods to prevent the spread of disease.**
- **Observe all cautionary information printed on the original solutions containers prior to their use.**
- **Dispose of all waste solutions according to your facility's waste disposal procedures.**
- **Operate the instrument in accordance with the instructions outlined in this manual and take all the necessary precautions when using pathological, toxic, or radioactive materials.**
- **Splashing of liquids may occur; therefore, take appropriate safety precautions, such as using safety glasses and wearing protective clothing, when working with potentially hazardous liquids.**
- **Use an appropriately-contained environment when using hazardous materials.**
- **Observe the appropriate cautionary procedures as defined by your safety officer when using flammable solvents in or near a powered-up instrument.**
- **Observe the appropriate cautionary procedures as defined by your safety officer when using toxic, pathological, or radioactive materials.**

NOTE Observe all warnings and cautions listed for any external devices attached or used during operation of the instrument. Refer to applicable external device user's manuals for operating procedures of that device.

NOTE For Safety Data Sheets (SDS/MSDS) information, go to the Beckman Coulter website at **www.beckmancoulter.com**.

Moving Parts

⚠ WARNING

Risk of personal injury. To avoid injury due to moving parts, observe the following:

- **Never attempt to exchange labware, reagents, or tools while the instrument is operating.**
- **Never attempt to physically restrict any of the moving components of the instrument.**
- **Keep the instrument work area clear to prevent obstruction of the movement.**

Cleaning

Observe the cleaning procedures outlined in this user's manual for the instrument. Prior to cleaning equipment that has been exposed to hazardous material:

- Contact the appropriate Chemical and Biological Safety personnel.
- Review the Chemical and Biological Safety information in the user's manual.

Maintenance

Perform only the maintenance described in this manual. Maintenance other than that specified in this manual should be performed only by service engineers.

IMPORTANT It is your responsibility to decontaminate components of the instrument before requesting service by a Beckman Coulter Representative or returning parts to Beckman Coulter. Beckman Coulter will NOT accept any items which have not been decontaminated where it is appropriate to do so. If any parts are returned, they must be enclosed in a sealed plastic bag stating that the contents are safe to handle and are not contaminated.

RoHS Notice

These labels and materials declaration table (the Table of Hazardous Substance's Name and Concentration) are to meet People's Republic of China Electronic Industry Standard SJ/T11364-2006 "Marking for Control of Pollution Caused by Electronic Information Products" requirements.

China RoHS Caution Label

This logo indicates that this electronic information product contains certain toxic or hazardous substances or elements, and can be used safely during its environmental protection use period. The number in the middle of the logo indicates the environmental protection use period for the product. The outer circle indicates that the product can be recycled. The logo also signifies that the product should be recycled immediately after its environmental protection use period has expired. The date on the label indicates the date of manufacture.

China RoHS Environmental Label

This logo indicates that the product does not contain any toxic or hazardous substances or elements. The "e" stands for electrical, electronic and environmental electronic information products. This logo indicates that this electronic information product does not contain any toxic or hazardous substances or elements, and is green and environmental. The outer circle indicates that the product can be recycled. The logo also signifies that the product can be recycled after being discarded, and should not be casually discarded.

Contents

Illustrations

Tables

Introduction

Overview

NOTE Unless otherwise noted, all information in this hardware manual refers to both the Biomek FX and FX^P instruments.

The Biomek FX Laboratory Automation Workstation (Figure 1) is a multiaxis liquid-handling instrument used in the drug discovery laboratory. The open-architecture design, along with the extensible operating software, provides a foundation for integrating current and future specific-use components. The design of the Biomek FX provides the foundation for continual evolution and expansion of liquid-handling systems.

The Biomek FX is available as a single- or dual-pod instrument. Different operating components can be installed on each pod, providing options for performing a variety of functions sequentially or simultaneously, depending upon desired tasks and configurations.

A variety of labware and hardware adapt the deck of the Biomek FX to accomplish multiple tasks, ranging from performing simple labware positioning and liquid transfers to completing complex activities that typically require additional devices in the laboratory.

The capabilities of the Biomek FX depend on the components installed, including the pod(s) and head(s), ALPs, and third party devices.

The chapters in this user's manual are arranged according to the components of the Biomek FX:

- Biomek FX instrument basics (this chapter).
- CHAPTER 1, *Multichannel Pod*
- CHAPTER 2, *Span-8 Pod*
- CHAPTER 3, *Configuring the Biomek FX in Hardware Setup*
- CHAPTER 4, *Framing the Biomek FX*
- CHAPTER 5, *Manually Controlling the Biomek FX in Biomek Software*

The appendices include system specifications and instructions for integrating the Biomek FX with a Stacker Carousel:

- APPENDIX A, *Specifications*
- APPENDIX B, *Using a Stacker Carousel*

Pod Configurations for the Biomek FX

The Biomek FX instrument is capable of supporting up to two bridges. Each bridge on the Biomek FX instrument holds one pod.

The available pod configurations for a single-pod instrument are:

- One Multichannel Pod (with either a 96-Channel 20 µL Head, a 96-Channel 200 µL Head, a 384-Channel Head, or an HDR Tool Body)
- One Span-8 Pod

Available pod configurations for a dual-pod instrument are:

- Two Multichannel Pods (any combination of heads)
- One Multichannel Pod (any head) and one Span-8 Pod

NOTE For detailed information on the Multichannel Pod and interchangeable heads, refer to CHAPTER 1, *Multichannel Pod*. For detailed information on the Span-8 Pod and probes, refer to CHAPTER 2, *Span-8 Pod*.

Control Modes

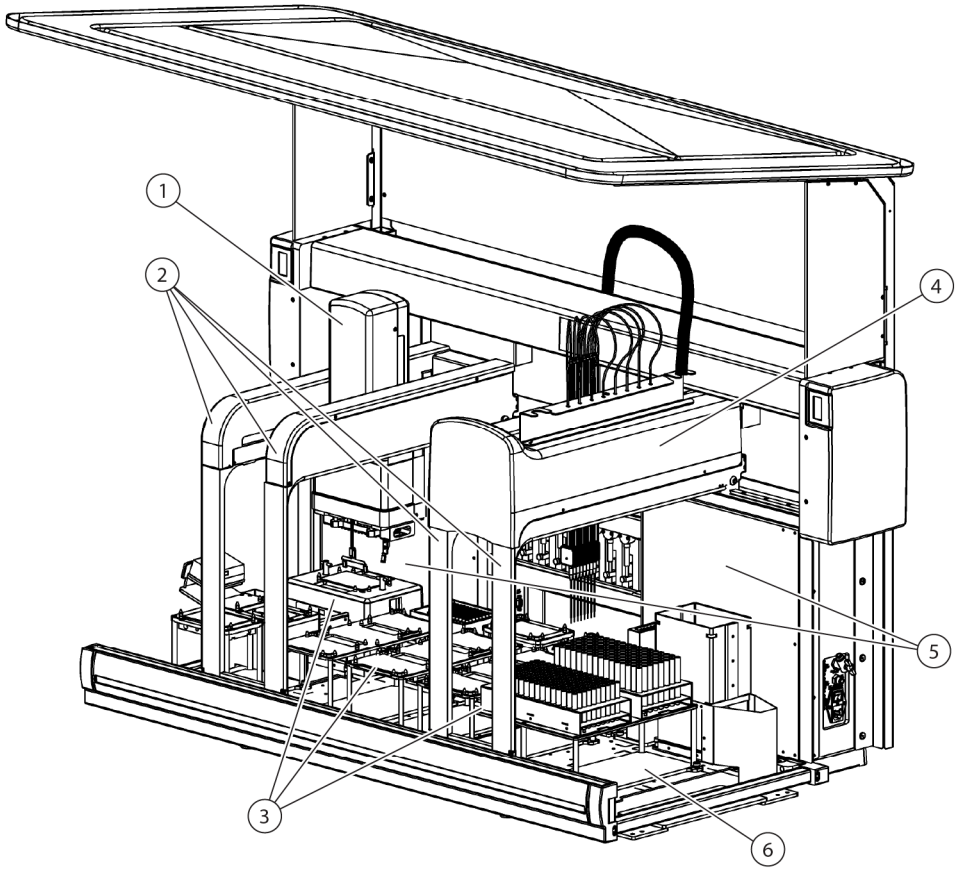
The Biomek FX is controlled using Biomek Software operated from the host computer. The Biomek FX can be:

- Operated as a standalone instrument, gripping and moving microplates without the assistance of a laboratory robot.
- Integrated into an automated robotic system.
- Operated using a combination of these capabilities.

System Components

The system components described below correspond to the components shown in Figure 1.

Figure 1 Biomek FX Main Components

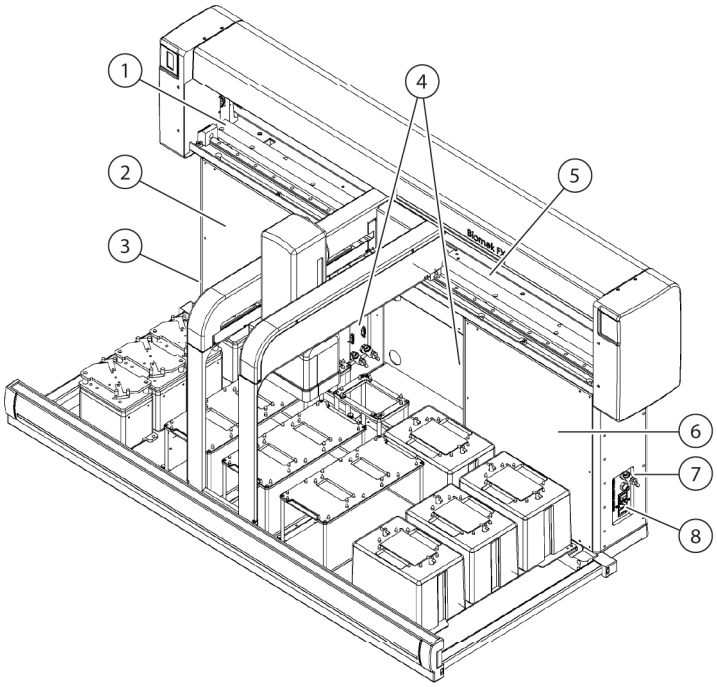


1. Multichannel *Pods and Heads*
2. *Bridges*
3. *ALPs*
4. Span-8 *Pods and Heads*
5. *Towers*
6. *Deck*

Towers

The Biomek FX towers form the rear vertical and horizontal uprights of the base unit along which the bridges travel in the X-axis. The links for master control of the Biomek FX, plus utility hook-ups and ALP connections, are on the towers. Built into the towers are green and amber indicator lights that keep users aware of the current operational status of Biomek FX instrument.

Figure 2 Main Components and Connections of the Biomek FX Towers



1. X-Axis Linear Rail
2. Left Tower
3. Outside Left Tower Connections (see Figure 3 for close-up)
4. Inside Tower Connections (see Figure 3 for close-up)
5. X-Axis Travel Plate
6. Right Tower
7. Outside Right Tower Connections (see Figure 3 for close-up)
8. Main Power Switch

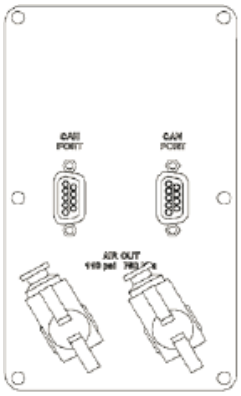
The towers house the following main components (Figure 2) and connections (Figure 3):

- X-axis linear rail travel plate for the bridges.
- Main power switch on the outside of the right tower.
- Communication hookup to host computer via RS232 on the outside of the left tower.
- Electrical plug-ins and CAN connections for active ALPs on the inside and outside of both towers.
- Pneumatically regulated air supply ports on the inside and outside of both towers for active ALPs.
- Main power fuses for the instrument on the outside of the right tower.

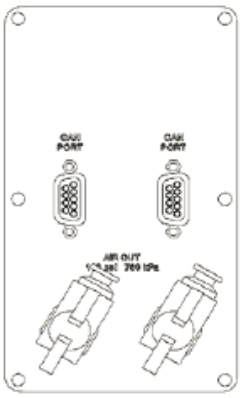
Figure 3 Inside and Outside Tower Connections (Detail View)

Inside Tower Connections

Left

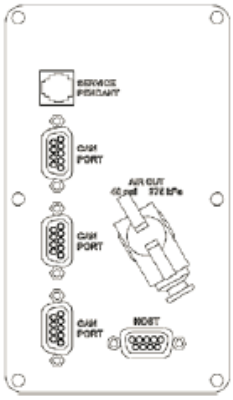


Right

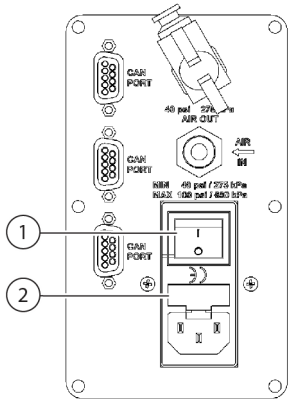


Outside Tower Connections

Left



Right



1.Main Power Switch
2.Fuse Carrier

Indicator Lights

A status indicator panel with green and amber indicator lights is built into the main cover and indicates the current operational status of the Biomek instrument and light curtain (*Light Curtain Protection System*). Table 1 defines the indicator light and the operational status each represents.

Table 1 Indicator Light Key

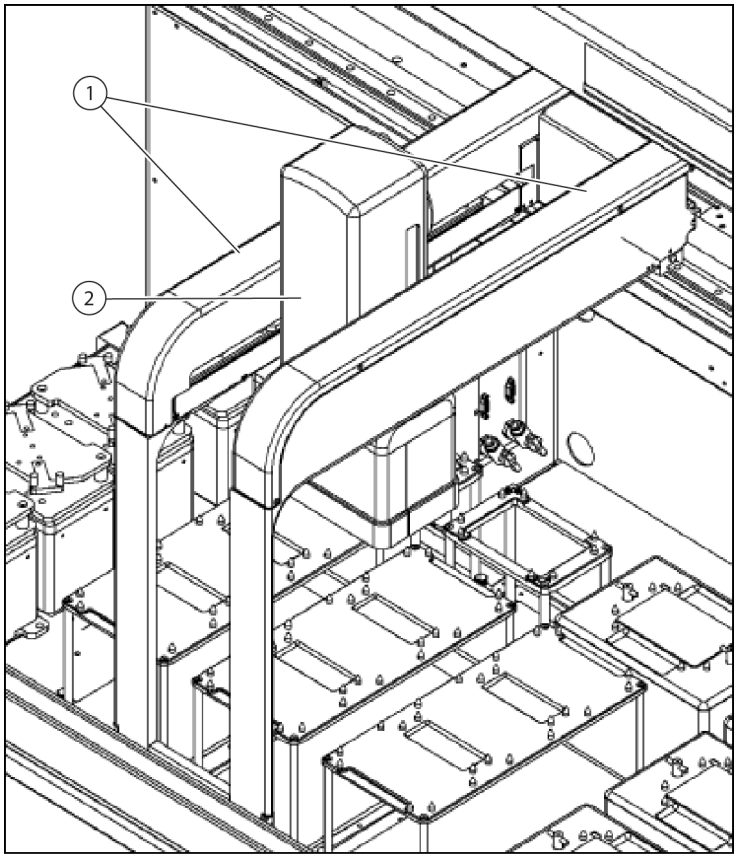
Light Indicator	State	Operational Status
Solid Green	Idle	System is functional and in a ready state. It is safe to access the instrument and deck without violating the light curtain protective zone.
Blinking Green	Pause	Planned pause. This may be written into a method to allow periodic access to the deck. When pause is terminated, the light curtain is reactivated and the method continues.
Solid Amber	Active	A method is running. A violation of the light curtain will halt operation.
Blinking Amber	Error	Caused by light curtain violation or system error. Halts pod and head operations immediately. Software communicates the cause.

Bridges

The Biomek FX bridges (Figure 4) are structures that move in the X-axis. The bridges hold the pods and move them in the Y- (front to back) and Z-axes (up and down). One or two bridges are available on the Biomek FX instrument to create a single- or dual-pod instrument. In a dual-pod system, the pods can work together to expand liquid-handling capabilities.

NOTE The left and right bridges on a dual-pod instrument are defined by viewing the instrument from the front.

Figure 4 Bridges Move in the X-Axis and Hold and Move Pods in the Y- and Z-Axes



1. Bridges on a Single-Pod Instrument
2. Multichannel Pod

Pods and Heads

Pods are self-contained components supported and positioned by the bridges. There are two types of pods available for the Biomek FX instrument:

- Multichannel Pod — holds various removable and interchangeable heads, such as the 96-Channel 200 µL Head, that perform liquid-handling operations, and a pair of grippers for labware movement operations. Refer to CHAPTER 1, *Multichannel Pod*, for more information on the Multichannel Pod and interchangeable heads.
- Span-8 Pod — holds a series of eight probes that perform liquid-handling operations independent of each other. Refer to CHAPTER 2, *Span-8 Pod*, for more information on the Span-8 Pod.

The operation of the pods, heads, and probes are controlled by Biomek Software from the Biomek controller host PC.

Deck

The deck is the worksurface of the Biomek FX instrument. The three-section stainless steel deck is mounted on a cast aluminum base plate and laser-etched with standard deck positions. The deck also contains predrilled locating holes used to precisely position ALPs (refer to *ALPs*), and thumbscrew holes to fasten ALPs securely to the deck. Sections of the deck are removable so external devices (refer to *Optional Devices and Solutions*) can be positioned within the Biomek FX perimeter, making them accessible by a pod.

NOTE Some ALPs and devices require a Device Controller (*Device Controller*) to provide power and communications between the device and the Biomek FX instrument.

ALPs

Automated Labware Positioners (ALPs) are removable and interchangeable platform structures that are installed on the Biomek deck to allow automated assays to be performed.

Automated Labware Positioners (ALPs) are removable and interchangeable platform structures that are installed on the Biomek deck to allow automated assays to be performed.

ALPs are either:

- Passive ALPs — some hold labware in place on the deck while others act as a receptacles for by-products from methods, such as system fluid and disposed tips, tip boxes, and labware.

  OR

- Active ALPs — contain mechanisms that may hook to power and/or air sources for mechanical operation, such as tip loading, tip washing, mixing/stirring, shaking, and precisely positioning labware.

NOTE Refer to the *ALPs User's Manual* (PN 987836) for detailed information on all available ALPs for the Biomek FX.

Optional Devices and Solutions

Optional devices and solutions, such as a Stacker Carousel, can be integrated with the Biomek FX instrument to accommodate specific operations.

NOTE Refer to APPENDIX B, *Using a Stacker Carousel* for information about integrating a Stacker Carousel.

Device Controller

A Device Controller is a peripheral box that connects to the Biomek FX to provide a means to control a number of high voltage (110VAC-220VAC) and low voltage (24VDC) devices, and low voltage digital inputs. High voltage devices receive power through an AC Power Input, while low voltage devices receive power through the Controller Area Network (CAN) interface located on the back of the Device Controller. Some ALPs and devices require a Device Controller to use them on the deck of the Biomek FX.

NOTE Refer to the *ALPs User's Manual* (PN 987836), Appendix A, *Device Controller* for detailed information about connecting and controlling devices using a device controller.

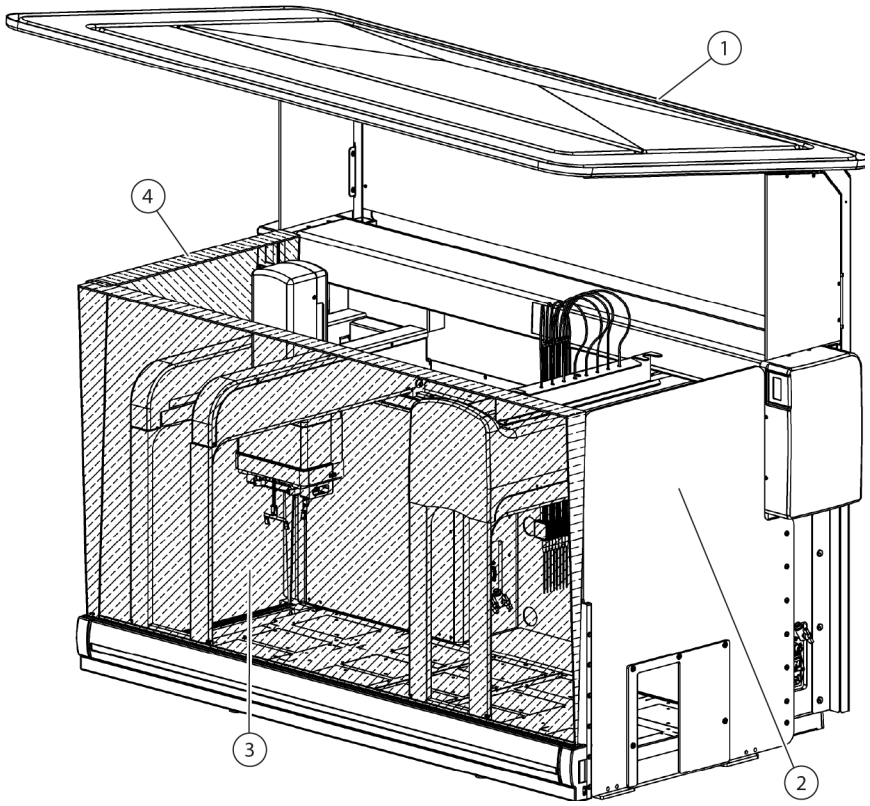
Protective Barriers

A perimeter protective safety system is standard for the Biomek FX instrument. This safety system helps protect against operator injury, damage to the equipment, and interruptions during the liquid-handling process. The standard Biomek FX perimeter protective system includes a diffuse-reflective light curtain along the front of the instrument and either diffuse-reflective side light curtains, or protective side safety shields along the left and right sides of the instrument.

Components of the perimeter protective safety system may include (see Figure 5):

- A diffuse-reflective perimeter light curtain along the front edge of the Biomek FX instrument.
- A diffuse-reflective perimeter light curtain along either or both sides of the Biomek FX instrument.
- Side safety shields.
- An overhead canopy.

Figure 5 Protective Barriers for the Biomek FX Instrument



1. Canopy
2. Protective Side Safety Shield
3. Front Light Curtain
4. Side Light Curtain

⚠ WARNING

Either safety shields or light curtains must be installed along the front and sides of the Biomek FX instrument to provide the required safety. The Biomek FX operates with a force that could cause injury if a hand is in the way during the loading of tips or other movement of the pipetting head. The safety shields and light curtains prevent entry into the work area during machine movement.

⚠ WARNING

To reduce the risk of personal injury, the safety shields or light curtains must be in place before operating.

Configuration options for the perimeter protective system include:

- Front light curtain with both left and right side light curtains.
- Front light curtain, left side light curtain, and right side safety shield.
- Front light curtain, right side light curtain, and left side safety shield.

- Front light curtain with both left and right side safety shields.

Light Curtain Protection System

⚠ WARNING

Dark non-reflective material affects the sensitivity of the light curtain and adversely impact its effectiveness. Typical lab dress, such as lab coats and latex gloves, do not degrade light curtain operation; however, it is advisable to test the impact of the all lab dress on light curtain sensitivity before operating the Biomek FX. Verify lab dress impact on light curtain sensitivity as follows: Use Manual Control in the software and insert the material no more than 1 in. past and approximately 21 in. above the light curtain panel. Make sure the solid amber indicator light changes to blinking amber.

The diffuse-reflective perimeter light curtain along the front edge of the Biomek FX instrument is a standard component; however, light curtains can also be installed along both sides of the Biomek FX instrument.

NOTE Either side light curtains or side safety shields must be installed by a Beckman Coulter Service Representative when the Biomek FX instrument is installed.

The light curtain projects a diffused array of infrared light, rather than a vertical laser-like beam (Figure 5). When a part of the human body or an object larger than approximately 1" in diameter (such as labware and large cables) penetrates this protective zone, the instrument shuts down immediately, stopping all pod and head operations. Some ALP operations, such as shaking or stirring, continue.

ALPs respond to a violation according to safety and operational requirements specific to each ALP. For example, a refilling reservoir may continue to operate if user safety is not compromised. ALPs that operate with a motion that could present a danger to the operator go to a safe state when the light curtain is violated.

NOTE When active ALPs or optional devices are operating and the light curtain is violated, an error message may not appear until after the ALP or optional device operation is complete.

NOTE It is important to become familiar with this protected zone. This reduces the possibility of causing the instrument to shut down accidentally during operation by unintentionally violating the light curtain zone.

When the instrument is sitting idle or in the paused mode, no violations are registered when the protective zone is penetrated. This allows full access to instrument components, ALPs, and labware on the Biomek FX deck during a pause or system idle time.

Protective Side Safety Shields

⚠ WARNING

To reduce the risk of personal injury, operate the Biomek FX instrument only with all protective shields in place.

Protective shields are available for installation along the sides of the Biomek FX instrument when side light curtains are not in use. Protective shields are installed by the Beckman Coulter Representative if side light curtain options are not utilized. If the instrument overhangs the table work surface on either side, a protective bottom shield is also installed on the side of the instrument overhanging the instrument envelope.

NOTE Either side light curtains or side safety shields must be installed by a Beckman Coulter Service Representative when the Biomek FX instrument is installed on site.

Canopy

The Biomek FX light curtain is blocked by a canopy that attaches to the towers and extends over the top of the instrument (Figure 5). The canopy stops light curtain violations resulting from movement above the instrument.

Preventive Maintenance

To ensure optimum operation of the Biomek FX, perform the following maintenance procedures as necessary.

⚠ WARNING

To prevent injury, use proper decontamination procedures.

- **Wipe up all spills on the deck immediately.**
- **Approximately every six to twelve months, schedule a Beckman Coulter service call to lubricate the linear rail.**

Light Curtain Maintenance

To ensure optimum operation of the light curtain protective system, perform the following maintenance procedures as necessary:

- Once a week, verify proper operation of light curtain using Manual Control in the software (refer to CHAPTER 5, *Manually Controlling the Biomek FX in Biomek Software*)and the light curtain test rod supplied with the Biomek FX. Insert the test rod no more than 1" past and approximately 21 in. above the front light curtain panel. If side light curtains are installed on your Biomek FX instrument, repeat this process approximately 24" above the side light curtain panel(s). Check to make sure the solid amber indicator light changes to blinking amber each time the light curtain is violated. If not, contact your Beckman Coulter Representative.
- When necessary, clean light curtain panels with a lint-free cloth.
- Once every 2-3 months, clean light curtain panels with a non-abrasive cleaner, making sure not to scratch the strip.

Troubleshooting

⚠ CAUTION

If service is required, contact your Beckman Coulter Representative.

Perform the troubleshooting techniques provided in Table 2 when necessary.

In the case of any other instrument-related problems, contact a Beckman Coulter Representative.

NOTE For troubleshooting information regarding the specific pods, refer to the Troubleshooting section in those respective chapters.

Table 2 Troubleshooting the Biomek FX Instrument

If	Then
All indicator lights are out	Check fuses.
The power is on, but system does not run	Check fuses.
The fuses appear burned or filaments are broken	Change fuses (*Changing Fuses*).
All indicator lights are out, the power is on, the fuses are okay, and the system does not run	Contact your Beckman Coulter Representative.
Power is lost to pod	Contact your Beckman Coulter Representative.
Y-axis motion is choppy	Contact your Beckman Coulter Representative.
A grinding or growling noise is heard	Contact your Beckman Coulter Representative.
Experiencing problems relating to the Multichannel Pod	CHAPTER 2, *Troubleshooting* in CHAPTER 1, *Multichannel Pod*, for more information.

Table 2 Troubleshooting the Biomek FX Instrument

If	Then
Experiencing problems relating to the Span-8 Pod	CHAPTER 2, *Troubleshooting*, in CHAPTER 2, *Span-8 Pod*, for more information.
Constant light curtain errors, even when no violation	Clean light curtain panels as described in *Light Curtain Maintenance*. Contact your Beckman Coulter Representative.

Changing Fuses

⚠ WARNING

Do not remove tower covers to access electrical wiring or fuses. Change only the fuses that are accessed from the outside of the instrument, without removing covers. Contact your Beckman Coulter Representative if further access is required.

⚠ WARNING

Turn off and unplug power to the instrument before changing fuses. Failure to do so can cause electrical shock or equipment damage.

The Biomek FX instrument uses any AC power source between 100V and 240V. The fuse holder holds two fuses.

Fuses are located in the outside right tower (Figure 6). If power is lost, check the fuses that are accessed from the outside of the instrument.

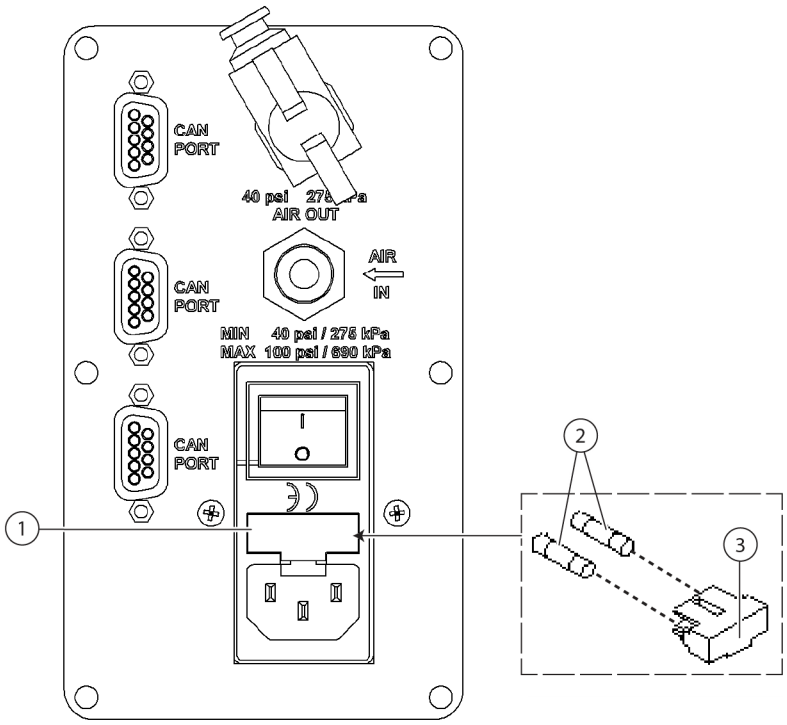
If fuses appear burned, change them by completing the following:

1 Turn off the instrument power switch.

2 Unplug the instrument from the power source.

3 Using a small flathead screwdriver, pry open the fuse carrier containing two fuses (Figure 6) from the AC power input module.

Figure 6 Replacing Fuses in Tower



1. Fuse Carrier
2. Fuses
3. Fuse Carrier Cover

4 Gently pull old fuses from the carrier by hand.

5 Gently place new fuses into carrier by hand.

NOTE Use 250v 3.15 amp 5x20 slow-blow type fuses for replacement.

6 Replace the fuse carrier into the AC power input module.

7 Plug the instrument into the power source.

8 Turn on the instrument power switch.

CHAPTER 1

Multichannel Pod

Overview

The Multichannel Pod is a self-contained working unit installed on the right, left, or both bridges of the Biomek FX (Figure 1.1). The Multichannel Pod is a full-microplate replication tool incorporating a gripper and interchangeable heads to accommodate a variety of functions (refer to *Interchangeable Heads*).

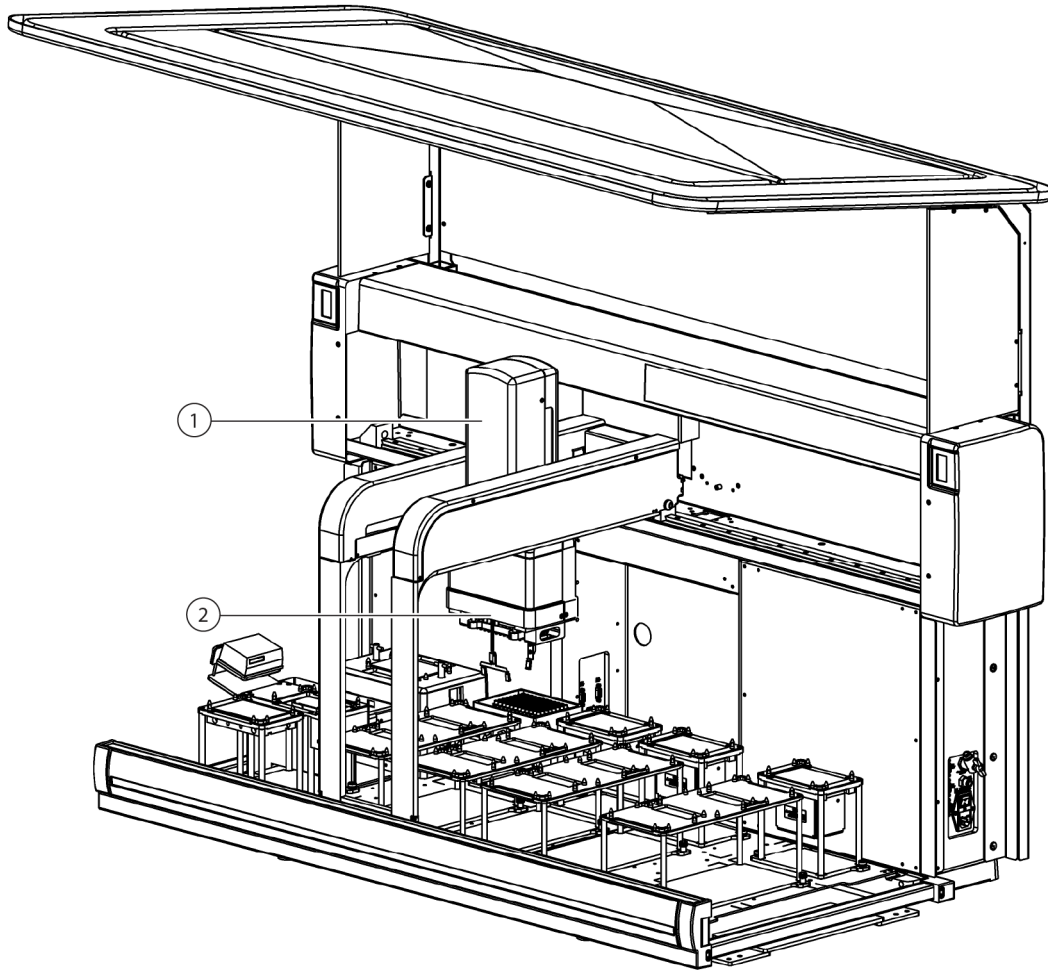
The Multichannel Pod contains its own electrical cabling, communication, and pneumatic connections with the base unit, and it interacts with ALPs located over the entire deck area of the Biomek FX.

NOTE When installed on a dual-pod system, the pod mounted on the left side of the Biomek FX instrument is only capable of accessing ALPs on that side of the deck, while a pod mounted on the right side of the Biomek FX instrument can only access ALPs on the right side of the deck.

The sections in this chapter include:

- *Pod*
- *Interchangeable Heads*
- *Gripper*
- *Preventive Maintenance*
- *Troubleshooting*

Figure 1.1 Multichannel Pod Installed on Biomek FX



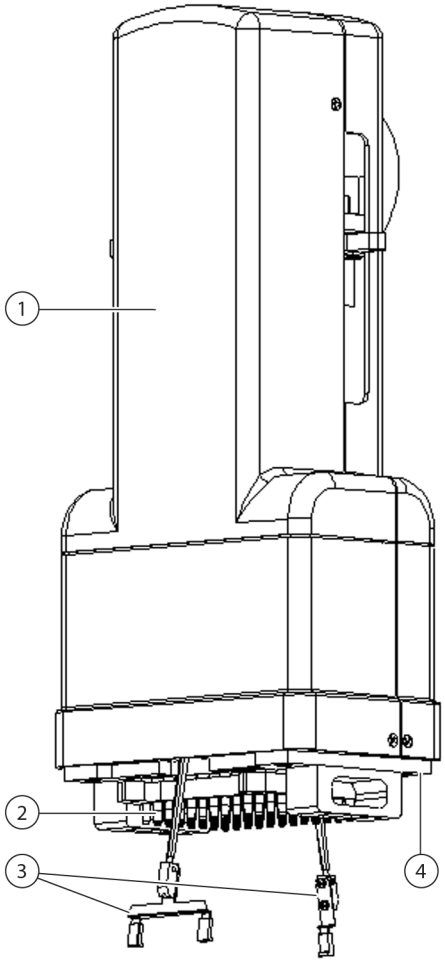
1. Multichannel Pod (Gripper Extended)
2. Head

Main Components of the Multichannel Pod

The main components of the Multichannel Pod are (Figure 1.2):

- *Pod* — Houses operating mechanism, pneumatic air line, communication and electrical power connections to the base unit, and moves in the Y-, Z-, and D-axes for liquid-handling functions.
- *Interchangeable Heads* — Holds mandrels and tips for performing full-plate replication.
- *Gripper* — Grip labware along the long side of the labware.

Figure 1.2 Multichannel Pod — Main Components



1. Pod
2. Mandrels
3. Grippers
4. Head

Pod

The Multichannel Pod is a full-microplate replication tool incorporating a gripper and interchangeable heads to accommodate a variety of functions.

Pod Movements

The Multichannel Pod performs movements in the Y-, Z-, and D-axes (see Table 1.1).

Table 1.1 Multichannel Pod Axes Movement

Axis	Movement
Y-	Entire pod moves front-to-back.
Z-	Entire pod moves up-and-down.
D-	Up-and-down aspirate/dispense, disposable tip shucking, and close/open gripper.

Control Modes

Commands entered via Biomek Software on the host computer control the operations of the Multichannel Pod. Manual control associated with the operation of the Multichannel Pod is accessed through Biomek Software.

NOTE Refer to CHAPTER 5, *Manually Controlling the Biomek FX in Biomek Software*, for information on manually controlling the Multichannel Pod.

Interchangeable Heads

An interchangeable, multichannel head is attached to the bottom of the pod to perform a specific liquid-handling procedure. Depending on the head and the desired liquid-handling procedure, different tip types may be used.

Presently, there are four types of heads that can be attached to the Multichannel Pod:

- 96-Channel 20 µL Head
- 96-Channel 200 µL Head
- 384-Channel 30 µL Head
- HDR Tool Body

Interchangeable heads installed on the Multichannel Pod aspirate and dispense liquid using disposable tips. The tips compatible and the maximum volume that may be aspirated and dispensed with those tips varies for each head, as described in Table 1.2.

NOTE The HDR Tool Body uses pin plates to perform low-volume liquid transfers by liquid adhesion (refer to *Interchangeable Pin Plates for the HDR Tool Body*).

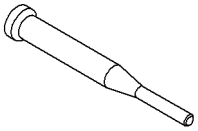
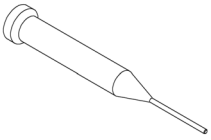
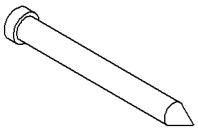
Table 1.2 Tip Compatibility and Max Volumes on Multichannel Heads

Head	Tip Type	P200	P200_Barrier	P200	P200_Barrier	P200	P200_Barrier
96-Channel 20 µL Head		55 µL	20 µL	--	--	55 µL	50 µL
96-Channel 200 µL Head		120 µL	20 µL	--	--	225 µL	125 µL
384-Channel 30 µL Head		--	--	35 µL	30 µL	--	--

Interchangeable Pin Plates for the HDR Tool Body

An interchangeable pin plate is attached to the mount plate on the bottom of the HDR Tool Body. Pin plates are available in 96-pin and 384-pin capacities and may have any of the pin types presented in Table 1.3:

Table 1.3 Pin Types

Image	Pin Type	Description
	0.045 in. Post	• A cylindrical pin with a 0.045 in. diameter. • Can access 96- and 384-well microplates.
	0.015 in. Post	• A cylindrical pin with a 0.015 in. diameter. • Can access 96-, 384-, and 1536-well microplates.
	0.015 in. Nail	• A cylindrical pin with a 0.015 in. conical tip. • Can access 96- and 384-well microplates.

Installing Pin Plates

To install a pin plate on the HDR Tool Body:

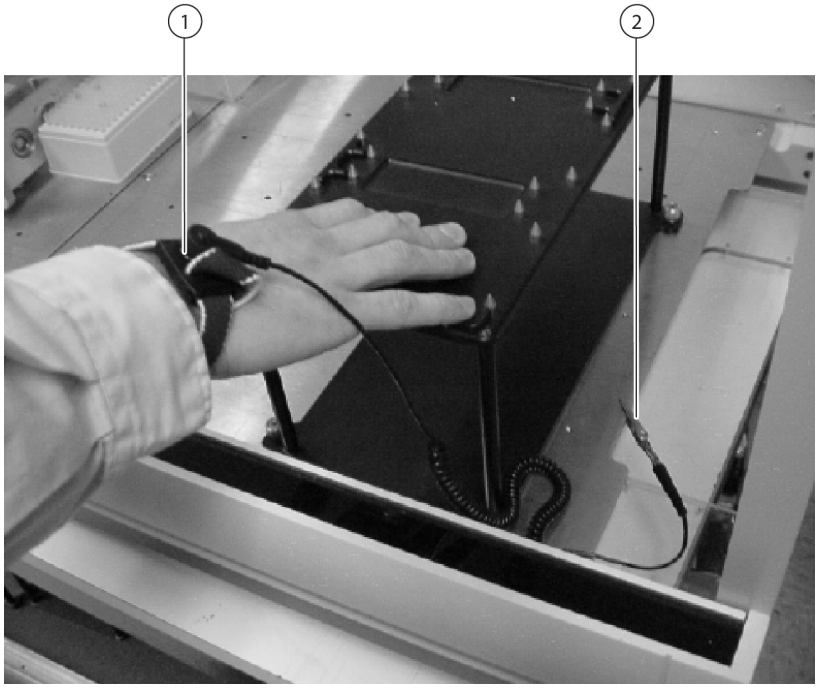
NOTE When a pin plate is changed, the Hardware Setup must be changed appropriately. If the hardware configuration is not updated using Hardware Setup, inaccurate liquid transfers may occur (refer to the *ALPs User's Manual* (PN 987836), *Installing and Configuring Devices Associated with the HDR Pin Drying ALP*, and *Circulating Reservoir in Hardware Setup*). Also check the Tip Type Editor and make sure the settings for the Pins tip type match the manufacturer's specifications for the pins installed on the HDR Tool Body (refer to the *Biomek Software User's Manual* (PN 987835), *Changing Tip Properties*).

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when installing pin plates.

NOTE A wrist ground strap, which must be attached to the instrument deck (base plate) using the "alligator" clip, is supplied with the Biomek FX instrument (Figure 1.3).

Figure 1.3 Wrist Ground Strap Attached to the Deck



1. Strap portion of wrist ground strap snugly attached to the wrist.
2. "Alligator" clip clamped to the instrument deck (base plate)

---

1 Using **Manual Control,** lower the pod along the D-axis 0.9 cm from the maximum height and extend the gripper (refer to CHAPTER 5, *Manually Controlling the Biomek FX in Biomek Software*).

---

2 Turn off power to the Biomek FX instrument.

---

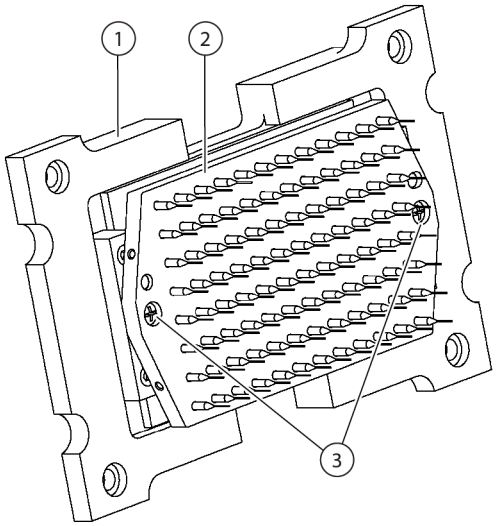
3 Slide the pin plate up between the gripper to the HDR Tool Body such that the holes in the pin plate line up with the locating pins on the HDR Tool Body.

⚠ CAUTION

Carefully hold the pin plate by the edges to avoid bending or damaging the pins.

4 While holding the pin plate in position, tighten the two Phillips head captive screws to attach the pin plate to the HDR Tool Body (Figure 1.4).

Figure 1.4 Fastening the Pin Plate to the HDR Tool Body



1. HDR Tool Body
2. Pin Plate
3. Captive Screws

Removing Pin Plates

To remove a pin plate from the HDR Tool Body:

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when installing the HDR Tool Body.

NOTE A wrist ground strap, which must be attached to the instrument deck (base plate) using the "alligator" clip, is supplied with the Biomek FX instrument.

1 Using **Manual Control**, lower the pod along the D-axis 0.9 cm from the maximum height and extend the grippers.

2 Turn off power to the Biomek FX instrument.

3 While holding the pin plate, loosen the two Phillips head captive screws to free the pin plate from the HDR Tool Body (Figure 1.8).

⚠ CAUTION

Carefully hold the pin plate by the edges to avoid bending or damaging the tips.

4 Remove the pin plate by sliding it down between the grippers.

5 Store pin plate according to instructions in *Storing HDR Pins*.

Replacing Bent or Damaged Pins

To replace damaged or bent pins:

1 Remove the pin plate from the HDR Tool Body (refer to *Removing Pin Plates*).

2 Place the populated pin plate with pins pointing down in a 96-well microplate for a 96-pin plate or a 384-well microplate for a 384-pin plate.

3 Remove any damaged or bent pins by lifting them out of the pin plate.

4 Drop the replacement pin gently into position.

5 Reinstall the pin plate on the HDR Tool Body (refer to *Installing Pin Plates*).

Storing HDR Pins

To store HDR pins:

⚠ CAUTION

Always store pins in the pin plate or pin storage case to prevent pins from getting damaged or bent.

1 Place the populated pin plate with pins pointing down in a 96-well microplate for a 96-pin plate or a 384-well microplate for a 384-pin plate.

2 Put on the pin capture plate to keep pins from falling out.

3 Return the pin plate and pins to the original packing materials and store in a dry, dust-free, environmentally controlled area.

NOTE It is desirable to allow the pin plate and pins to air-dry before returning them to the original packing materials.

Changing Heads

Each Multichannel head can be removed and replaced to accommodate the needs of a particular method.

NOTE When a head is changed, the **Hardware Setup** must be changed appropriately. If the hardware configuration is not updated using **Hardware Setup**, inaccurate pipetting may occur (refer to *Configuring a Multichannel Pod*).

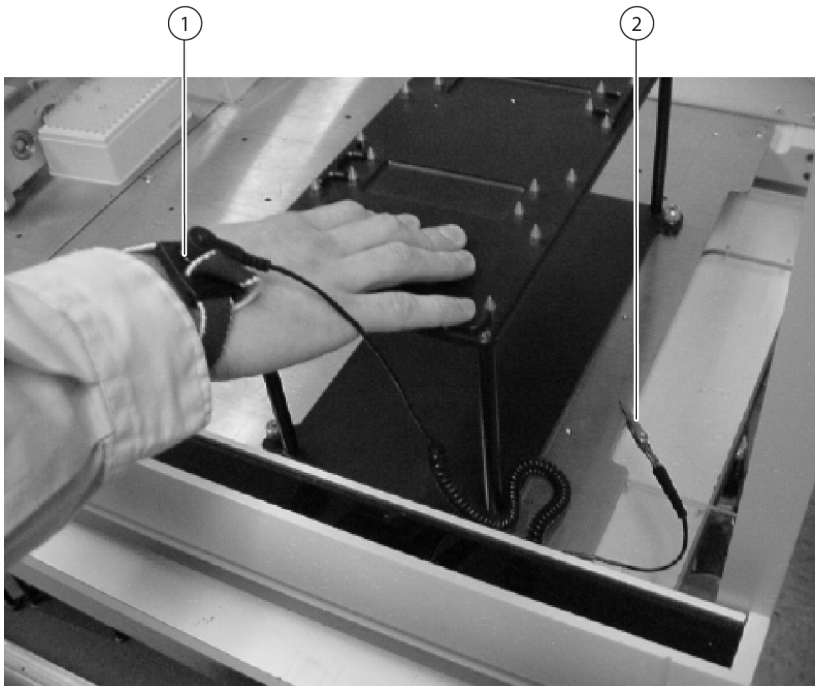
Removing Heads

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when removing a multichannel head.

NOTE A wrist ground strap, which must be attached to the instrument deck (base plate) using the "alligator" clip, is supplied with the Biomek FX instrument (Figure 1.5).

Figure 1.5 Wrist Ground Strap Attached to the Deck



1. Strap portion of wrist ground strap snugly attached to the wrist.
2. "Alligator" clip clamped to the instrument deck (base plate)

The same method is used to remove the 96-Channel 20 µL Head, 96-Channel 200 µL Head, 384-Channel 30 µL Head, and HDR Tool Body.

Removing a head from the Multichannel Pod includes:

- removing the bottom cover.
- removing the head.

Removing the Bottom Cover

To remove the bottom cover to expose the head:

---

1 In **Hardware Setup**, select the appropriate Multichannel **Pod**.

NOTE A Multichannel Pod is identified with a **96** or **384** and a Span-8 Pod is identified with an **8**.

2 Choose **Change Head**.

NOTE Choosing **Change Head** moves the D-axis to –0.6 cm and extends the grippers.

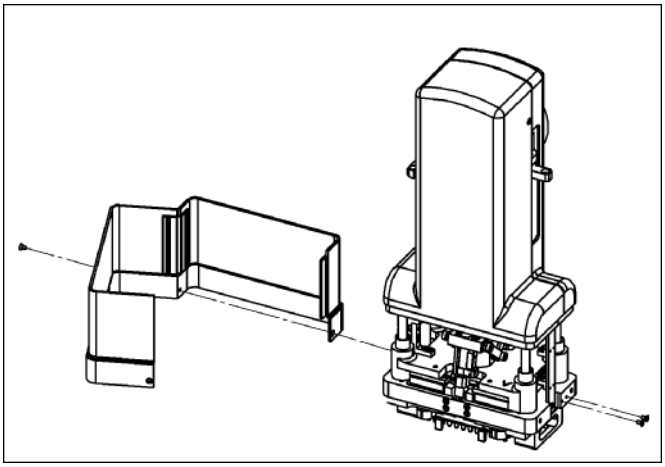
3 Turn off power to the Biomek FX instrument.

4 Position the strap portion of the wrist ground strap snugly around the wrist.

5 Clamp the "alligator" clip of the wrist ground strap to the instrument deck (base plate) (Figure 1.3).

6 Using a Phillips screwdriver, remove the three screws from the plastic bottom cover (Figure 1.6).

Figure 1.6 Bottom Cover Removed from the Pod



7 Carefully open and remove the bottom cover. Do NOT remove the top cover.

Removing the Head

To remove the head from the pod:

NOTE Remove the pin plate before removing an HDR Tool Body (refer to *Removing Pin Plates*).

1 Make sure the head is completely in the down position (D-axis) before proceeding with removing the head. This helps to ensure that the seals are protected during removal.

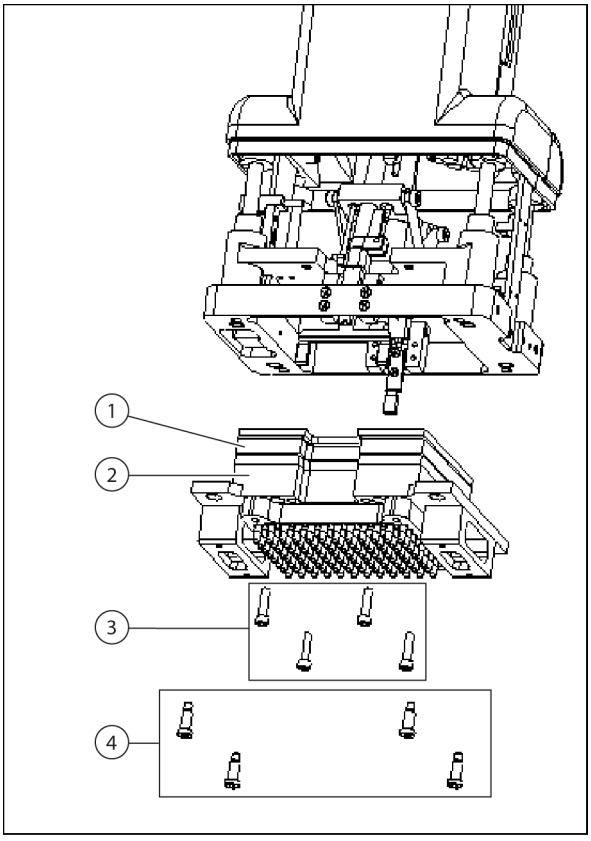
2 Using the 9/64 Allen wrench provided, remove the four plunger screws from the plunger plate (Figure 1.7) in the sequence designated in Figure 1.8.

3 With the same 9/64 Allen wrench, remove the four shoulder screws from the mandrel plate (Figure 1.7) in the sequence designated in Figure 1.8.

⚠ CAUTION

Before removing the fourth shoulder screw, take hold of the head firmly to make sure it does not fall once all screws are removed.

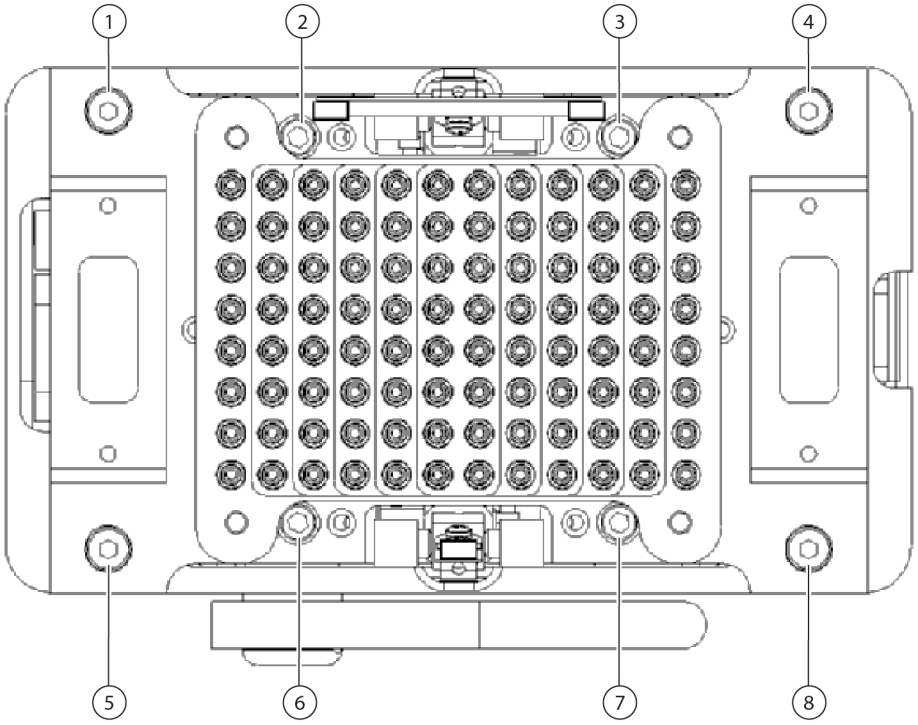
Figure 1.7 Plunger Screws and Shoulder Screws Removed from Multichannel Head



1. Plunger Plate
2. Mandrel Plate
3. Plunger Screws
4. Shoulder Screws

NOTE It is very important to remove the plunger screws in the correct sequence *before* removing the shoulder screws in the correct sequence.

Figure 1.8 Sequence for Removing Four Plunger Screws and Four Shoulder Screws on All Multichannel Heads



1. Shoulder 2
2. Plunger 2
3. Plunger 4
4. Shoulder 4
5. Shoulder 3
6. Plunger 3
7. Plunger 1
8. Shoulder 1

4 Slide the head down and out of the pod. Due to the weight of the head (approximately five pounds), maintain a firm grasp on the head while sliding the head out.

5 Cover and store the head flat side down in a clean, cool, dry place.

Installing Multichannel Heads

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when installing a multichannel head.

NOTE A wrist ground strap, which must be attached to the instrument deck (base plate) using the "alligator" clip, is supplied with the Biomek FX instrument.

The same method is used to install the 96-Channel 20 µL Head, 96-Channel 200 µL Head, and 384-Channel 30 µL Head.

NOTE Refer to *Installing an HDR Tool Body*, for instructions on installing the HDR Tool Body.

To install a head:

1. In **Hardware Setup**, select the appropriate Multichannel **Pod**.

   NOTE A Multichannel Pod is identified with a 96 or 384 and a Span-8 Pod is identified with an 8.

2. Choose **Change Head**.

   NOTE Choosing **Change Head** moves the D-axis to –0.6 cm and extends the grippers.

3. Turn off the power and make sure the plastic bottom cover is removed.

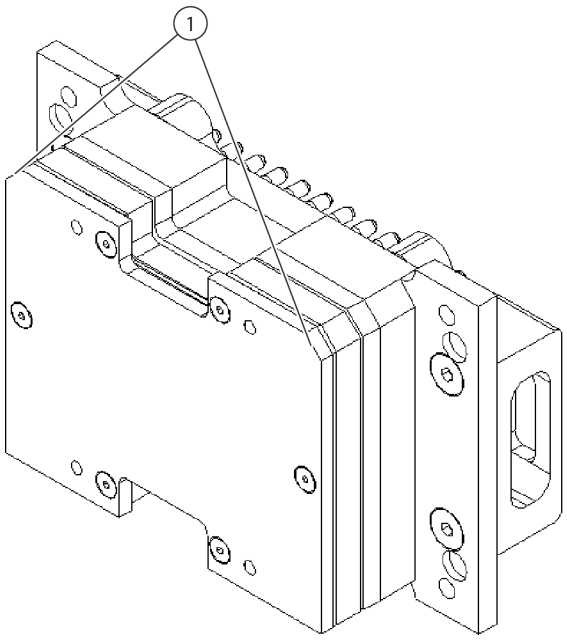
   NOTE Do not remove top cover.

4. Position the strap portion of the wrist ground strap snugly around the wrist.

5. Clamp the “alligator” clip of the wrist ground strap to the instrument deck (base plate).

6 With the chamfers (Figure 1.9) pointed to the back of the instrument, carefully slide the head up into the pod.

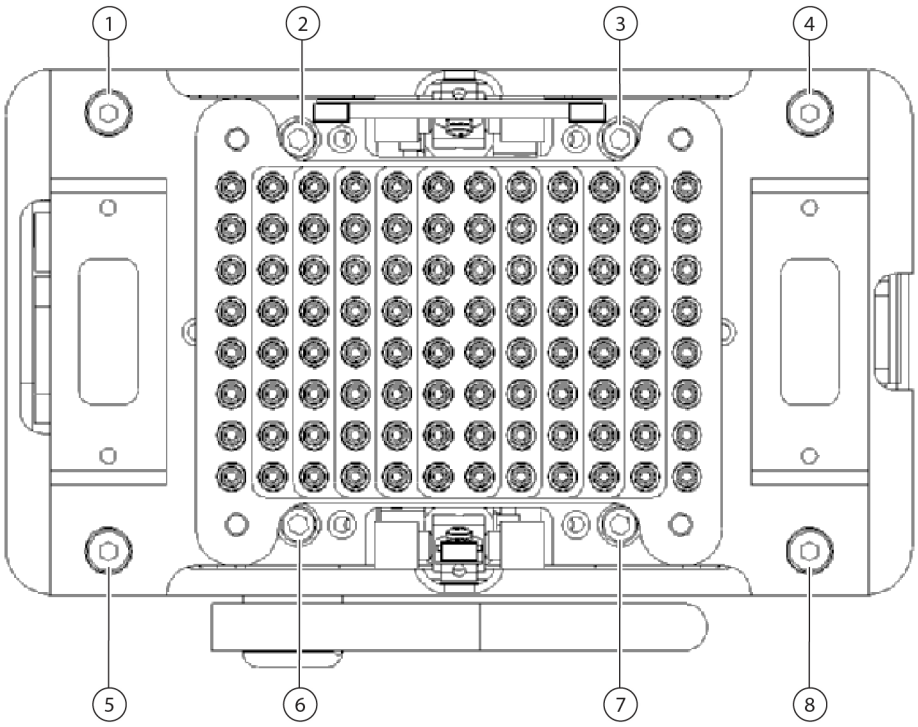
Figure 1.9 Chamfer Location on a Multichannel Head



1. Chamfers

7 Slide the first shoulder screw (Shoulder 1) into the head (Figure 1.10). Make sure the shoulder screw is in far enough to engage the threads.

Figure 1.10 Sequence for Installing Four Plunger Screws and Four Shoulder Screws on All Multichannel Heads



1. Shoulder 2
2. Plunger 2
3. Plunger 4
4. Shoulder 4
5. Shoulder 3
6. Plunger 3
7. Plunger 1
8. Shoulder 1

8 Using a 9/64 Allen wrench, tighten the first shoulder screw until it is snug, then back it off (loosen it) 1/2 turn.

NOTE This 1/2 turn allows the other three shoulder screws to be installed without skewing the head.

9 Using the sequence designated in Figure 1.10, follow the procedure in step 8 to install the remaining three shoulder screws.

10 After all four shoulder screws are installed, go back and tighten them securely in the same order.

11 Using a 9/64 Allen wrench, follow the installation sequence designated in Figure 1.10 to install the four plunger screws. Turn each plunger screw until barely snug.

12 After all four plunger screws are installed, go back and tighten all of them securely in the same order.

13 Replace the bottom pod cover and tighten the three screws.

14 Turn on the power.

15 Retract the gripper using **Advanced Manual Control**.

NOTE After installing a multichannel head on a Multichannel Pod, **Hardware Setup** must be updated (refer to CHAPTER 3, *Configuring a Multichannel Pod*).

Installing an HDR Tool Body

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when installing the HDR Tool Body.

NOTE A wrist ground strap, which must be attached to the instrument deck (base plate) using the "alligator" clip, is supplied with the Biomek FX instrument.

To install the HDR Tool Body:

1 Turn on the Biomek FX instrument.

2 In **Hardware Setup**, select the appropriate Multichannel **Pod**.

NOTE A Multichannel Pod is identified with a **96** or **384** and a Span-8 Pod is identified with an **8**.

3 Choose **Change Head**.

NOTE Choosing **Change Head** moves the pod along the D-axis to –0.6 cm and extends the grippers.

4 Turn off power and make sure the plastic bottom cover is removed (refer to *Removing the Bottom Cover*).

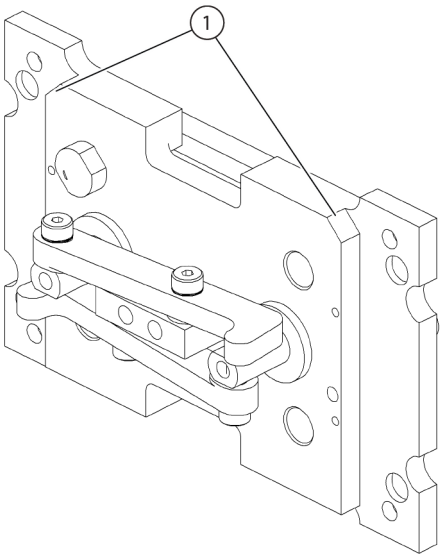
NOTE Do not remove top cover.

5 Position the strap portion of the wrist ground strap snugly around the wrist.

6 Clamp the “alligator” clip of the wrist ground strap to the instrument deck (base plate).

7 With the chamfers (Figure 1.11) pointed to the back of the instrument, carefully slide the HDR Tool Body up into the pod.

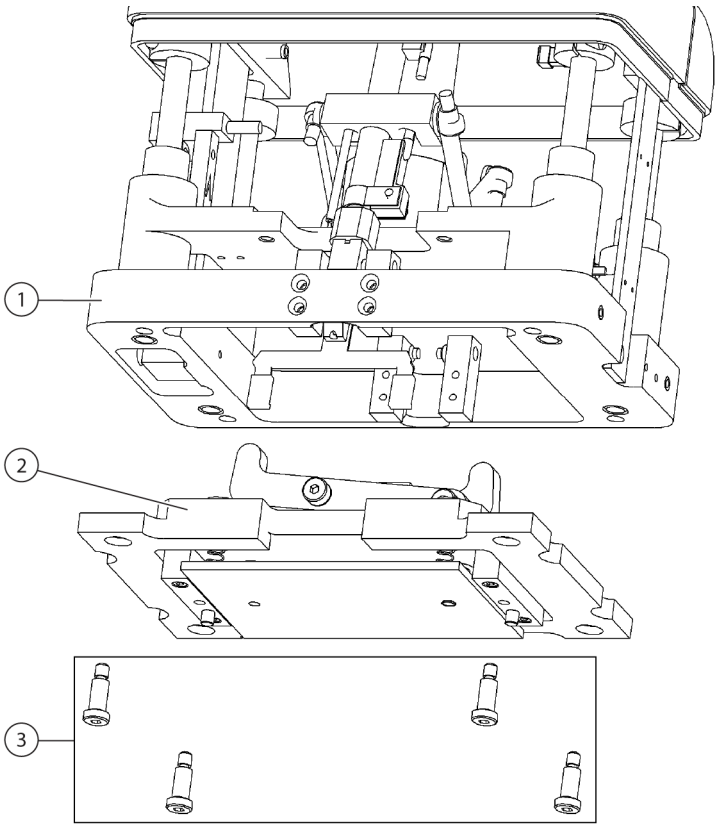
Figure 1.11 Chamfer Locations on the HDR Tool Body



1. Chamfers

8 Slide the first shoulder screw (**Shoulder 1**) into the HDR Tool Body (Figure 1.12). Make sure the shoulder screw is in far enough to engage the thread.

Figure 1.12 Fastening the HDR Tool Body With Shoulder Screws



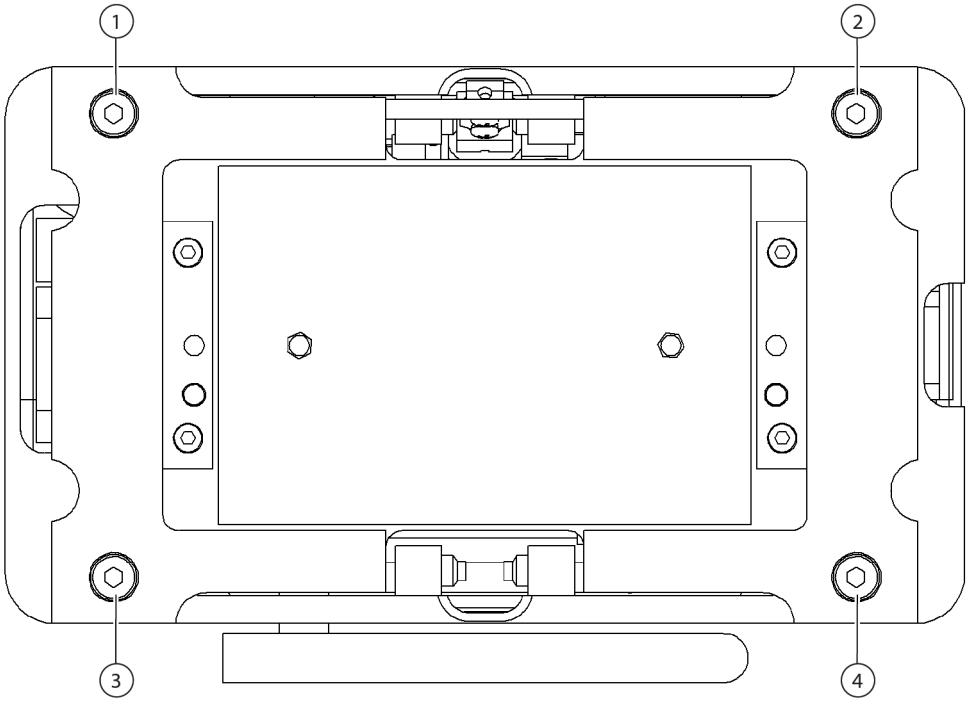
1. Multichannel Pod
2. HDR Tool Body
3. Shoulder Screws

9 Using a 9/64 Allen wrench, tighten the first shoulder screw until it is snug, then back it off (loosen it) 1/2 turn.

NOTE This 1/2 turn allows the other three shoulder screws to be installed without skewing the HDR Tool Body.

10 Using the sequence designated in Figure 1.13, follow the procedure in steps 8 and 9 to install the remaining three shoulder screws.

Figure 1.13 Sequence for Installing Four Plunger Screws and Four Shoulder Screws on the HDR Tool Body



1. Shoulder 2
2. Shoulder 4
3. Shoulder 3
4. Shoulder 1

11 After all four shoulder screws are installed, go back and tighten them securely in the same order.

12 Replace the bottom pod cover and tighten the three screws.

13 Turn on the power to the Biomek FX instrument.

14 Retract the gripper using **Advanced Manual Control**.

NOTE After installing the HDR Tool Body on a Multichannel Pod, **Hardware Setup** must be updated (refer to CHAPTER 3, *Configuring a Multichannel Pod*).

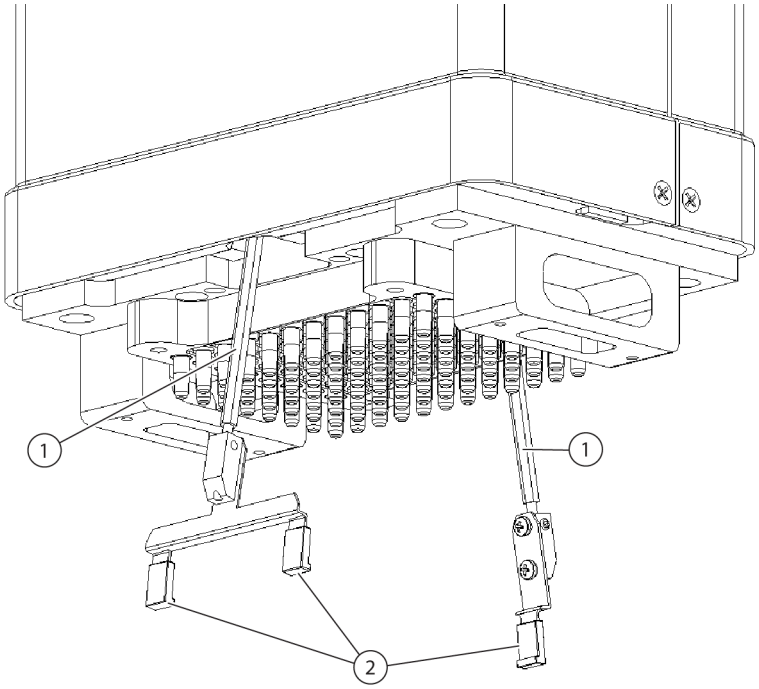
Gripper

The Multichannel Pod incorporates a gripper tool (gripper) (Figure 1.14) that grasps and moves labware from one location on the Biomek FX deck to another.

The gripper can:

- move labware no taller than 2.35 inches in height.
- move stacks of standard height labware no more than four plates high (maximum 2.35 inches).
  NOTE. The gripper stacks and unstacks groups of labware from the bottom. If a stack containing four pieces of labware is being unstacked, the gripper grasps the top three and moves them to a new position. Then, the gripper grasps the top two of that stack and moves them; finally, the gripper grasps the top piece of labware in that stack and moves it to a new location.
- place lids on and remove lids from labware.

Figure 1.14 Gripper



1. Gripper Shaft
2. Gripper Fingers

The gripper contains two fingers:

- a double gripper located to the front of the instrument
- a single gripper located to the back of the instrument

Framing the Gripper

⚠ WARNING

Gripper fingers may bend if not taught (framed) properly with the AccuFrame.

The gripper is framed during installation by a Beckman Coulter Representative. The framing process for the gripper must be repeated when:

- A head is changed.
- Extraordinary circumstances occur, such as accidentally bending a gripper.

Should the gripper need to be framed, refer to CHAPTER 4, *Framing the Gripper on a Multichannel Pod*.

Preventive Maintenance

The Multichannel Pod requires little preventive maintenance; however, to ensure optimum operation, perform the following maintenance procedures as necessary.

⚠ WARNING

To prevent injury, use proper decontamination procedures.

- Wipe up all spills immediately.
- Return heads to their original packaging when they are not in use.
- Check connections periodically to make sure that all are secure (refer to *Troubleshooting*).
- Check and tighten head mount screws and gripper mount screws.
- Make sure that gripper shafts are straight and gripper pads are in good condition. Replace as needed (refer to *Replacing Gripper Fingers*).
- Make sure all pins on the HDR Pin Tool Body are clean and straight.

NOTE Dirt or grease residue on pins could result in poor liquid transfer results. Keep pins and the pin plate clean.

NOTE Bent pins could result in poor liquid transfer results or labware crashes. Replace any bent pins immediately (refer to *Replacing Bent or Damaged Pins*).

Troubleshooting

⚠ WARNING

Do not connect or disconnect any cable while power is applied to the Biomek FX.

Perform the troubleshooting techniques provided in Table 1.4 when necessary.

NOTE In the case of any other pod-related problems, contact a Beckman Coulter Representative.

Table 1.4 Multichannel Pod Troubleshooting

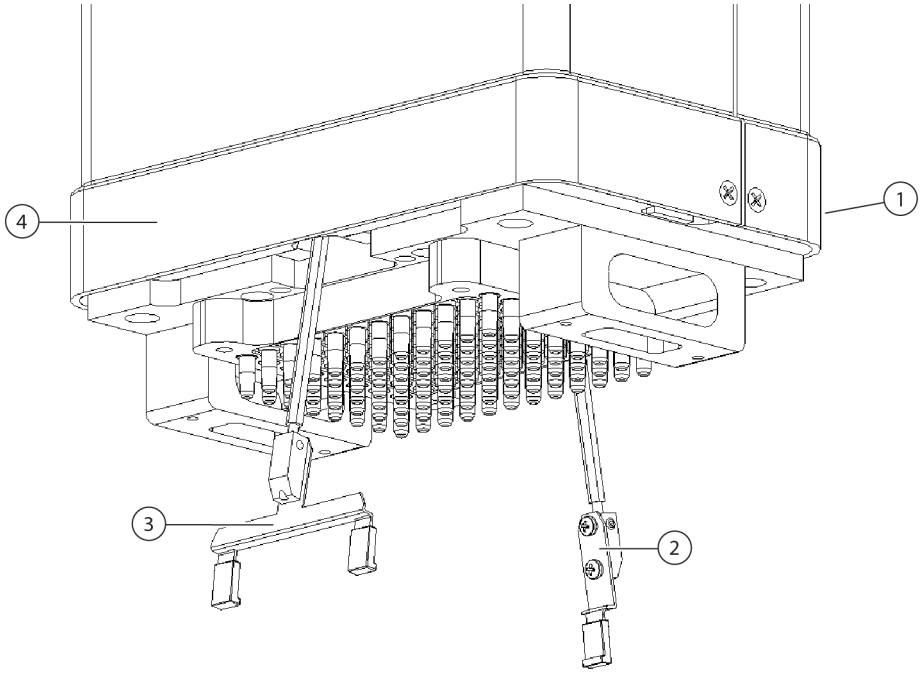
If...	Then...
Power is lost to the pod.	Contact a Beckman Coulter Representative.
The gripper is not deploying.	Check input air pressure. Contact a Beckman Coulter Representative.
Power is lost to the Y-axis.	Contact a Beckman Coulter Representative.
The head does not work properly.	Contact a Beckman Coulter Representative.
Aspiration or dispense actions are not accurate.	Contact a Beckman Coulter Representative.
A mandrel on the head is damaged.	Contact a Beckman Coulter Representative — the head may need to be returned to the factory for repair or replacement.
Liquid transfer operations with the HDR Pin Tool Body are not accurate.	Make sure pins are clean and replace any bent pins. Contact a Beckman Coulter Representative.
Front gripper shaft is bent.	Replace the front gripper fingers using Front Removable Rod Assembly, Beckman Coulter PN 394062. Refer to *Replacing Gripper Fingers*, for instructions.
Front gripper pads look worn.	
Rear gripper shaft is bent.	Replace the rear gripper fingers using Rear Removable Rod Assembly, Beckman Coulter PN 394063. Refer to *Replacing Gripper Fingers*, for instructions.
Rear gripper pads look worn.	

Replacing Gripper Fingers

Gripper fingers are easily replaced by pulling the damaged gripper fingers out of the head and pushing the replacement fingers into the head.

NOTE Not all Multichannel Pods are equipped with the replaceable gripper. If the Multichannel Pod does not have the replaceable gripper, contact a Beckman Coulter Representative for assistance.

Figure 1.15 Installed Replicable Gripper Fingers



1. Pod Rear
2. Rear Removable Assembly
3. Front Removable Gripper Assembly
4. Pod Front

Removing Gripper Fingers

⚠ WARNING

Avoid all labware on the Biomek FX deck when removing or installing gripper fingers. It is recommended that all labware in the vicinity of the pod be moved or removed to avoid spills and contact with labware.

⚠ CAUTION

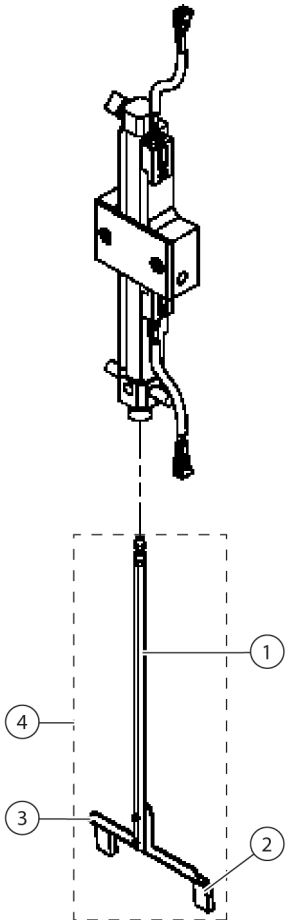
Use caution when removing gripper fingers. Since gripper fingers mount tightly into the Multichannel Pod, they pull free of the Multichannel Pod suddenly.

To remove gripper finger:

1. Move the Multichannel Pod to the maximum Y- and Z-axis limits (refer to CHAPTER 5, *Using the Advanced Manual Control with the Multichannel Pod*).
2. Grasp both sides of the gripper (Figure 1.16).
3. Apply force in a downward direction to pull the gripper from the head.

NOTE Since gripper fingers mount tightly into the Multichannel Pod, they pull free of the Multichannel Pod suddenly.

Figure 1.16 Removable Front Gripper Assembly



1. Gripper Shaft
2. Gripper Pads
3. Front of Gripper
4. Gripper Finger

Installing Gripper Fingers

⚠ WARNING

Avoid all labware on the Biomek FX deck when removing or installing grippers. It is recommended that all labware in the vicinity of the pod be moved or removed to avoid spills and contact with labware.

To install gripper fingers:

1 Move the Multichannel Pod to the maximum Y- and Z-axis limits (refer to CHAPTER 5, *Using the Advanced Manual Control with the Multichannel Pod*).

2 Orient the gripper finger so that the front of the gripper finger faces the outside and gripper pads face the inside of the Multichannel Pod (Figure 1.16).

3 Grasping both sides of the gripper finger, push the finger straight up into the Multichannel Pod.

NOTE A click can be heard and felt when the gripper fingers are seated in the Multichannel Pod.

4 Pull down on the gripper finger to ensure that it is fully seated in the pod.

5 Reframe the Multichannel Pod (refer to CHAPTER 4, *Framing the Gripper on a Multichannel Pod*).

CHAPTER 2

Span-8 Pod

Overview

The Span-8 Pod is a self-contained working unit installed on the Biomek FX instrument (Figure 2.1). The Span-8 Pod is a liquid-handling tool capable of performing liquid transfers from test tubes and large pieces of labware to smaller pieces of labware, or vice versa. The Span-8 Pod can also perform liquid level sensing (LLS) during liquid transfers when liquid level sensing enabled tips are attached to the probes.

➢ **FX^{P}** — Span-8 Pod can also perform clot detection (CD) during liquid transfers when conductive tips are attached to the probes.

NOTE Conductive disposable tips are identified as **LLS** in the **Tip Type Editor**. Fixed tips are also conductive.

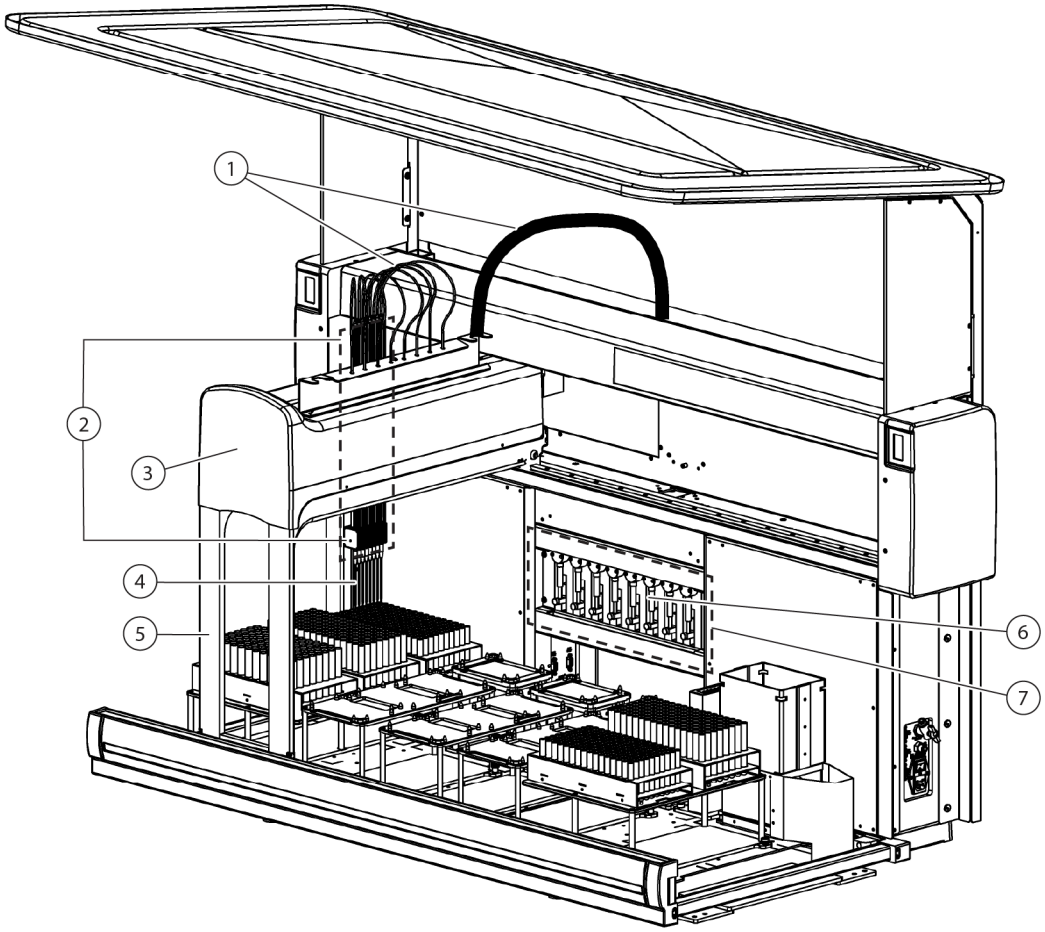
The Span-8 Pod performs liquid transfers using a series of eight probes that can move independently in the Z-axis, pipette independently in the D-axis, and span from 9mm to 20mm between the probes in the S-axis (Figure 2.1). The pipetting action of the Span-8 Pod is accomplished using pumps and either fixed or disposable tips, with or without liquid level sensing capabilities.

The Span-8 Pod contains its own electrical cabling, and communication with the base unit, and it interacts with ALPs located over the entire deck of the Biomek FX.

NOTE When installed on a dual-pod system, the pod mounted on the left side of the Biomek FX instrument is capable of accessing all ALPs on the deck excluding those in the far right column, while a pod mounted on the right side of the Biomek FX instrument is capable of accessing all ALPs on the deck excluding those in the far left column.

The sections in this chapter include:

Figure 2.1 Span-8 Pod Installed on a Single Pod Biomek FX Instrument



1. Tubing—System fluid through the tubing.
2. Probes
3. Span-8 Pod
4. Tips
5. Bridge
6. Pumps and Syringes
7. Pump Assembly

Main Components of the Span-8 Pod

The Span-8 Pod houses the operating mechanisms, communications, and electrical connections to the base unit, and moves the probes in the D, Z, and Y axes for liquid handling functions (Figure 2.1 and Figure 2.2).

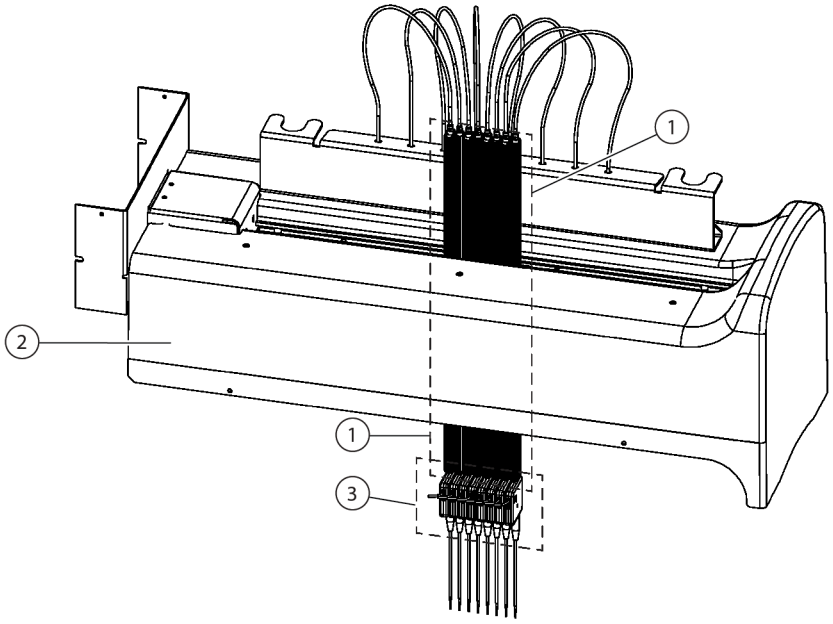
The main components of a Span-8 Pod are (Figure 2.1):

- *Probes* — Move independently in the Z-axis and pipette independently in the D-axis with the assistance of the pump assembly. Hold the tip interface for fixed or disposable tips, both Liquid Level Sensing (LLS) capable and non-LLS capable, used to perform liquid-handling operations

(refer to *Interchangeable Tips*) (Figure 2.1 and Figure 2.2); probes move in the Y-, Z-, S(pan), and D(ispense) axes (Figure 2.1).

- *Interchangeable Tips* — Fixed or disposable tips that are attached to the Span-8 probes used to perform microplate-to-microplate, test tube-to-microplate, and test tube-to-test tube liquid transfers.
- *Pump Assembly* — Houses the individual pumps and syringes which control the flow of system fluid to and from each of the eight probes by controlling the D-axis (Figure 2.1) (Figure 2.3); located between the towers at the back of the Biomek FX instrument (Figure 2.1) (refer to *System Components*).
- *Liquid System* — Stores and transports system fluid used to provide a vacuum for pipetting, wash tips, and perform bulk dispense operations.
- *Speed Pump* — Optional device which propels system fluid through fixed tips at a rate of speed greater than can be supplied by the pumps and syringes for increased tip washing efficiency.

Figure 2.2 Span-8 Pod (Detailed View)



1. Probes
2. Span-8 Pod
3. Tip Interface — Tips are attached to the probes at the tip interface.

Probes

The Span-8 Pod uses eight probes that can move independently in the Z-axis and pipette independently in the D-axis with the assistance of the pumps. Movement in the S-axis provides a span between the probes.

The pipetting action of the Span-8 Pod is accomplished using either fixed or disposable tips attached to the tip interface of the probes. These tips may or may not be liquid level sensing capable (refer to *Interchangeable Tips*).

NOTE The Span-8 Pod can perform liquid level sensing (LLS) during any liquid transfers, but only if liquid level sensing tips are attached to the probes.

Probe Movements

The Span-8 Pod performs movements in the Y, Z, D, and S axes (refer to Table 2.1).

Table 2.1 Span-8 Pod Axes Movement

Axis	Movement
Y-	Entire pod moves front-to-back.
Z-	Entire pod moves up-and-down.
D-	Up-and-down aspirate/dispense, disposable tip shucking, and close/open gripper.
S-	The span (or distance) between the eight probes can expand and collapse. **NOTE** The span between each of the eight probes is always equal.

Control Modes

Commands entered via the Biomek Software on the host computer control the operations of the Span-8 Pod. Manual control associated with the operation of the Span-8 Pod is accessed through the Biomek Software. Refer to CHAPTER 5, *Manually Controlling the Biomek FX in Biomek Software*, for information on manually controlling the Span-8 Pod.

Interchangeable Tips

⚠ CAUTION

Use Manual Control to move the probes in the Y-axis. Dragging the probes by hand may affect alignment and the ability to access labware.

⚠ WARNING

Use care when handling septa fluted tips; they are extremely sharp.

⚠ CAUTION

Use care when handling septa fluted tips; they are extremely fragile.

Interchangeable tips are attached to the Span-8 probes to perform liquid-handling procedures. The following interchangeable tips are used on the Span-8 Pod although septa fluted are available only with a Biomek FX^P instrument:

- Fixed
- Disposable
- Septa Fluted — fixed; but also capable of piercing septum when the **Requires Piercing Tips** property of the Septum Piercing Tube Racks is checked in the **Labware Type Editor** (refer to the Biomek Software User's Manual (PN 987835), *Editing Labware Type Properties*). Septa fluted tips are available only with a Biomek FX^P instrument.

Fixed tips are available in two sizes with or without Teflon coating. Disposable tip mandrels may also be installed on the Span-8 probes. When using disposable tip mandrels, any standard, LLS-capable, or barrier disposable tips may be loaded onto and unloaded from the disposable tip mandrels.

Liquid Level Sensing

If the liquid level in a piece of labware is not known, the Span-8 Pod can determine the liquid level when Liquid Level Sensing (LLS) capable tips are attached to the probes.

NOTE LLS tips must be attached to the probes to detect the liquid level.

NOTE An LLS plate option used on a 1 x 1 Passive ALP can improve LLS capabilities (refer to the ALPs User's Manual (PN 987836), *1 x 1 Passive ALP with LLS Plate Option*).

LLS tips are used to determine the liquid level in a piece of labware by detecting a shift in the capacitance. The LLS tip moves to a specified height within a well and then slowly moves down into the well. When the tip contacts liquid, there is a large change in the capacitance detected. The liquid level is sensed by determining the height at which this change in capacitance occurs. Refer to CHAPTER 5, *Verifying Liquid Level Sensing*, for more information on detecting the liquid level in labware.

The Span-8 Pod on the Biomek FX supports the following liquid level sensing tips:

- Fixed 60 (Coated and Uncoated) — maximum of 1000 µL liquid and/or air capacity
- Fixed 100 (Coated and Uncoated) — maximum of 1000 µL liquid and/or air capacity

  NOTE Fixed tips can pull samples into the tubing, but the maximum sample volume is limited to syringe capacity (refer to *Syringes*).

  NOTE Fixed tips can be used only with the Span-8 Pod.

- Septa Fluted — maximum of 1000 µL liquid and/or air capacity

  NOTE Septa Fluted Fixed tips can pull samples into the tubing, but the maximum sample volume is limited to syringe capacity (refer to *Syringes*).

➢ **FX^{P}** — Septa Fluted are only available with this instrument.

- Disposable 20 µL LLS — up to 100 µL liquid capacity; up to 120 µL air capacity
- Disposable 200 µL LLS — up to 220 µL liquid capacity; up to 240 µL air capacity

  NOTE The Multichannel Pod can load disposable LLS tips, but it is not liquid level sensing capable. The Span-8 is the only pod capable of performing liquid level sensing; therefore, disposable LLS tips should be used only with a Span-8 Pod.

- Disposable P1000 LLS (sterile and non-sterile) — up to 1000 µL liquid and air capacity
- Disposable P1000 LLS (barrier) — up to 1000 µL liquid and air capacity

  NOTE Refer to *Interchangeable Tips*, for more information on tips available for use with the Span-8 Pod.

Liquid Level Sensing Settings

Sensitivity settings for liquid level sensing affect the magnitude of change required for LLS tips to detect the liquid. A higher sensitivity setting detects smaller changes in the capacitance detected (refer to CHAPTER 5, *Verifying Liquid Level Sensing*).

Disabling Liquid Level Sensing

If LLS is disabled in the Technique governing the liquid-handling procedure, LLS is unavailable regardless of the type of tips attached to the probes. Refer to the *Biomek Software User's Manual* (PN 987835), *Setting Technique Values*, for enabling and using liquid level sensing in techniques.

Clot Detection (Available Only with a Biomek FX^P Instrument)

⚠ WARNING

When working with blood samples, observe the cautionary procedures as defined by your safety officer.

The Span-8 Pod can detect if a possible clot is on the end of a tip after an aspirate operation when conductive tips (called **LLS** in the **Tip Type Editor**) are attached to the probes.

NOTE Conductive tips must be attached to the probes to enable clot detection.

NOTE An LLS plate option used on a 1 x 1 Passive ALP can improve clot detection capabilities (refer to the *ALPs User's Manual* (PN 987836), *1 x 1 Passive ALP with LLS Plate Option*).

Conductive tips (fixed, disposable, or septa fluted) are used to determine if a clot is detected by detecting a shift in the capacitance. The tip moves to a specified height within the well and then slowly moves down into the well. When the tip aspirates and rises out of the liquid, there is a large change in capacitance detected. A clot is detected by determining the change in capacitance as the tip moves up after aspiration.

Clot Detection Settings

Sensitivity settings for clot detection sensing affect the magnitude of change required for conductive tips to detect a clot. A smaller sensitivity setting detects smaller changes in the capacitance (refer to the *Biomek Software User's Manual* (PN 987835), *Setting Technique Values*).

Clot Detecting Tips

⚠ WARNING

Use care when handling septa fluted tips; they are extremely sharp.

⚠ CAUTION

Use care when handling septa fluted tips; they are extremely fragile.

Biomek FX^P Span-8 supports the following clot detecting tips:

- Fixed 60 (Coated and Uncoated) — maximum of 1000 µL liquid and/or air capacity
- Fixed 100 (Coated and Uncoated) — maximum of 1000 µL liquid and/or air capacity
- Septa Fluted — maximum of 1000 µL liquid and/or air capacity

  NOTE Fixed and septum piercing tips can pull samples into the tubing, but the maximum sample volume is limited to syringe capacity (refer to *Syringes*).

- Disposable 20µL LLS — up to 100 µL liquid capacity; up to 120 µL air capacity
- Disposable 200µL LLS — up to 220 µL liquid capacity; up to 240 µL air capacity

- Disposable P1000 LLS (sterile and non-sterile) — up to 1000 µL liquid and air capacity
- Disposable P1000 LLS (barrier) — up to 1000 µL liquid and air capacity

NOTE Refer to *Interchangeable Tips*, for more information on tips available for use with the Span-8 Pod.

Disabling Clot Detection

If clot detection is disabled in the Technique governing the liquid-handling procedure, clot detection is unavailable regardless of the type of tips attached to the probes. Refer to the Biomek Software User's Manual (PN 987835), Chaper 9, *Setting Technique Values*, for enabling and using clot detection in techniques.

Selecting Which Type of Tips to Use

The best tips to use depends on a number of factors relating to the application, such as the liquid and labware types used and volumes required for aspirate and dispense operations.

There are 11 types and sizes of fixed and disposable tips that can be attached to the Span-8 probes. These tips are listed in Table 2.2.

Table 2.2 Span-8 Tip Types

Tip Type	Tip Name (Software)	LLS/CD Capable	Tip Volume
Fixed 60 (Coated*) Fixed 60 (Uncoated)	**Fixed60**	Yes	maximum of 1000 µL liquid and/or air capacity, depending on syringe size
Fixed 100 (Coated*) Fixed 100 (Uncoated)	**Fixed100**	Yes	maximum of 1000 µL liquid and/or air capacity, depending on syringe size
Septa Piercing (Fixed) ➢ **FX^{P}** — available only with this instrument.	**SeptaFluted**	Yes	maximum of 1000 µL liquid and/or air capacity, depending on syringe size
Disposable 20µL LLS	**AP96_20_LLS**	Yes	maximum of 100 µL liquid capacity; up to 120 µL air capacity, depending on syringe size
Disposable 20µL	**Span_8_20µL**	No	
Disposable 200µL LLS	**AP96_200_LLS**	Yes	maximum of 220 µL liquid capacity; up to 240 µL air capacity, depending on syringe size
Disposable 200µL	**Span_8_200µL**	No	
Disposable 20µL barrier tips	**Span_8_20µL_Barrier**	Yes	maximum of 20 µL liquid and/or air capacity, depending on syringe size**
Disposable 200µL barrier tips	**Span_8_200µL_Barrier**	Yes	maximum of 125 µL liquid and/or air capacity, depending on syringe size**

Table 2.2 Span-8 Tip Types

Tip Type	Tip Name (Software)	LLS/CD Capable	Tip Volume
Disposable P1000 µL (sterile and non-sterile)	**Span8_P1000_LLS**	Yes	maximum of 1000 µL liquid and/ or air capacity, depending on syringe size
Disposable P1000 µL barrier tips	**Span8_P1000_LLS_Barrier**	Yes	maximum of 1000 µL liquid and/ or air capacity, depending on syringe size**
* Coated refers to tips covered with a Teflon coating. The coating assists in preventing cross contamination Solutions are less likely to adhere to the Teflon coating than to uncoated stainless steel fixed tips and are easier to wash off, thereby reducing the potential for cross-contamination. **NOTE** Biomek Software does not distinguish between Coated/Uncoated fixed tips. ** Barrier tips are recommended when using disposable tips with liquids that are susceptible to contamination, such as blood.			

Labware and Tip Compatibility with the Span-8 Pod

The Span-8 Pod cannot access 1536 microplates. However, it can access all other types of labware supported by the Biomek FX instrument, although specific types of tips are recommended to access specific types of labware. Table 2.3 shows some tips supported by the Span-8 Pod and their accessibility to some types of labware supported by the Biomek FX instrument.

NOTE Table 2.3 is provided as a general reference and does not cover all commercially available microplate types. It is the user's responsibility to verify that labware functions properly with the selected tip type. For example, a flat 384 square well microplate has a larger top cross-sectional area than a flat 384 round well microplate; therefore, Fixed 100 tips can be used to access the flat 384 square well microplate, but Fixed 60 tips would be more reliable when accessing the smaller area flat 384 round well microplate.

Consult Customer Technical Support for information on labware and tip compatibility not covered in Table 2.3.

⚠ CAUTION

Use labware and tip combinations labeled as 'Limited' with caution. Tips could become wedged inside labware, picking the labware up with the probe when the probe is raised.

Table 2.3 Labware and Tip Compatibility

Labware	Tip Type				
	Fixed 100	Fixed 60	Disposable AP96_200 µL	Disposable AP96_20 µL	P1000
Flat 96	R	R	R	R	R
Deep 96	R	R	R	L[a]	R
Flat 384	L[b]	R	L[c]	R	N

Table 2.3 Labware and Tip Compatibility

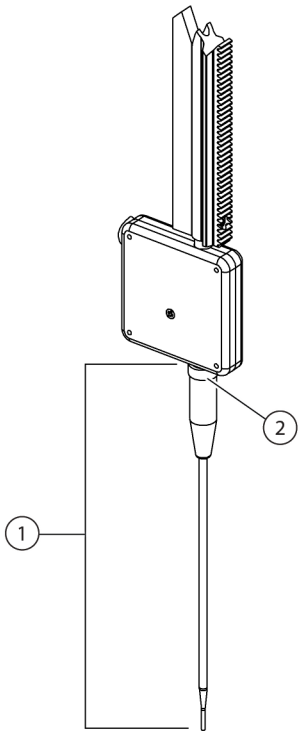
Labware	Tip Type				
	Fixed 100	**Fixed 60**	**Disposable AP96_200 µL**	**Disposable AP96_20 µL**	**P1000**
Deep 384	L[b]	R	L[c]	L[a]	N
BCTubeRack_10mm (x75 mm)	R	L[a]	L[c]	L[c]	R
BCTubeRack_12mm (x75 mm)	R	L[a]	R	R	R
BCTubeRack_13mm (x100 mm)	R	L[a]	R	R	R
BCTubeRack_15mm (x100 mm)	R	L[a]	R	R	R
R = Recommended L = Limited Access (Due to height and/or width restrictions. See Caution above.) N = No Access					

a. The tip (fixed or disposable) is too short to allow the tip to access fluid in the bottom of the test tube (Figure 2.3 and Figure 2.4).

b. Fixed 100 tips are designed to fully access test tubes, while Fixed 60 tips are designed to increase reliability in accessing high density (384-well) microplates.

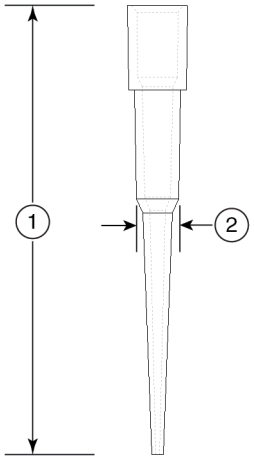
c. The maximum diameter of the disposable tip is too wide to allow the tip to fully access the labware (Figure 2.3, Figure 2.4, and Figure 2.5).

Figure 2.3 Fixed Tip Height and Width Restrictions



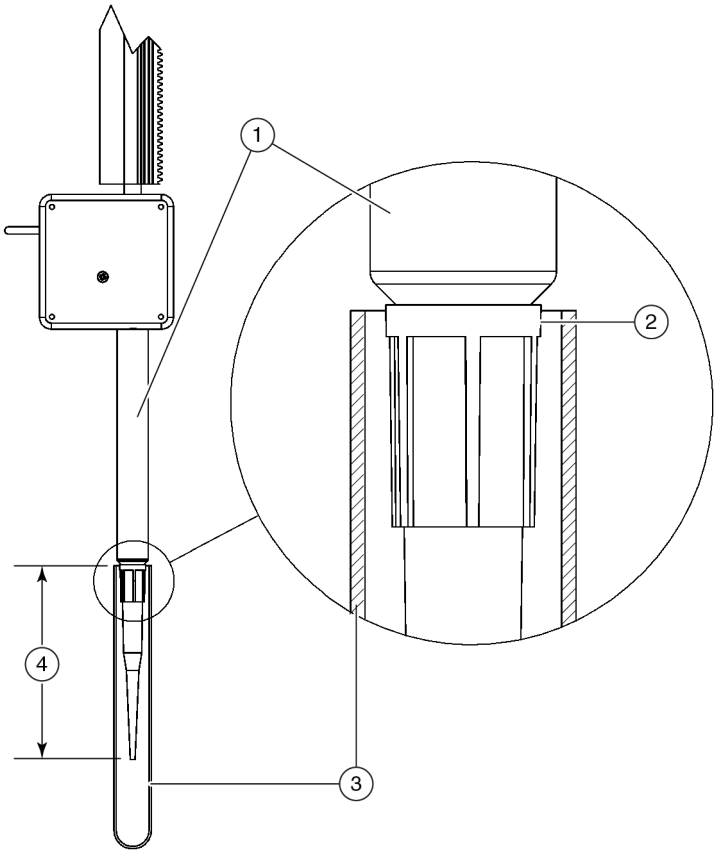
1. Height
2. Maximum Diameter

Figure 2.4 Disposable Tip Height and Width Restrictions



1. Height
2. Maximum Diameter

Figure 2.5 Disposable Tip and Tip Shuck Tube Width Restrictions With 10mm Test Tubes



1. Tip Shuck Tube — Only the disposable tip portion should descend into 10mm test tubes; tip shuck tubes should not descend into 10mm test tubes. The clearance between the tip shuck tubes and a 10mm test tubes is too tight to safely allow the tip shuck tubes to access 10mm test tubes.
2. Maximum Diameter — Accessibility of disposable tips into a 10mm test tube is limited to the height of the tip.
3. 10 mm Test Tube
4. Tip Height

Electro-Static Discharge Protection when Changing Tips on the Span-8 Pod

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when working with tips on the Span-8 Pod.

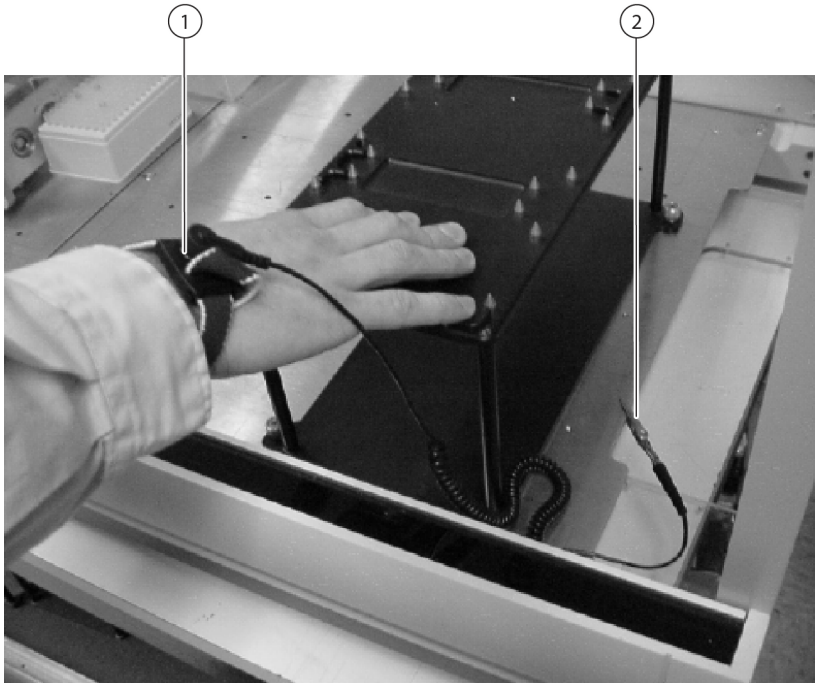
A wrist ground strap must be attached to the instrument deck (base plate) prior to installing or removing tips on the Span-8 Pod or moving the Span-8 Pod by hand.

NOTE A wrist ground strap, which must be attached to the instrument deck (base plate) using the “alligator” clip, is supplied with the Biomek FX instrument.

To attach a wrist ground strap:

1. Turn off the power to the Biomek FX instrument.
2. Position the strap portion of the wrist ground strap snugly around the wrist.
3. Clamp the "alligator" clip of the wrist ground strap to the instrument deck (Figure 2.6).
4. Power-up the Biomek FX instrument.

Figure 2.6 Wrist Ground Strap Attached to the Deck



1. Strap portion of wrist ground strap snugly attached to the wrist.
2. "Alligator" clip clamped to the instrument deck (base plate)

Fixed Tips

All fixed tips are LLS-capable when liquid level sensing is enabled in the technique governing the liquid-handling procedure. If liquid level sensing is disabled in the technique, LLS is unavailable regardless of the type of tips attached to the probes. (Refer to CHAPTER 5, *Verifying Liquid Level Sensing*, for more information on detecting the liquid level in labware. Refer to the Biomek Software User's Manual (PN 987835), *Setting Technique Values*, for enabling and using liquid level sensing in techniques.)

To use fixed tips, they must be physically installed on the probes and configured for use in **Hardware Setup** (refer to CHAPTER 3, *Configuring a Span-8 Pod*).

NOTE After installing fixed tips, it is necessary to frame the Span-8 Pod.

Installing Fixed Tips

⚠ CAUTION

Do not perform aspirate or dispense operations without mandrels installed and tubing attached to fixed tips. To operate the system without the mandrels installed and the tubing attached to tips may cause corrosion in the tip interface.

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when working with tips on the Span-8 Pod.

NOTE A wrist ground strap must be attached to the instrument deck (base plate) prior to installing or removing tips on the Span-8 Pod (refer to *Electro-Static Discharge Protection when Changing Tips on the Span-8 Pod*).

To install fixed tips:

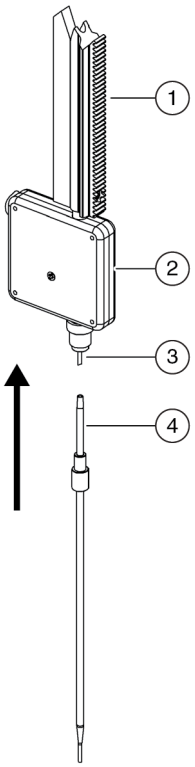
1 Place the end of a fixed tip into the tubing that extends from the bottom of the Span-8 probe (Figure 2.7).

2 While holding the tip in one hand, push the tubing down over the tapered end of the tip until it is flush with the flat portion of the tip with the other hand. Make sure the tip is secure to prevent air entering the system and fluid leaks around the tip.

NOTE The ends of the tubing may become damaged or stretched after repeated tip installation and removal. It may be necessary to cut a small portion (1/2”) of tubing off the end prior to attaching to ensure a tight fit.

NOTE Since the tubing is Teflon, it may be difficult to hold. Holding the tubing with a Kimwipe may prevent slipping while pushing the tubing down onto the tip.

Figure 2.7 Inserting a Fixed Tip into the Tubing

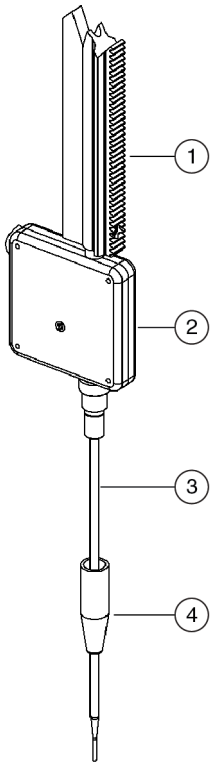


1. Probe
2. Tip Interface
3. Tubing
4. Fixed Tip

3 Gently push the tubing and tip up into the Span-8 probe.

4 Pass the collar up over the tip to the tip interface (Figure 2.8).

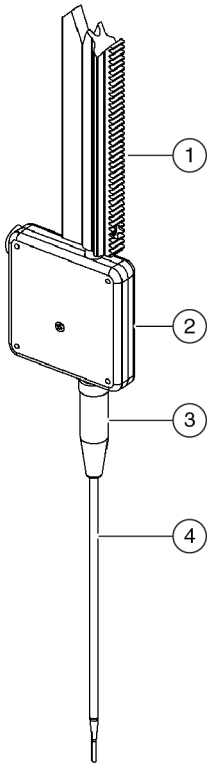
Figure 2.8 Passing Collar Over Fixed Tip



1. Probe
2. Tip Interface
3. Fixed Tip
4. Collar

5 Screw the collar clockwise onto the tip interface until a tight fit is achieved. The tip is now installed (Figure 2.9).

Figure 2.9 Installed Fixed Tip



1. Probe
2. Tip Interface
3. Collar
4. Fixed Tip

6 Repeat steps 1 through 5 for any other probes requiring fixed tips.

Removing Fixed Tips

⚠ WARNING

SPILL HAZARD

⚠ WARNING

Use an appropriately contained environment when using hazardous materials.

⚠ WARNING

Do not spill liquids on or around the instrument. Wipe up any spills immediately according to the procedures outlined by the laboratory safety officer.

⚠ WARNING

Observe cautionary procedures as defined by your safety officer when using toxic, pathological, or radioactive materials.

⚠ WARNING

Always wear protective gloves when removing the tips.

⚠ CAUTION

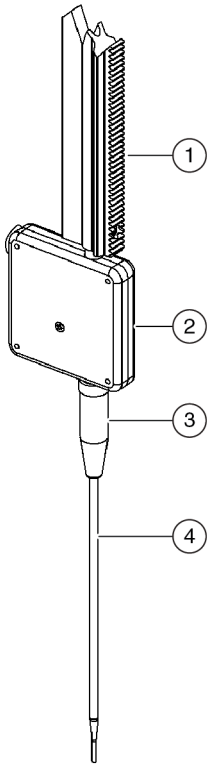
To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when working with tips on the Span-8 Pod.

NOTE A wrist ground strap must be attached to the instrument deck (base plate) prior to installing or removing tips on the Span-8 Pod (refer to *Electro-Static Discharge Protection when Changing Tips on the Span-8 Pod*).

To remove fixed tips:

1 Unscrew the collar from the bottom of the probe by turning the collar counterclockwise (Figure 2.10).

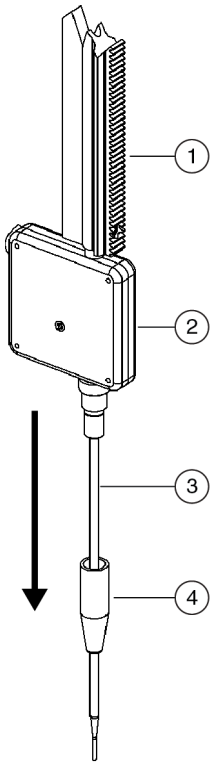
Figure 2.10 Fully Installed Fixed Tip



1. Probe
2. Tip Interface
3. Collar
4. Fixed Tip

2 Pull the collar down and off the tip (Figure 2.11).

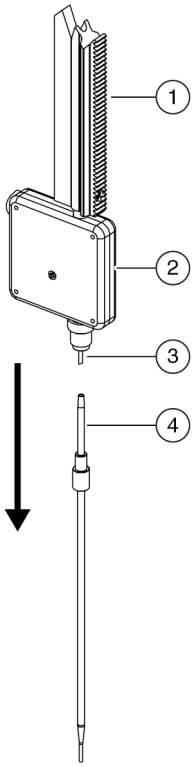
Figure 2.11 Pulling the Collar off the Fixed Tip



1. Probe
2. Tip Interface
3. Fixed Tip
4. Collar

3 Gently pull the tubing and tip down from the Span-8 probe until enough tubing is extended to grasp between thumb and forefinger (Figure 2.12).

Figure 2.12 Removing a Fixed Tip



1. Probe
2. Tip Interface
3. Tubing
4. Fixed Tip

4 While holding the tip in one hand, pull the tubing off the tip with the other hand.

NOTE Since the tubing is Teflon, it may be difficult to hold. Holding the tubing with a Kimwipe may prevent slipping while pulling the tubing off the tip.

NOTE Carefully twisting the fixed tip while pulling on the tubing may ease removal of the tip.

5 Repeat steps 1 through 4 to remove the remaining tips.

Disposable Tip Mandrels

Disposable tips can be used on the Multichannel Pod or the Span-8 Pod, but LLS disposable tips should be used only on the Span-8 Pod.

To use the disposable tips option, disposable tip mandrels must be installed on the Span-8 probes and configured for use in the **Hardware Setup** (refer to CHAPTER 3, *Configuring a Span-8 Pod*).

Installing Disposable Tip Mandrels

⚠ CAUTION

Do not perform aspirate or dispense operations without mandrels installed and tubing attached to disposable tips. To operate the system without the mandrels installed and the tubing attached to tips may cause corrosion in the tip interface.

⚠ CAUTION

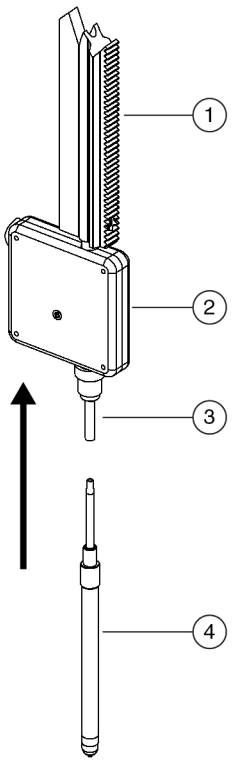
To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when working with tips on the Span-8 Pod.

NOTE A wrist ground strap must be attached to the instrument deck (base plate) prior to installing or removing tip mandrels on the Span-8 Pod (refer to *Electro-Static Discharge Protection when Changing Tips on the Span-8 Pod*).

To install disposable tip mandrels:

1 Place the end of a disposable tip mandrel into the tubing that extends from the bottom of the tip interface (Figure 2.13).

Figure 2.13 Inserting a Disposable Tip Mandrel into the Tubing



1. Probe
2. Tip Interface
3. Tubing
4. Disposable Tip Mandrel

2 While holding the disposable tip mandrel in one hand, push the tubing down onto the disposable tip mandrel with the other hand. Make sure the disposable tip mandrel is secure to prevent air entering the system and fluid leaks around the tip.

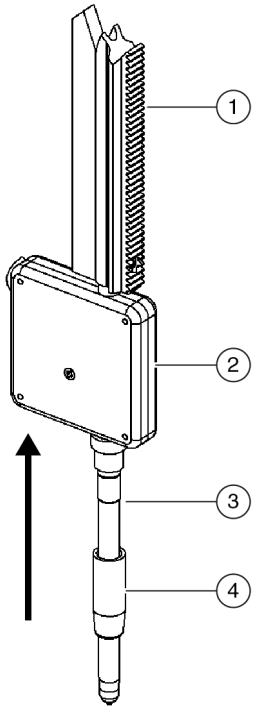
NOTE The ends of the tubing may become damaged or stretched after repeated tip installation and removal. It may be necessary to cut a small portion (1/2") of tubing off the end prior to attaching to ensure a tight fit.

NOTE Since the tubing is Teflon, it may be difficult to hold. Holding the tubing with a Kimwipe may prevent slipping while pushing the tubing down onto the tip.

3 Gently push the tubing and disposable tip mandrel up into the tip interface.

4 Pass the collar up over the disposable tip mandrel to the tip interface (Figure 2.14).

Figure 2.14 Passing Collar Over a Disposable Tip Mandrel



1. Probe
2. Tip Interface
3. Disposable Tip Mandrel
4. Collar

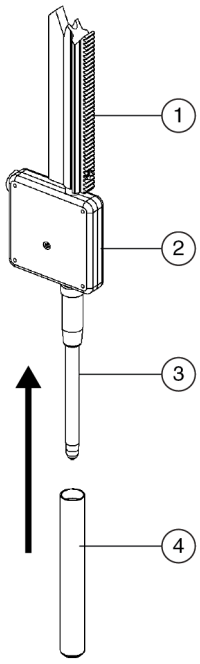
5 Screw the collar clockwise into the tip interface until a tight fit is achieved.

NOTE If the tip mandril is not held, the syringe line twists at the top of the probe assembly and kinks.

NOTE Each week, check that disposal tip collars are securely fastened to the tip interface. Disposal tips may not shuck if collars are loose.

6 Pass the tip shuck tube up over the disposable tip mandrel to the tip interface (Figure 2.15).

Figure 2.15 Installing a Tip Shuck Tube on a Disposable Tip Mandrel



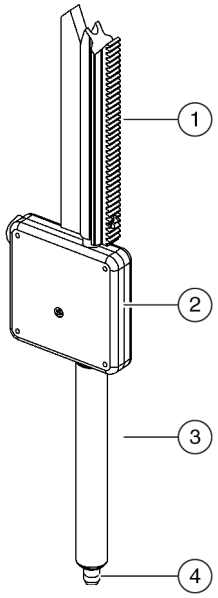
1. Probe
2. Tip Interface
3. Disposable Tip Mandrel
4. Tip Shuck Tube

7 Screw the tip shuck tube clockwise into the tip interface until a tight fit is achieved. Make sure the tip shuck tube is securely tightened to prevent it from working off during operation. The disposable tip mandrel is now installed (Figure 2.16).

⚠ CAUTION

Do not overtighten the tip shuck tube. Problems with unloading tips may result.

Figure 2.16 Installed Disposable Tip Mandrel



1. Probe
2. Tip Interface
3. Tip Shuck Tube
4. Disposable Tip Mandrel

8 Repeat steps 1 through 7 for any other probes requiring disposable tips.

Removing the Disposable Tips Option

To remove the disposable tips option, the disposable tip mandrels must be removed from the Span-8 probes.

⚠ WARNING

SPILL HAZARD

⚠ WARNING

Use an appropriately contained environment when using hazardous materials.

⚠ WARNING

Do not spill liquids on or around the instrument. Wipe up any spills immediately according to the procedures outlined by the laboratory safety officer.

⚠ WARNING

Observe cautionary procedures as defined by your safety officer when using toxic, pathological, or radioactive materials.

⚠ WARNING

Always wear protective gloves when removing the tips.

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when working with tips on the Span-8 Pod.

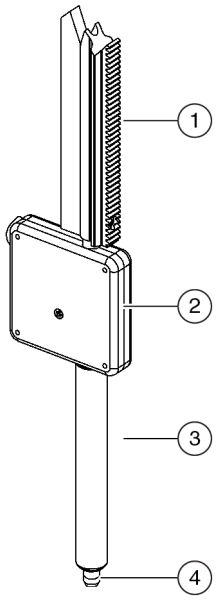
NOTE Disposable tips should be disposed of into a Span-8 Disposal ALP prior to removal of the disposal tips option.

NOTE A wrist ground strap must be attached to the instrument deck prior to installing or removing tip mandrels on the Span-8 Pod (refer to *Electro-Static Discharge Protection when Changing Tips on the Span-8 Pod*).

To remove the disposable tips option:

1 Unscrew the tip shuck tube counterclockwise from the bottom of the tip interface (Figure 2.17).

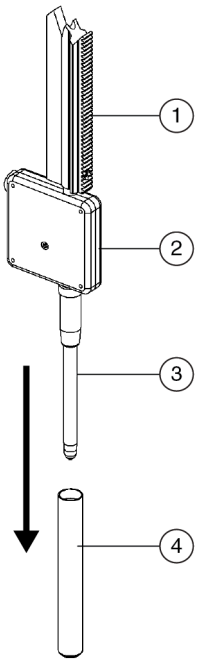
Figure 2.17 Fully Installed Disposable Tip Mandrel



1. Probe
2. Tip Interface
3. Tip Shuck Tube
4. Disposable Tip Mandrel

2 Pull the tip shuck tube down and off the disposable tip mandrel (Figure 2.18).

Figure 2.18 Removing a Tip Shuck Tube From a Disposable Tip Mandrel

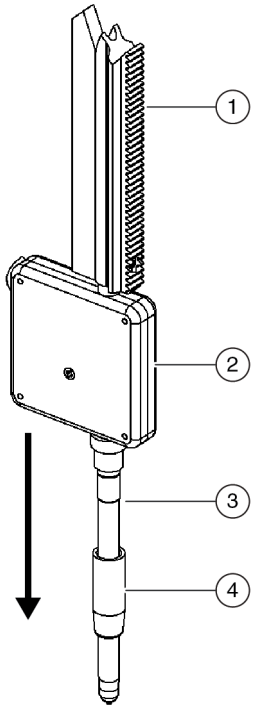


1. Probe
2. Tip Interface
3. Disposable Tip Mandrel
4. Tip Shuck Tube

3 Unscrew the collar counterclockwise from the bottom of the tip interface.

4 Pull the collar down and off the disposable tip mandrel (Figure 2.19).

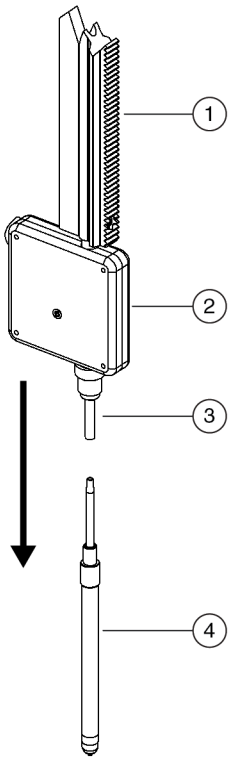
Figure 2.19 Removing the Collar from a Disposable Tip Mandrel



1. Probe
2. Tip Interface
3. Disposable Tip Mandrel
4. Collar

5 Gently pull the tubing and disposable tip mandrel down from the tip interface until enough tubing is extended to grasp between thumb and forefinger (Figure 2.20).

Figure 2.20 Detaching a Disposable Tip Mandrel from the Probe Tubing



1. Probe
2. Tip Interface
3. Tubing
4. Disposable Tip Mandrel

6 While holding the disposable tip mandrel in one hand, gently pull the tubing off the mandrel with the other hand (Figure 2.20).

NOTE Since the tubing is Teflon, it may be difficult to hold. Holding the tubing with a Kimwipe may prevent slipping.

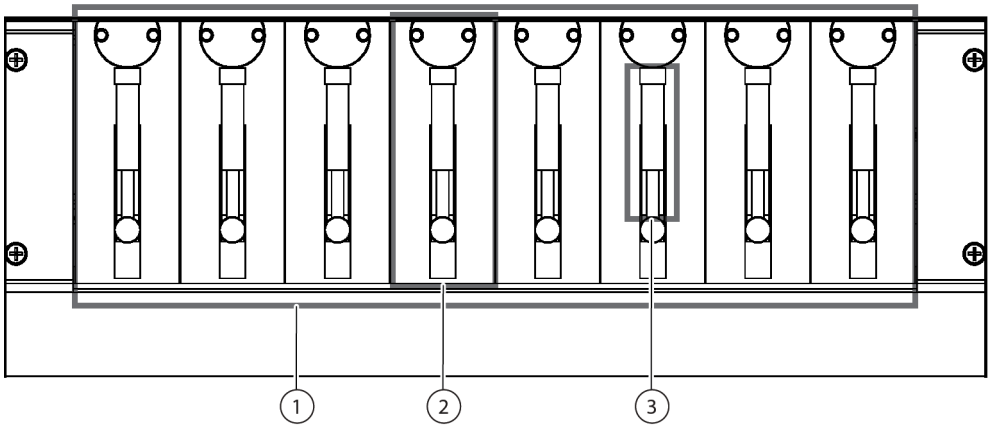
NOTE Carefully twisting the mandrel while pulling on the tubing may ease removal of the mandrel.

7 Repeat steps 1 through 6 for any other probes requiring disposable tip mandrels.

Pump Assembly

The pump assembly comprises eight pumps and syringes, one for each of the eight probes in the Span-8 Pod (Figure 2.21). The pumps and syringes of the pump assembly provide a vacuum which allows the aspirate and dispense actions of the Span-8 Pod.

Figure 2.21 Span-8 Pump Assembly



1. Pump Assembly — The pump assembly consists of the eight pumps, one for each of the Span-8 probes.
2. Pump
3. Syringe

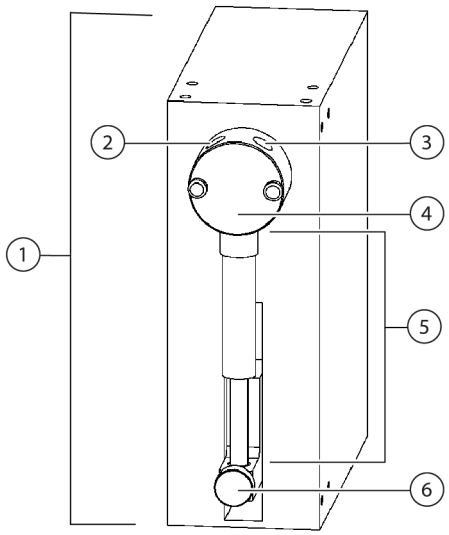
Pumps

The pumps control the flow of system fluid into the syringes, tubes, and probes of the Span-8 Pod. The amount and direction for the flow of system fluid is controlled by setting the state of the valve in the pump. The valve can be set to one of three states:

- Input — Opens the valve and allows system fluid to flow to and from the syringe with the supply container as the source/destination of the fluid.
- Output — Opens the valve and allows system fluid to flow to and from the syringe with the tip as the source/destination of the fluid.
- Bypass — Opens the valve and allows system fluid to flow through the valve without activating (bypassing) the syringe.

NOTE The state of a valve can be changed in Advanced Manual Control, if necessary (refer to CHAPTER 5, *Setting Valve States*).

Figure 2.22 Pump and Syringe



1. Pump
2. Input
3. Output
4. Valve
5. Syringe
6. Thumbscrew

Syringes

A syringe is housed in each of the eight pumps in the pump assembly (Figure 2.21 and Figure 2.22). Syringes provide pipetting accuracy by controlling the amount of system fluid aspirated from and dispensed into the tubing for each of the eight Span-8 probes. The volume of fluid aspirated and dispensed by the syringes is equivalent to the volume the probes aspirate and dispense.

How Syringes Affect Pipetting Accuracy

Syringes affect pipetting accuracy by:

- controlling the amount of system fluid aspirated from and dispensed into the tubing for each of the eight Span-8 probes.

  NOTE The volume of fluid aspirated into and dispensed from the Span-8 tubing is approximately equivalent to the volume of fluid a tip aspirates and dispenses.

- maintaining a minimum and maximum operational speed which dictates how fast fluid can be aspirated into and dispensed from the syringes and, ultimately, the tips.

- controlling the amount of fluid dispensed per second by a syringe before the dispense action of the syringe abruptly stops.

  NOTE The speed at which fluid is dispensed per second prior to the dispense action abruptly stopping is called the **Cutoff Velocity**. If the **Cutoff Velocity** in the technique or liquid type governing the pipetting operation is too slow, droplets can be left at the end of tips after a dispense pipetting operation rather than all the liquid dispensing into the labware.

Syringe Size

The size of a syringe dictates the maximum amount of fluid aspirated into and dispensed from the tubing for each of the eight Span-8 probes and the speed at which the fluid flows.

Syringes are available in three sizes:

- 250 µL
- 500 µL
- 1mL

Two different sizes of syringes can be used in the pump assembly at the same time in order to perform pipetting operations at different volumes during a single method.

NOTE Probes 1 through 4 must all use the same size syringe, and probes 5 through 8 must all use the same size.

If two different sizes of syringes are required to ensure pipetting accuracy within a single method, or the size of syringes installed in the Biomek FX instrument changes frequently, new techniques for each size of syringe should be created. This is accomplished by copying the Span-8 techniques to create multiple sets of techniques and by editing the Cutoff Velocity and other pipetting parameters in those techniques to support the size of syringe(s) installed.

NOTE Refer to the *Biomek Software User's Manual* (PN 987835), *Modifying Saved Techniques*, for more information on copying techniques and *Overriding Liquid Type Values*, for more information on editing liquid types.

Assembling and Installing Syringes

Syringes are shipped in two pieces:

- Plunger
- Glass casing

Once assembled, these two pieces constitute the syringe.

NOTE A syringe reflecting the maximum volume most frequently aspirated and dispensed during a method should be installed in the pumps.

To assemble and install syringes:

---

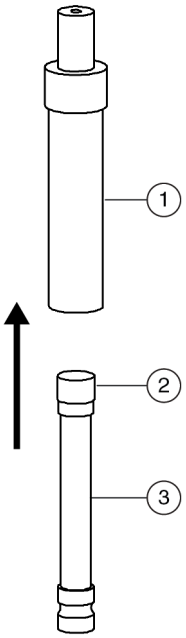
1 Remove the syringe components (plunger and glass casing) from their original packaging material.

2 Moisten the rubber gasket on the end of the plunger with water.

3 Insert the end of the plunger with a rubber gasket into the glass casing.

4 Push the plunger into the glass casing until it stops (Figure 2.23). The syringe is now assembled.

Figure 2.23 Installing Syringes — Assembling the Syringe



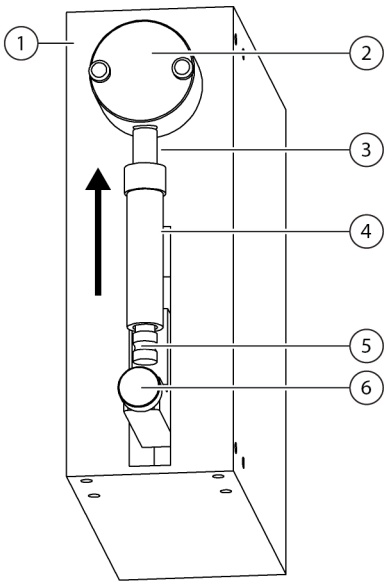
1. Glass Casing
2. Rubber Gasket
3. Plunger

5 Gently insert the top of the syringe into the valve (Figure 2.24).

6 Screw the top of the syringe into the valve by turning the syringe to the right until finger tight (Figure 2.24).

NOTE Make sure the syringe is secure to prevent air entering the system and fluid leaks around the syringe.

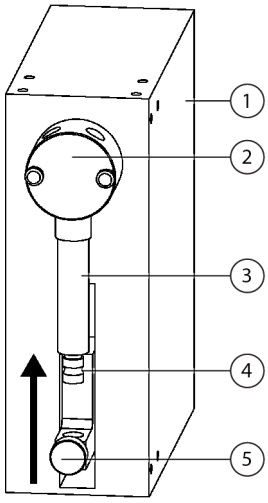
Figure 2.24 Installing Syringes — Push the Syringe up Into the Valve and Screw it in



1. Pump
2. Valve
3. Top of the Syringe
4. Syringe
5. Base of the Syringe
6. Thumbscrew

7 Push the thumbscrew up to the base of the syringe (Figure 2.25).

Figure 2.25 Installing Syringes — Push the Thumbscrew Up



1. Pump
2. Valve
3. Syringe
4. Base of the Syringe
5. Thumbscrew

NOTE Four syringes are configured at a time: syringes for probes 1 through 4 and syringes for probes 5 through 8. Probes 1 through 4 may be configured with one size of syringe and probes 5 through 8 may be configured with another size of syringe.

8 Tighten the thumbscrew at the base of the syringe by turning the thumbscrew to the right until finger tight.

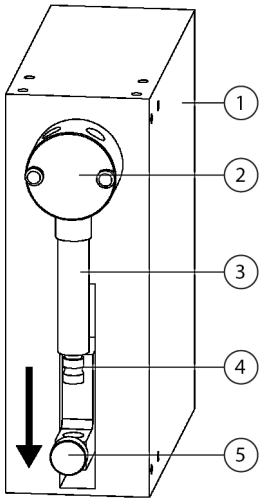
Removing and Disassembling Syringes

To remove and disassemble syringes:

1 Loosen the thumbscrew at the base of the syringe by turning the thumbscrew to the left.

2 Pull the thumbscrew down (away) from the syringe (Figure 2.26).

Figure 2.26 Removing Syringes — Loosen the Thumbscrew and Pull Down

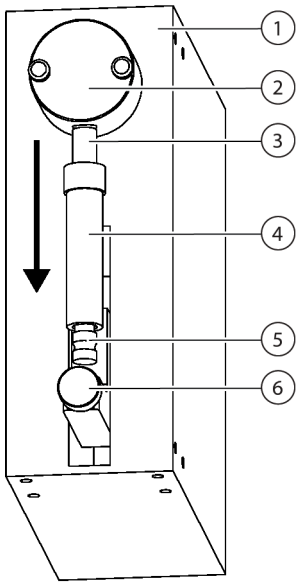


1. Pump
2. Valve
3. Syringe
4. Base of the Syringe
5. Thumbscrew

3 Unscrew the top of the syringe from the valve by turning the syringe to the left.

4 Gently pull the syringe down from the valve (Figure 2.27).

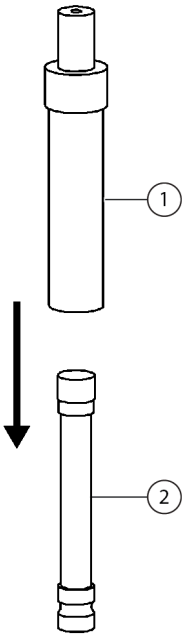
Figure 2.27 Removing Syringes — Unscrewing and Pull Down on the Syringe



1. Pump
2. Valve
3. Top of the Syringe
4. Syringe
5. Base of the Syringe
6. Thumbscrew

5 Gently pull the plunger out of the glass casing (Figure 2.28).

Figure 2.28 Removing Syringes — Pulling the Syringe out of the Glass Casing



1. Glass Casing
2. Plunger

6 Return the syringe components (plunger and glass casing) to their original packaging material.

NOTE Syringes are configured in two sets of four. Each set of four syringes may be configured with different size syringes.

Syringe Cutoff Velocities

The speed at which fluid is dispensed per second prior to the dispense action abruptly stopping is called the **Cutoff Velocity**. If the **Cutoff Velocity** in the technique or liquid type governing the pipetting operation is too slow, droplets can be left at the end of tips after a dispense pipetting operation. Accurately setting the **Cutoff Velocity** causes the liquid to be ejected at a speed sufficient to prevent droplets from forming on the end of a tip.

NOTE Refer to the *Biomek Software User's Manual* (PN 987835), *Syringe Cutoff Velocities (FX, NX-S8 only)*, and *Changing the Cutoff Velocity for Span-8 Pods in Liquid Type Editor (FX, NX-S8 only)*.

The minimum and maximum **Cutoff Velocity** for the syringes supported by the Biomek FX are listed in Table 2.4.

NOTE The default **Cutoff Velocity** value for all techniques and liquid types is the recommended **Cutoff Velocity** for a 1 mL syringe. When 250 µL or 500 µL syringes are installed on the Biomek FX instrument, changes must be made to the technique governing the pipetting operation in the **Technique Editor**, and to the parameters of the fluid used during the pipetting operation in the **Liquid Type Editor**.

NOTE The **Cutoff Velocities** recommended in Table 2.4 are intended as a starting point. The values provided should be experimented with in order to determine the most accurate **Cutoff Velocity** for a specific liquid handling operation.

Table 2.4 Span-8 Cutoff Velocities for Syringes

Syringe Size	Minimum Cutoff Velocity[a]	Maximum Cutoff Velocity[b]	Recommended Cutoff Velocity
250 µL	2.08 µL per second	112.5 µL per second	100 µL per second
500 µL	4.17 µL per second	225 µL per second	150 µL per second
1 mL	8.33 µL per second	450 µL per second	150 µL per second

a. The minimum **Cutoff Velocity** for each syringe is established using the following equation: 50 x <Syringe size in µL>/6000.
b. The maximum **Cutoff Velocity** for each syringe is established using this equation: 2700 x <Syringe size in µL>/6000.

Optimizing Syringe Performance and Life Expectancy

Syringes should be used, cleaned, and stored in accordance with the manufacturer's specifications in order to achieve optimal performance and maximum life expectancy.

⚠ CAUTION

Do not run syringes more than a few cycles without fluid in the syringes.

Syringes should not actuate while dry unless the system is being primed (refer to *Priming the System with System Fluid*). When priming the system, the syringes should cycle at maximum volume as few times as possible in order to flood the syringe with system fluid as quickly as possible.

NOTE A cycle is one up or down motion of the plunger in a syringe. Refer to *Assembling and Installing Syringes*, for identification of the parts of a syringe.

Liquid System

The Span-8 Pod uses a liquids system to provide a vacuum for pipetting operations, as well as for tip washing and bulk dispense.

The liquid system includes:

- **System Fluid** — Acts as a medium for syringes to apply a vacuum used during pipetting operations and is used to wash fixed tips in the Span-8 Pod Tip Wash ALP (refer to *System Fluid*).

- **Tubing** — System fluids are moved through the tubing (refer to *Tubing*).
- **Supply Container** — Source of system fluid for the Span-8 Pod (refer to *Supply Container*).
- **Waste Container** — Final destination of fluids dispensed to the Span-8 Tip Wash ALP and overflow from the pumps (refer to *Waste Container*).

System Fluid

The system fluid is used to create a vacuum that facilitates the aspirate and dispense actions of the Span-8 Pod. System fluid is also used to wash fixed tips positioned in the Span-8 Tip Wash ALP.

⚠ CAUTION

Tap water is not recommended due to high mineral content which could cause blockages in the tubing and increase the possibility of leaks at tubing connections.

The following liquids are recommended as system fluid for the Span-8 Pod:

- De-ionized water
- Distilled water

NOTE It is possible to use system fluids other than those supported for use with the Span-8 Pod. However, the corrosive nature of each fluid and its impact on system components along the Span-8 system fluid flow path and in the Span-8 Tip Wash ALP must be considered.

Using Non-Supported System Fluids

System fluids other than those listed as supported system fluids (refer to *System Fluid*) may damage the components along the Span-8 system fluid flow path and the Span-8 Tip Wash ALP. Therefore, before using non-supported system fluids, use Table 2.5 to verify that component parts along the Span-8 system fluid flow path are not susceptible to the caustic nature of any non-supported system fluids. Use Table 2.6 to verify the parts on the Span-8 Tip Wash ALP are not susceptible to the caustic nature of any non-supported system fluids.

NOTE All system fluid, whether supported or non-supported, must be degassed prior to use. The system must then be primed with the new system fluid and the Span-8 system tubing must be purged of air. Refer to *Preparing the Liquid System* for more information on degassing, priming, and air purging procedures.

Parts Along the Span-8 System Fluid flow Path

Each of the Span-8 system parts listed in Table 2.5 comes into contact with the system fluid and must be considered for possible susceptibility to the caustic nature of non-supported system fluid.

Table 2.5 Parts and Materials Along the Span-8 Fluid Flow Path

Part	Material
Carboy	Polypropylene
Supply carboy tubing	Tygon 2075
Carboy Cap	Polypropylene
Tubing (cap to quick disconnect)	Tygon 2075
Quick Disconnect Body	Polypropylene, EPDM, and Stainless Steel
Quick Disconnect insert	Polypropylene, EPDM, and Stainless Steel
Supply tubing	Tygon 2075
Manifold Inlet fitting	Polypropylene
Manifold	There are two styles of manifolds: Teflon manifolds (Part # 717892) Polypropylene manifolds (Part # 719964)
Tubing (manifold to pump)	Teflon Stainless Steel and Polypropylene fittings should not contact liquid if tightened properly.
Pump valve	Kel-F
Valve plug	Virgin Teflon
Syringe	Glass
Syringe piston seal	Teflon
Tubing (pump to the tips)	Teflon **NOTE** Polypropylene fittings should not contact liquid if tightened properly.
Tips: Fixed Disposable Conductive Disposable tips	 Stainless Steel or Teflon Coated Stainless Steel Polypropylene Polypropylene Impregnated with Carbon
Disposable tip mandrel	Stainless Steel

NOTE All fitting threads may be wrapped with Teflon tape.

Parts Along the Wash Station System Fluid Flow Path

Since system fluid may be used as a wash fluid, each of the Span-8 Tip Wash ALP parts that comes into contact with the system fluid or waste fluid must also be considered for possible susceptibility to the caustic nature of non-supported system fluid and is therefore listed in Table 2.6.

Table 2.6 Parts and Materials Along the Span-8 Tip Wash ALP Flow Path

Part	Material
8-Channel Passive Wash ALP	Polypropylene
Outlet Fitting	Polypropylene
Tubing	Tygon 2075
Quick Disconnect insert	Polypropylene, EPDM, and Stainless Steel
Quick Disconnect body	Polypropylene, EPDM, and Stainless Steel
Tubing	Tygon 2075
Cap	Polypropylene
Carboy	Polypropylene

NOTE All fitting threads may be wrapped with Teflon tape.

Tubing

The tubing is a means of transporting system fluid to and from the Span-8 Pod. The Span-8 Pod uses 1/8-in. tubing from the supply container to each syringe pump, 1/8-in. tubing from the syringe pumps to the probes of the Span-8 Pod, and 1/4-in. tubing from the pump assemblies overflow to the waste container.

NOTE The 1/4-in. tubing is Tygon 2075 (ultra-chemical resistant). All 1/8-in. tubing is Teflon. All diameters refer to outer diameter dimensions.

Supply Container

⚠ WARNING

SPILL HAZARD.

⚠ CAUTION

Do not kink tubing between the supply container and the Span-8 pumps.

⚠ WARNING

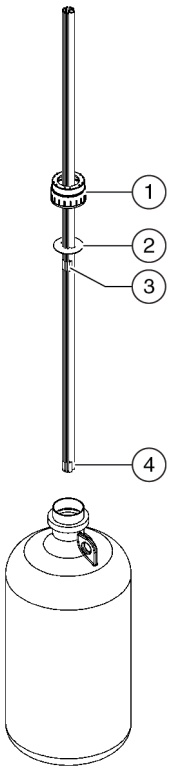
Do not spill liquids on or around the instrument. Wipe up any spills immediately according to the procedures outlined by the laboratory safety officer.

The supply container is the source of the system fluid used by syringe pumps for the Span-8 Pod (Figure 2.29).

The supply container attaches to the Biomek FX Span-8 instrument via eight 1/8-in. tubing lines from the syringe pumps. In the supply container, the eight lines are bundled together using two tubing retainers, a gasket, and container cap.

NOTE Supply containers can be reused when they are filled with a system fluid recommended for the Span-8 Pod (refer to *System Fluid*).

Figure 2.29 Supply Container and Tubing Bundle



1. Cap
2. Gasket
3. Upper tubing retainer
4. Lower tubing retainer

Exchanging Supply Containers

The supply tubing is initially bundled by a Beckman Coulter Representative when the Biomek FX Span-8 instrument is installed. When supply containers are exchanged, the bundled tubing and container cap are transferred as one unit from the old container to the new container.

This section also contains complete instructions fro bundling the tubing (refer to *Bundling the Supply Tubing*).

Exchanging Supply Containers Without Rebundling the Tubing

To exchange supply containers without rebundling the tubing:

---

1 Unscrew the cap from the empty container and remove it and the tubing bundle.

---

2 Insert the tubing bundle into the new container and screw the cap on until hand tight.

3 Remove the empty container.

NOTE Supply containers can be refilled with system fluid, degassed, and then reattached to the Biomek FX Span-8 instrument.

4 Position a new supply container in the same location the original supply container occupied.

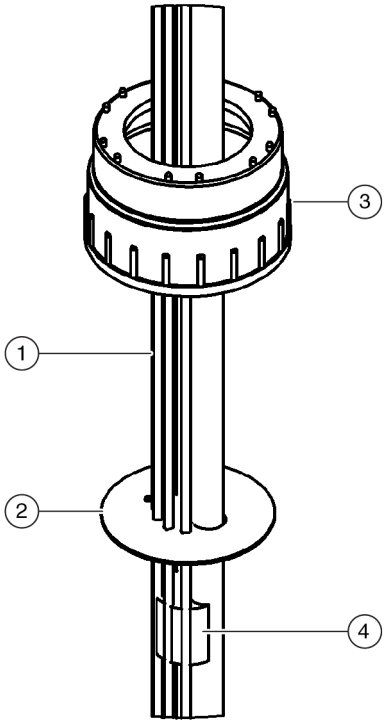
NOTE The supply container is positioned at installation to minimize tubing length and to keep kinks and bends out of the tubing and to reduce uphill slopes as much as possible. Positioning the new supply container in the same location ensures proper alignment of the tubing and reduces pipetting errors due to air in the tubing.

Bundling the Supply Tubing

To bundle the supply tubing:

1 Route the tubing from the syringe pumps through the cap (Figure 2.30).

Figure 2.30 Supply Tubing Bundle (Upper)



1. Syringe Pump Supply Tubing
2. Gasket
3. Cap
4. Upper Tubing Retainer

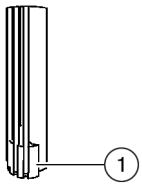
2 Thread each tubing line through a matching hole in the gasket.

3 Push the gasket up the tubing to the position where the tubing emerges from the container through the cap. Make sure the gasket is positioned so that the bottom of the tubing reaches the bottom of the container.

4 Position the upper tubing retainer approximately 1/2 in. (13 mm) below the gasket, and press each tubing line into a matching groove on the retainer until it is firmly secured.

5 Position the lower tubing retainer at the end of the tubing, and press each tubing line into a groove on the retainer until it is firmly secured (Figure 2.31). The weight of the lower tubing retainer ensures that the tubing ends remain at the bottom of the container.

Figure 2.31 Supply Tubing Bundle (Lower)



1. Lower Tubing Retainer

Waste Container

⚠ WARNING

SPILL HAZARD.

⚠ CAUTION

Do not kink tubing between the waste container, the Span-8 Tip Wash ALP and drip tray.

⚠ WARNING

Observe cautionary procedures as defined by your safety officer when using toxic, pathologic, or radioactive materials.

⚠ WARNING

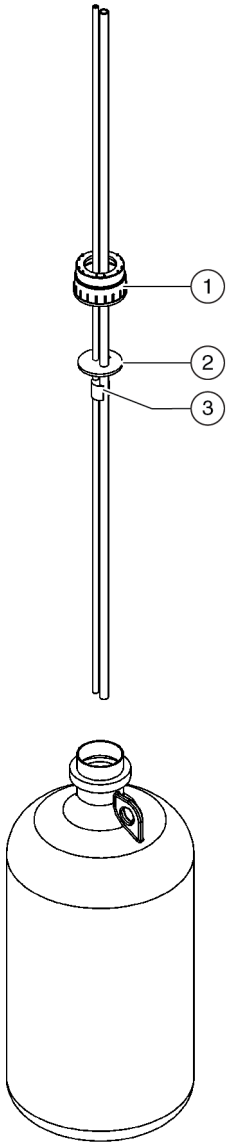
Do not spill liquids on or around the instrument. Wipe up any spills immediately according to the procedures outlined by the laboratory safety officer.

The waste container is an off-deck disposal site for fluid from the Span-8 Tip Wash ALP (refer to the *ALPs User's Manual* (PN 987836), *Span-8 Tip Wash ALP*) and drip tray.

The waste container attaches to the Biomek FX Span-8 instrument via a 3/8-in. tubing line from the Span-8 Tip Wash ALP and a 1/4-in. tubing line from the drip tray. In the waste container, the lines are bundled together using a tubing retainer, a gasket, and container cap.

NOTE Separate waste containers can be used for each Span-8 Tip Wash ALP on the deck if it is undesirable to mix the contaminates washed off the tips.

Figure 2.32 Waste Container and Tubing



1. Cap
2. Gasket
3. Tubing retainer

Exchanging a Waste Container

The waste tubing is initially bundled by a Beckman Coulter Representative when the Biomek FX Span-8 instrument is installed. When waste containers are exchanged, the bundled tubing and container cap are transferred as one unit from the old container to the new container.

This section also contains complete instructions for bundling the tubing (refer to *Bundling the Waste Tubing*).

Exchanging Waste Containers Without Rebundling the Tubing

To exchange waste containers without rebundling the tubing:

1 Unscrew the cap from the empty container and remove it and the tubing bundle.

2 Insert the tubing bundle into the new container and screw the cap on until hand tight.

3 Remove the full waste container and dispose of as directed by the laboratory safety officer.

NOTE Waste containers can be reused; however, waste materials contained in the waste container must be disposed of as directed by the laboratory safety officer.

4 Position a new waste container in the same location the original waste container occupied.

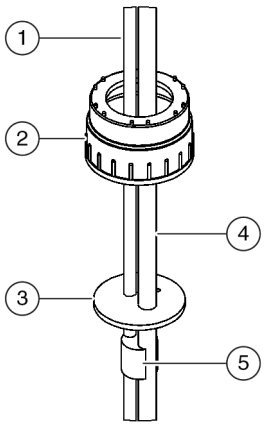
NOTE The waste container is positioned at installation to minimize tubing length to keep kinks and bends out of the tubing and to reduce uphill slopes as much as possible. Positioning the new waste container in the same location ensures proper alignment of the tubing and maximizes drainage from the Span-8 Tip Wash ALP and drip tray.

Bundling the Waste Tubing

To bundle the waste tubing:

1 Route the tubing from the Span-8 Tip Wash ALP and drip tray through the cap (Figure 2.30).

Figure 2.33 Waste Tubing Bundle



1. Drip Tray Waste Tubing
2. Cap
3. Gasket
4. Span-8 Tip Wash ALP Waste Tubing
5. Tubing Retainer

2 Thread each tubing line through the matching hole in the gasket.

3 Push the gasket up the tubing to the position where the tubing emerges from the container through the cap.

4 Position the tubing retainer approximately 1/2-in. (13 mm) below the gasket, and press each tubing line into the matching groove on the retainer until it is firmly secured.

Preparing the Liquid System

Air must be removed from the system fluid and tubing to maximize the pipetting performance of the Span-8 Pod. Air removal is accomplished by:

- *Degassing the System Fluid*
- *Priming the System with System Fluid*
- *Purging the Tubing and Syringes of Air*

Degassing the System Fluid

⚠ CAUTION

The system fluid must be degassed prior to use.

Degassing the system fluid improves pipetting accuracy by reducing the amount of air in the system fluid. The system fluid is compressed and released in the syringes to create a vacuum used during pipetting operations; however, air in the system fluid compresses at a different rate than the system fluid itself, which can cause pipetting errors. To reduce pipetting errors caused by air in the system fluid, the system fluid must be degassed prior to priming the Biomek FX Span-8 instrument with the system fluid.

Degassing the system fluid is accomplished by letting the system fluid rest in the supply container for 24 to 48 hours prior to attaching it to the Biomek FX Span-8 instrument (refer to *Supply Container*). The lack of motion allows the air bubbles in the system fluid to escape or burst prior to use.

NOTE It is recommended that extra supply containers be degassed at all times so that properly degassed system fluid is readily available when a supply container must be replaced (refer to *Supply Container*).

Priming the System with System Fluid

Priming the system is the initial aspiration of system fluid into the tubing for the Span-8 Pod. It ensures that system fluid is in all the tubing prior to purging the system of air and performing any pipetting actions. Priming the system with system fluid is accomplished through **Manual Control** (refer to *Purging the Tubing and Syringes of Air*).

Purging the Tubing and Syringes of Air

⚠ CAUTION

Do not purge the system without mandrels installed and tubing attached to disposable or fixed tips. To purge the system without the mandrels installed and the tubing attached to tips may cause corrosion in the tip interface.

To accurately transfer liquid using the Span-8 Pod, air must be purged from the tubing and syringes prior to running a method. The tubing and syringes must also be purged of air after new tips or syringes are installed. The purging process draws system fluid through the tubing and syringes until all air bubbles are removed from the tubing and syringes. Purging the tubing and syringes of air is accomplished through **Manual Control** (refer to *Purging the Tubing and Syringes of Air*).

Speed Pump

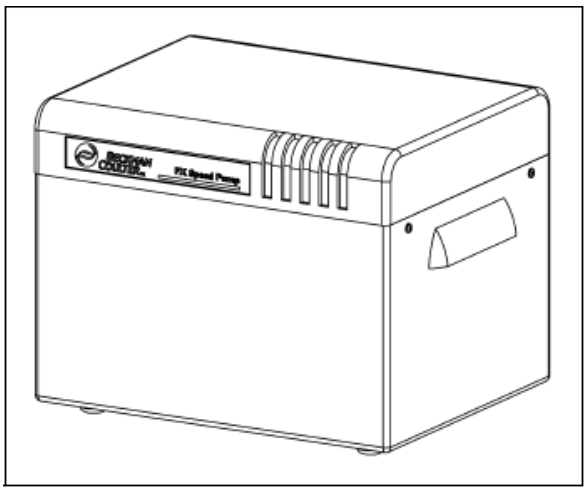
The Speed Pump (Figure 2.34) is an optional device used to increase the speed of the tip washing process in the Span-8 Tip Wash ALP; refer to the ALPs User's Manual (PN 987836), *Span-8 Tip Wash ALP*. The Speed Pump propels system fluid through fixed tips at a rate of speed greater than can be supplied by the pumps and syringes. The increased speed, when used in conjunction with the Span-8 Tip Wash ALP, is sufficient to clean the inside and outside of any fixed tips.

The flow of system fluid is controlled by the Speed Pump without actuating the pumps or syringes. When the Span-8 Pod needs to perform a tip wash in the Span-8 Tip Wash ALP with the assistance of a Speed Pump, a **Device Action** step must be inserted in the method prior to the **Span-8 Wash Tips** step, and the Use speed pump option must be selected. The Use speed pump option facilitates setting the valves in the pumps to bypass, so the pumps and syringes are not used (refer to the *Biomek Software User's Manual* (PN 987835), *Configuring the Device Action Step for a Positive Position ALP (FX, NX only)*).

NOTE The volume of fluid used during the tip wash and the number of wash cycles completed are set in the Span-8 Wash Tips step configuration (refer to the *Biomek Software User's Manual* (PN 987835), *Span-8 Wash Tips Step*).

NOTE The Speed Pump is used only during the tip wash process for fixed tips. Disposable tips cannot be washed in the Span-8 Tip Wash ALP.

Figure 2.34 Speed Pump (Front View)



NOTE The Speed Pump must be positioned in line between the supply container (the source of the system fluid) and the pumps.

⚠ WARNING

Debris resulting from installing a fitting in the supply container may clog the tubing.

⚠ WARNING

Using a dirty supply container may clog the tubing.

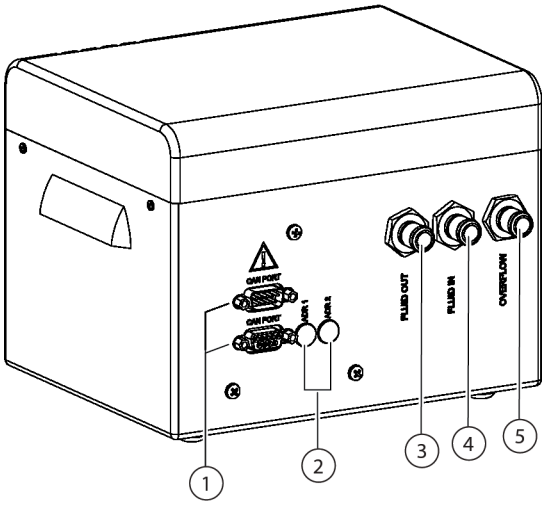
Located on the back of the Speed Pump are (Figure 2.35):

- Two CAN communication ports

  NOTE A Controller Area Network (CAN) interface with a small microcontroller provides power and communication to the Speed Pump.

- Two address switches
- One fluid out port
- One fluid in port
- One [fluid] overflow port

Figure 2.35 Speed Pump (Back View)



1. CAN Ports
2. Address Switches
3. Fluid Out
4. Fluid In
5. Overflow

The Speed Pump is shipped in two pieces:

- The Speed Pump (Figure 2.35).
- The tubing connector (with the fluid in and overflow tubes already attached) (Figure 2.36).

Speed Pump Specifications

Table 2.7 Speed Pump Specifications

Item	Description
Environment	Indoor use only.
Input Power Requirements	36V (supplied via the CAN bus)
Dimensions	7.52 in. (w) × 6.04 in. (d) × 5.91 in. (h)
Weight	3.25 lbs.
Ambient Operating Temperature	5-30°C (41-86°F)
Humidity Restrictions	<85% (non-condensing) @ 30°C (86°F)

Speed Pump manufactured by:
Beckman Coulter, Inc.
250 S. Kraemer Blvd.
Brea, CA 92821 U.S.A.

Adding a Speed Pump to the Biomek FX Instrument

A Speed Pump can be installed anywhere convenient for normal operation of the Biomek FX instrument, as long as it is positioned in line between the supply container and the pumps. Installing the Speed Pump involves attaching the tubing connector to the Speed Pump and attaching the system tubing from the Biomek FX instrument to the vacant port on the tubing connector.

NOTE A Speed Pump must be configured in **Hardware Setup** after installation to the Biomek FX instrument (refer to CHAPTER 3, *Configuring a Speed Pump*).

⚠ CAUTION

Do not remove the cover of the Speed Pump.

⚠ WARNING

Turn off power to the Biomek FX before connecting CAN communication cables.

To install a Speed Pump:

1 Turn off power to the Biomek FX instrument before attaching the Speed Pump.

2 Using the Speed Pumps CAN communication cable, connect the Speed Pump to a CAN communications port on a Biomek FX tower.

NOTE Three CAN communications ports are located on each side of the Biomek FX instrument. When making the decision on which CAN communications port to use, consider the number of CAN communication ports in use and try to even the load.

NOTE Up to three Speed Pumps can be chained together. Up to two Speed Pump can connect to a CAN communications port on another Speed Pump, but one of the three Speed Pumps must be connected to a CAN communications port on a Biomek FX tower.

3 Position the Speed Pump in an off-deck location that does not interfere with the normal operation of the Biomek FX instrument.

NOTE The Speed Pump must be in line between the supply container (the source of the system fluid) and the pumps.

4 Remove the ferrule from the vacant port on the tubing connector (Figure 2.36).

5 Slide the ferrule from the vacant port on the tubing connector up approximately 1” from the end of the tubing projecting from the distribution manifold at the back of the pump assembly (Figure 2.35).

6 Slide the end of the tubing with the ferrule over the vacant port on the tubing connector (Figure 2.36).

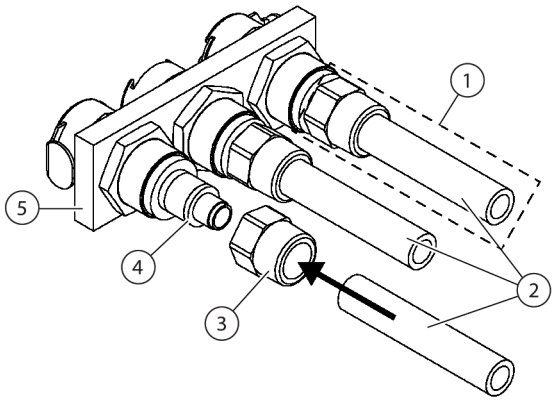
NOTE Make sure the tubing is securely seated to the port on the tubing connector.

NOTE Make sure the tubing is securely seated to the port on the tubing connector.

7 Slide the ferrule down onto the port.

8 Tightly screw the ferrule onto the port by turning the screw to the right. Visually verify that it is fully seated (Figure 2.36).

Figure 2.36 Tubing and ferrule Attachment to the Tubing Connector

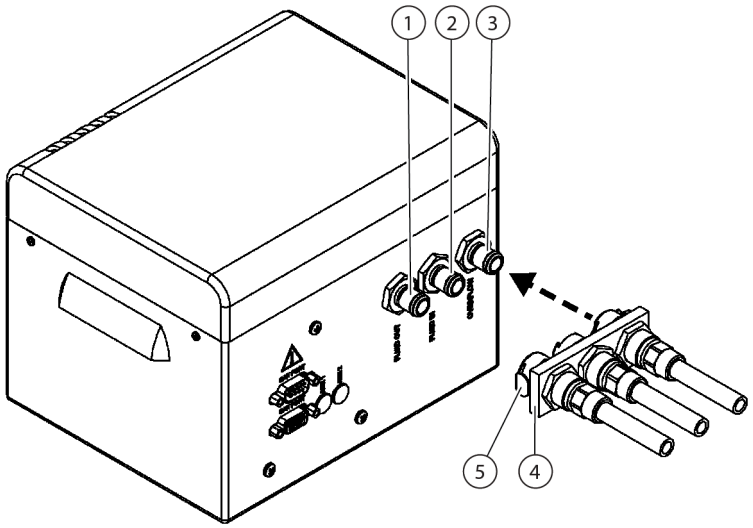


1. Attached Tubing and Ferrule: The tubing and ferrule are positioned so they are flush with the base of the port.
2. Tubing
3. Ferrule
4. Tubing Port
5. Tubing Connector

9 Attach the tubing connector to the back of the Speed Pump by squeezing the tabs on each side of the connector and pushing it firmly onto the ports on the back of the Speed Pump (Figure 2.37). The tabs snap into place when the tubing connector is attached.

NOTE Ensure that the tubing connector is attached to the Speed Pump so the tubing projecting from the distribution manifold to the pump assembly is attached to the Fluid Out port.

Figure 2.37 Attaching the Tubing Connector to the Back of the Speed Pump



1. Fluid Out Port: *Fluid passes from the Speed Pump, through the Fluid Out port, and into the distribution manifold for the pump assembly.*
2. Fluid In Port: *Fluid passes from the supply container, through the Fluid In port, and into the Speed Pump.*
3. Overflow Port: *Unused system fluid passes through the Overflow port on its way back to the supply container.*
4. Tubing Connector
5. Tabs: *Squeeze the silver tabs to mount the tubing connector to the Speed Pump. (There are two tabs, one on each end of the tubing connector.)*

10 Run the tubing connected to the Fluid In port to the supply container containing the system fluid.

11 Cut the length of the Fluid In tubing so no excess tubing is used.

12 Run the tubing connected to the Overflow port to the supply container.

NOTE The supply container must be positioned below the height of the Speed Pump.

13 Cut the length of the Overflow tubing so no excess tubing is used and no rises or bumps occur between the Speed Pump and the supply container. The Speed Pump is installed.

Setting Address Switches

When more than one Speed Pump is attached to the system, a separate address must be set for each one to enable the software to identify the Speed Pump assigned a specific operation. Addresses are set using the Address Switches on the back of the Speed Pump (Figure 2.35).

To set Speed Pump addresses:

1. Make sure the power to the Biomek FX instrument is off.
2. On the first Speed Pump, make sure Address Switch 1 is set to 3.
3. On the first Speed Pump, make sure Address Switch 2 is set to 0.

   NOTE Default settings for all Speed Pumps are Address Switch 1 is set to 3 and Address Switch 2 is set to 0.
4. For a second Speed Pump, make sure Address Switch 1 is set to 3.

   NOTE Default settings for all Speed Pumps are Address Switch 1 is set to 3 and Address Switch 2 is set to 0.
5. For a second Speed Pump, turn Address Switch 2 to 1.
6. For a third Speed Pump, make sure Address Switch 1 is set to 3.
7. For a third Speed Pump, turn Address Switch 2 to 2.
8. Turn on power to the Biomek FX instrument. The Speed Pump(s) can now be identified by the Biomek FX instrument.

Preventive Maintenance

The Span-8 Pod requires little preventive maintenance; however, to ensure optimum operation, perform the following maintenance procedures as necessary.

⚠ WARNING

To prevent injury, use proper decontamination procedures.

- Make sure all spills are wiped up immediately.
- Return fixed tips, disposable tip mandrels, syringes, speed pumps, and accessories to their original packaging when they are not in use.
- Check for leaks at all tubing fittings periodically to make sure that all are tight.

  NOTE When tubing is repeatedly removed and reattached, the end of the tubing may stretch out or split. If tubing is not forming a tight fit, cut off approximately 0.5 in. of tubing to remove the damaged portion before attaching the tubing to the port.

- Check that disposable tip collars are securely tightened to the tip interfaces each week.

Troubleshooting

Do not connect or disconnect any cable while power is applied to the Biomek FX

⚠ WARNING

Do not connect or disconnect any cable while power is applied to the Biomek FX.

Perform the troubleshooting techniques presented in (see Table 2.8) when necessary.

Table 2.8 Span-8 Pod Troubleshooting

If...	Then...
Power is lost to the pod	Contact a Beckman Coulter Representative.
Motion is lost in an axis	Contact a Beckman Coulter Representative.
The probes do not work properly	Contact a Beckman Coulter Representative.
The Span-8 Pod is leaking from tubing connections	Cut off approximately 1/2 in. of tubing to remove the damaged portion before reattaching the tubing.
Leaking is occurring around syringes	Tighten the syringes.
Leaks are occurring around fixed tips	Make sure the tip is inserted securely into the tubing. Cut off approximately 1/2 in. of tubing off the end to ensure a tight fit. Make sure the collar is securely tightened to the tip interface.
Leaks are occurring around disposable tips	Make sure the disposable tip mandrel is inserted securely into the tubing. Cut off approximately 1/2 in. of tubing off the end to ensure a tight fit. Make sure the collar is securely tightened to the tip interface.
Disposable tips are not mounting correctly	Make sure the tip shuck tube is securely tightened to the tip interface.
Disposable tips are not shucking	Make sure the collar is securely tightened to the tip interface. If the collar is loose, turn the collar clockwise until a tight fit is achieved. Refer to *Installing Disposable Tip Mandrels* for more information.
Liquid level sensing is not working	Make sure LLS tips are being used (refer to *Interchangeable Tips*. Make sure LLS tips are correctly mounted to the probes (refer to *Fixed Tips*, and *Disposable Tip Mandrels*. Make sure LLS is enabled in the Technique governing the method. Refer to the *Biomek Software User's Manual* (PN 987835), *Understanding and Creating Techniques* and *Understanding and Creating Liquid Types*. Contact a Beckman Coulter Representative.
Aspirate and dispense actions are not being completed	Ensure there is system fluid in the supply container (refer to *Supply Container*).
Aspirate and dispense actions are inaccurate	Ensure tubing connections are secure (refer to *Fixed Tips* and *Removing the Disposable Tips Option*. Ensure fixed tip seating is secure (refer to *Fixed Tips*). Ensure disposable tip mandrels are correctly mounted (refer to *Installing Disposable Tip Mandrels*). Ensure system fluid and tubing have been purged of air (refer to *System Fluid*).
Tips are clipping edges of labware or not able to access labware	Reframe the position. Check to see if tip or mandrel is obviously bent. Contact a Beckman Coulter Representative.

Table 2.8 Span-8 Pod Troubleshooting

If...	Then...
Speed Pump is not operational.	Check the CAN cable connection.
The Span-8 Pod has not performed aspirate or dispense actions since installation of the Speed Pump	Make sure valves are set to bypass in Advanced Manual Control (CHAPTER 5, *Setting Valve States*). Contact a Beckman Coulter Representative.
The Speed Pumps CAN connection has been verified, its valves are set to bypass, and the Speed Pump is still not operational	Check to make sure supply container is full.
The Speed Pumps CAN connection has been verified, pumps are set to bypass and the unit is not dispensing fluid to the probes	Check to make sure supply container is full.
The Speed Pump is leaking from an area other than a tubing connection	Contact a Beckman Coulter Representative.
The Speed Pump is leaking from a tubing connection	Cut off approximately 1/2” of tubing to remove the damaged portion before reattaching the tubing.

NOTE In the case of any other pod-related problems, contact a Beckman Coulter Representative.

CHAPTER 3

Configuring the Biomek FX in Hardware Setup

Overview

The Biomek FX Laboratory Automation Workstation must be configured in Biomek Software to ensure proper operation. **Hardware Setup** tells Biomek Software what devices, pods, and heads to expect on the instrument by providing a connection between the instrument and the software. This connection is established by installing, configuring, and removing devices in **Hardware Setup**.

After a device has been physically installed, the device is detected on the Biomek FX instrument and must be properly installed and configured in **Hardware Setup**. While a new device is normally installed and configured in **Hardware Setup** when the device is installed, it also may be necessary to install, configure, and remove other devices using **Hardware Setup**.

⚠ CAUTION

Do not make any changes to the pod axes limits in Hardware Setup without contacting a Beckman Coulter Representative.

Hardware Setup is used for:

- *Configuring the Biomek FX Instrument*
- *Configuring a Multichannel Pod*
- *Configuring a Span-8 Pod*
- *Saving, Restoring, and Deleting Settings*

NOTE Any active ALPs that require a CAN communication or other devices integrated on the deck of the Biomek FX must also be configured in **Hardware Setup**. Refer to the *ALPs User's Manual* (PN 987836) or the specific device integration manual for instructions on configuring the ALP or device in **Hardware Setup**.

NOTE Refer to APPENDIX B, *Configuring the Stacker Carousel in Hardware Setup*, for information on configuring the Stacker Carousel in **Hardware Setup**.

Accessing Hardware Setup

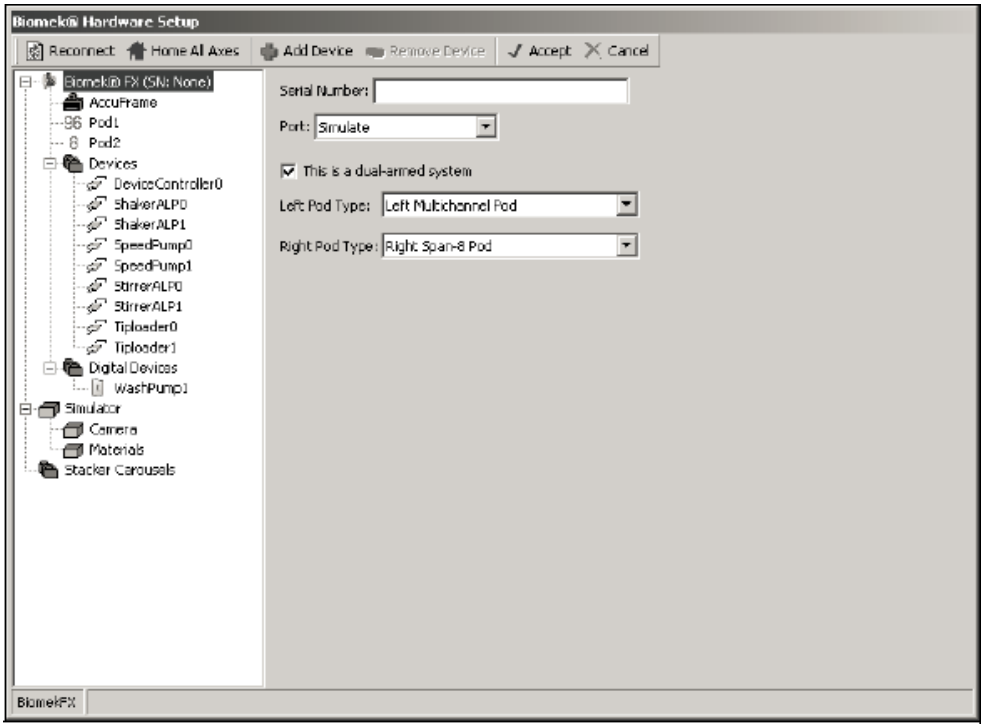
Hardware Setup (Figure 3.1) is accessed from within Biomek Software.

To access **Hardware Setup:**

1 Choose **Start > Programs > Beckman Coulter > Biomek Software.** Biomek Software appears.

2 From the **Instrument** menu, choose **Hardware Setup**. **Hardware Setup** appears (Figure 3.1).

Figure 3.1 Hardware Setup for a Dual-Pod System with a Multichannel Pod and Span-8 Pod



NOTE A single-pod system lists only the one installed pod.

Understanding the Options in Hardware Setup

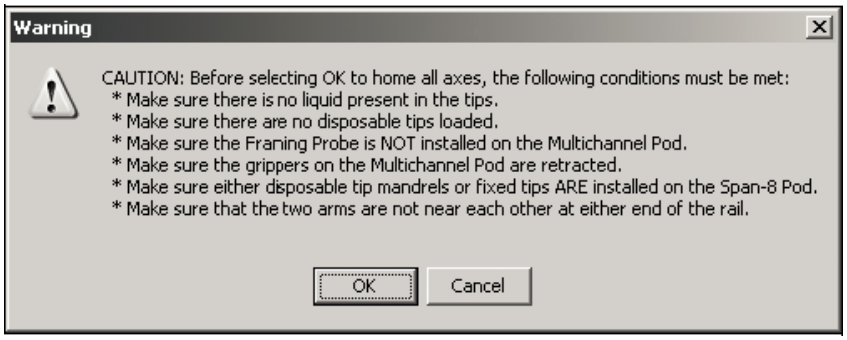
An understanding of the options on the toolbar in **Hardware Setup** (Figure 3.1) is necessary to properly install, configure, and remove devices.

Table 3.1 lists and describes the toolbar options in **Hardware Setup:**

Table 3.1 Hardware Setup Options

Option	Description
Reconnect	Allows **Hardware Setup** to reexamine the devices present. Choose this option to determine what devices are present rather than closing and reopening **Hardware Setup**.
Home All Axes	Gives the Biomek FX instrument a point of reference from which to make subsequent moves. For a single-pod system, home position is left, back. For a dual-pod system, home position for the first (left) pod is left, back and for the second (right) pod is right, back. **NOTE** Pods should be homed each time the Biomek FX instrument is powered on. Depending on the type of pods on the system, a Warning Figure 3.2 appears. After confirming that the actions have been addressed properly, choose **OK**. CHAPTER 5, *Homing All Axes of the Pod or Pods*, for more information on homing all axes of the pods.
Add Device	Installs a device.
Remove Device	Removes a device.
Accept	Saves all changes to the instrument and closes **Hardware Setup**. Choose this option after the device has been installed and configured.
Cancel	Closes **Hardware Setup** without saving the modifications to the instrument. I

Figure 3.2 Warning After Choosing Home All Axes



Configuring the Biomek FX Instrument

The Biomek FX instrument is configured in Hardware Setup to relate information about the configuration (single-arm or dual-arm) of the pod(s) on the system to the software and to specify the communications port to which it is connected.

To configure the Biomek FX instrument:

1 From **Hardware Setup**, select **Biomek FX** from the left pane. The configuration view appears in the right pane (Figure 3.3).

2 Make sure the serial number listed in **Hardware Setup** corresponds to the serial number on the Biomek FX instrument.

3 Choose the appropriate **Port**.

4 If two pods are located on the instrument, check **This is a dual-armed system**.

5 Choose the appropriate type for **Left Pod Type** and **Right Pod Type** from the drop-down menus.

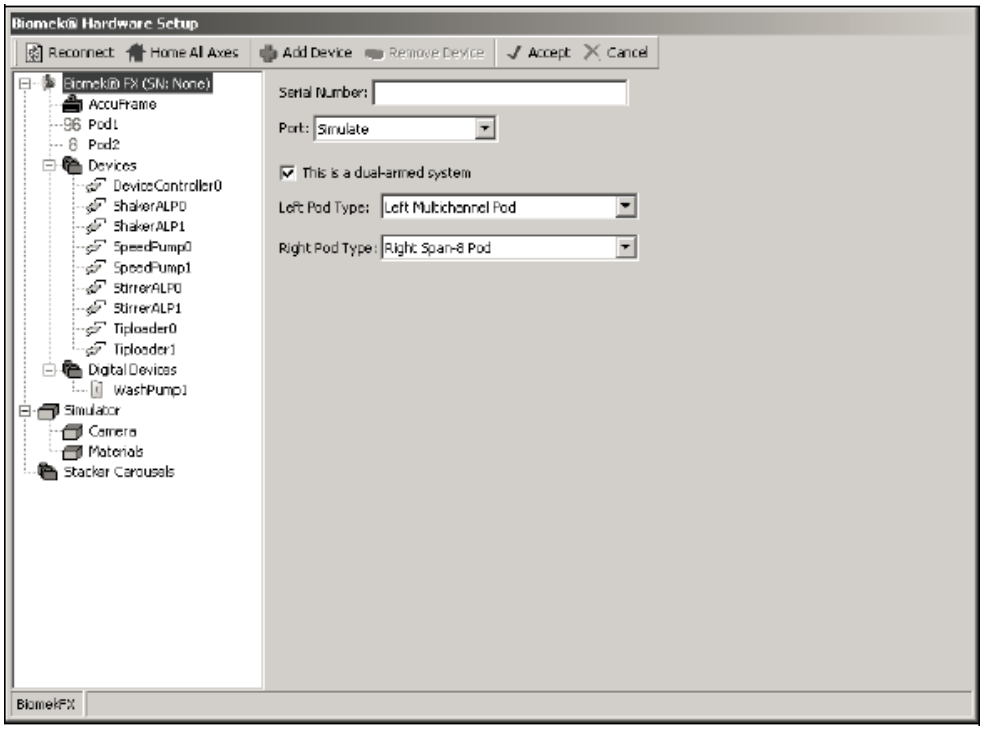
6 Configure the left and right pods appropriately according to the instructions in *Configuring a Multichannel Pod* or *Configuring a Span-8 Pod*.

7 Choose **Accept**. **Hardware Setup** closes.

NOTE **Accept** must be chosen after the instrument has been configured to allow **Hardware Setup** to accept the configurations. However, other devices may be configured when the Biomek FX instrument is configured, and **Accept** may be chosen after all devices have been configured.

NOTE An asterisk next to the device indicates the device has been modified since the instrument was loaded.

Figure 3.3 Hardware Setup Configuration for Biomek FX



Configuring a Multichannel Pod

The Multichannel Pod is a full-microplate replication tool incorporating a gripper and interchangeable heads to accommodate a variety of functions (refer to CHAPTER 1, *Multichannel Pod*). A Multichannel Pod may be installed on the right, left, or both bridges of the Biomek FX.

Configuring a Multichannel Pod in **Hardware Setup** includes:

- *Configuring a New Head*

  NOTE An HDR Tool Body is configured as a head in **Hardware Setup**.

- *Correlating the Pods*

  NOTE Correlating the pods should be performed only by a Beckman Coulter Representative at initial setup.

- *Setting Multichannel Pod Properties*, as instructed by a Beckman Coulter Representative.

NOTE The settings for a Multichannel Pod can be saved, restored, and deleted (refer to *Saving, Restoring, and Deleting Settings*).

Configuring a New Head

When a head on a Multichannel Pod is changed, the **Hardware Setup** must be changed appropriately.

⚠ CAUTION

If the hardware configuration is not updated using Hardware Setup, hardware crashes or inaccurate liquid transfer may occur.

⚠ CAUTION

To avoid hardware crashes, a new D-axis limit must be established and the gripper framed in the Biomek Software after the head has been configured in Hardware Setup.

To change the head:

NOTE First, physically change the head on a Multichannel Pod (refer to CHAPTER 1, *Changing Heads*) and then configure **Hardware Setup** according to the following instructions.

---

1 In **Hardware Setup**, select the appropriate Multichannel **Pod** (Figure 3.4).

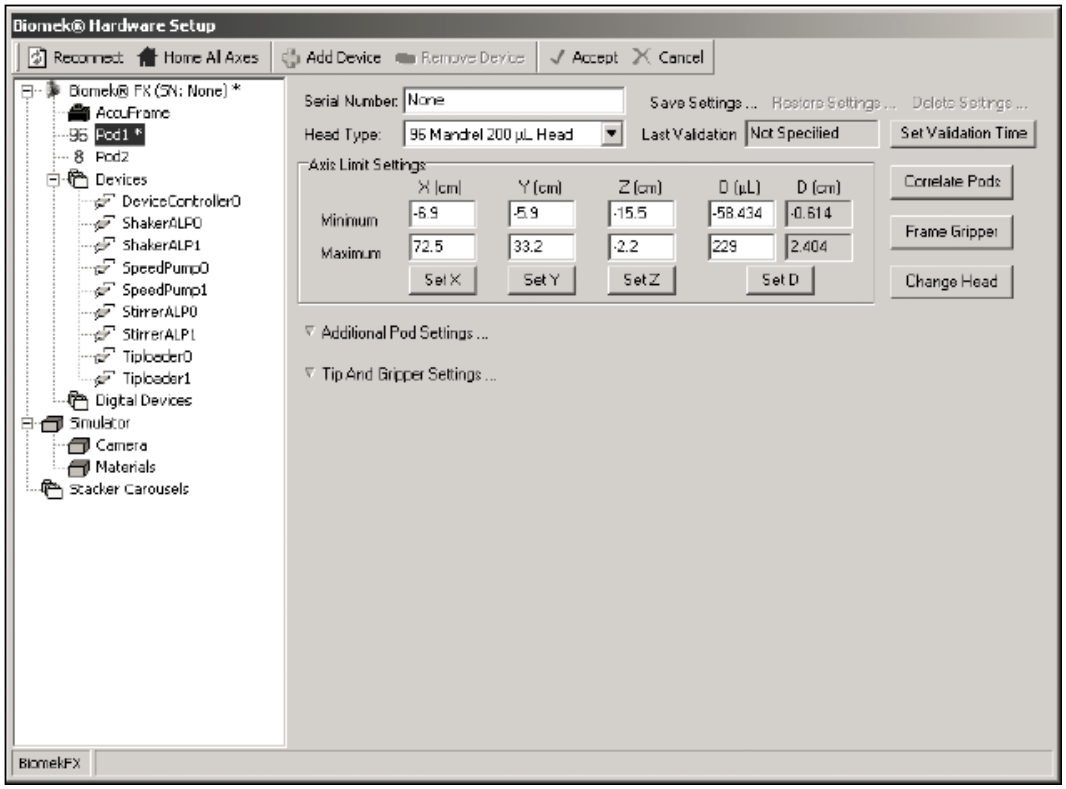
NOTE A Multichannel Pod is identified with a **96** or **384** and a Span-8 Pod is identified with an **8**.

---

2 Change the **Serial Number** to correspond to the serial number on the new head.

3 Choose the appropriate head in **Head Type** (Figure 3.4).

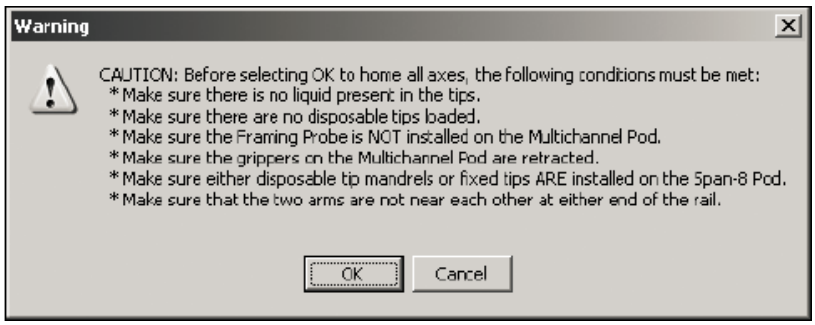
Figure 3.4 Hardware Setup Showing the Configuration View for a Multichannel Pod



4 Choose **Home All Axes**. The following **Warning** appears (Figure 3.5):

NOTE Choosing **Home All Axes** homes all of the axes for all pods.

Figure 3.5 Warnings Must Be Addressed Before Homing Process Begins



5 Choose **OK** after confirming that the **Warning** has been addressed appropriately.

NOTE Other Warnings may also appear depending upon the type of heads and deck configuration of the Biomek FX instrument. Respond to all warnings appropriately and choose **OK** to continue.

6 In **Hardware Setup**, choose **Set D** to establish a new D-axis limit.

NOTE Address any warnings that appear appropriately.

7 Choose **Set Z** to establish a new Z-axis limit.

NOTE Address any warnings that appear appropriately.

8 Frame the gripper according to the procedures outlined in CHAPTER 4, *Framing the Gripper on a Multichannel Pod*.

NOTE An asterisk next to the pod indicates that the head has been modified since the instrument configuration file was loaded.

NOTE Choose **Change Head** only when physically removing or installing a head. Choosing **Change Head** moves the D-axis to –0.6 cm and extends the gripper to remove and install a head (refer to CHAPTER 1, *Removing Heads* and CHAPTER 1, *Installing Multichannel Heads*).

Correlating the Pods

⚠ CAUTION

Do not use Correlate Pods in Hardware Setup without contacting a Beckman Coulter Representative.

To avoid collisions in a dual-pod system, the pods must be correlated. This procedure is performed during initial setup by a Beckman Coulter Representative in **Hardware Setup** and should not be repeated.

Setting Multichannel Pod Properties

Most of the properties, including pod settings and axes limits, of a Multichannel Pod are initially configured by a Beckman Coulter Representative in **Hardware Setup** and should not be modified without specific instructions from a Beckman Coulter Representative. New D- and Z-axis limits must be established, however, when switching between the HDR Tool Body and a Multichannel head.

⚠ CAUTION

Do not make any changes to the pod axes limits without contacting a Beckman Coulter Representative.

Table 3.2 describes the pod properties and axes limits listed in **Hardware Setup** for a Multichannel Pod.

NOTE Some of the fields listed in the following table (see Table 3.2) may be accessed by choosing **Additional Pod Settings** and **Tip and Gripper Settings** in **Hardware Setup** (Figure 3.4). Tip settings are not applicable to the HDR Tool Body.

Table 3.2 Multichannel Pod Properties

Property	Description
Additional Roving Height	Margin above the default height for the pod as it moves over everything on the deck.
Additional Timeout	Specifies a number of seconds to wait in addition to the normal time it takes to carry out a step before a timeout error occurs. Use when experiencing timeout problems without actual hardware problems.
Always move to max Z when roving	Check this field to move the pod to its maximum height during any move in the X- or Y-axis.
Enable Plate Sensor	Enables the plate sensor on the gripper to sense labware. Default setting is not checked. Refer to *Using the Plate Sensor*.
Final D Position (under Tip Load Settings)	Position the pod returns to along the D-axis after loading tips.
Final D Position (under Tip Unload Settings)	Position the pod returns to along the D-axis after unloading tips.
Gripper Extend Time	Specifies the time the pod takes to extend grippers.
Gripper Retract Time	Specifies the time the pod takes to retract grippers.
Gripper X, Y, Z, D Offsets	Controls gripping operation along X-, Y-, Z-, and D-axes from center of back edge of deck position. These offsets are automatically updated when the gripper is framed. **NOTE** Gripper X offset is read-only.
Last Validation	Set by a Beckman Coulter Representative, using the **Set Validation** button.
Maximum X, Y, Z, D	The maximum position the pod may move to along the X-, Y-, Z-, and D-axes (relative to the Home position). Set by using the appropriate buttons under the X (cm), Y (cm), Z (cm), and D (µL) columns. The D-axis must be established when a head is changed, but do not change the other axes limits without contacting a Beckman Coulter Representative.
Minimum X,Y, Z, D	The minimum position the pod may move to along the X-, Y-, Z-, and D-axes (relative to the Home position). Set by using the appropriate buttons under the X (cm), Y (cm), Z (cm), and D (µL) columns. The D-axis must be established when a head is changed, but do not change the other axes limits without contacting a Beckman Coulter Representative.

Table 3.2 Multichannel Pod Properties

Property	Description
Speed Limit	Controls the speed for pod movement based on a percent of its maximum speed.
Tip Settle Time	Specifies the time required for tips to settle on the mandrels after loading.
Tip Unload Time	Specifies the amount of time the pod takes to unload tips.
Unload Speed	Controls the pod speed when unloading tips, based on a percentage of the maximum pod speed. Recommended that this be modified only by a Beckman Coulter Representative.

Using the Plate Sensor

The plate sensor on the gripper is available on newer Biomek FX instruments.

To enable the plate sensor, the Multichannel Pod must have:

- Master Controller firmware version 2.62
- ZD Board version 0.11.0 or later

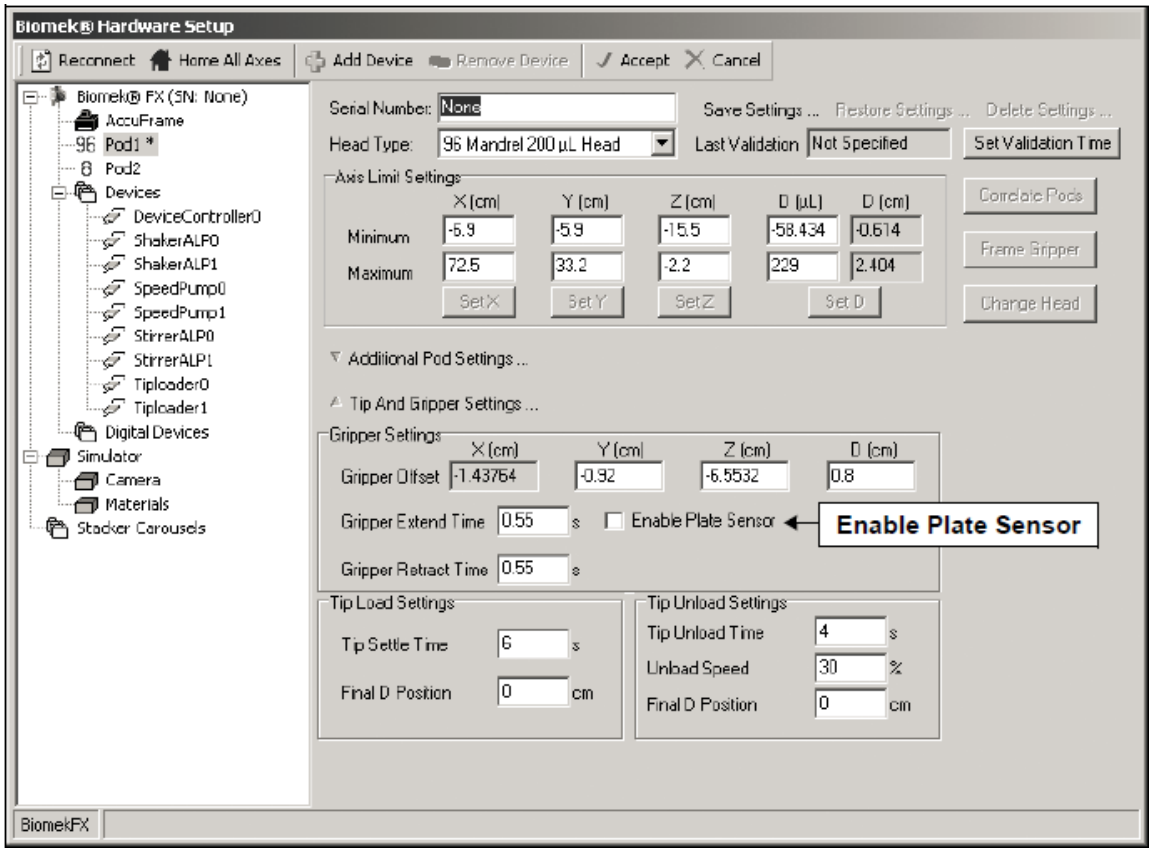
  NOTE To verify the Master Controller and ZD Board versions, refer to CHAPTER 5, *Viewing the Firmware Version*.

- Biomek Software version 3.0 or later

  NOTE To verify the software version, choose **Help** > **About** from Biomek Software.

When the gripper has a plate sensor and **Enable Plate Sensor** (Figure 3.6) is checked in **Hardware Setup** and for the specific labware in the **Labware Type Editor**, labware can be sensed when the gripper is squeezed.

Figure 3.6 Hardware Setup Displaying Enable Plate Sensor



1. Enable Plate Sensor

An error message appears if labware is not sensed when the gripper is squeezed (Figure 3.7). Refer to the *Biomek Software User's Manual* (PN 987835), *Handling and Preventing Errors*, for information on recovering from errors.

NOTE By default, **Enable Plate Sensor** is not checked.

Figure 3.7 Error for No Plate Sensed

Configuring a Span-8 Pod

Configuring a Span-8 Pod in **Hardware Setup** includes:

- *Configuring the Probes for Fixed or Disposable Tips*
- *Configuring a Speed Pump*
- *Correlating the Pods*

  NOTE Correlating the pods should be performed only by a Beckman Coulter Representative at initial setup.

- *Correlating the Z Axes*

  NOTE Correlating the Z axes should be performed only by a Beckman Coulter Representative at initial setup.

- *Performing Find LLS Sensitivities*
- *Performing Clot Detection Sensitivities (available only with a Biomek FXP Instrument)*

  NOTE Clot detection is only available with a Biomek FX^{P} instrument.

- *Setting Span-8 Pod Properties*, as instructed by a Beckman Coulter Representative.
- *Enabling Purge Settings*, by a Beckman Coulter Representative.

NOTE The settings for a Multichannel Pod can be saved, restored, and deleted (refer to *Saving, Restoring, and Deleting Settings*.

Configuring the Probes for Fixed or Disposable Tips

The probes on the Span-8 Pod may be configured for fixed or disposable tips. This configuration must be accomplished in **Hardware Setup**.

The probes on the Span-8 Pod must be configured when:

- Changing from disposable tips to fixed tips.
- Changing from fixed tips to disposable tips.
- Changing the type of fixed tips.

When probe configuration is changed from disposable to fixed tips or from fixed to disposable tips, the pod must be homed (refer to CHAPTER 5, *Homing All Axes of the Pod or Pods*) and **Find Sensitivities** must be performed (refer to *Performing Find LLS Sensitivities*).

NOTE The pod may be homed by choosing **Home All Axes** from **Hardware Setup**.

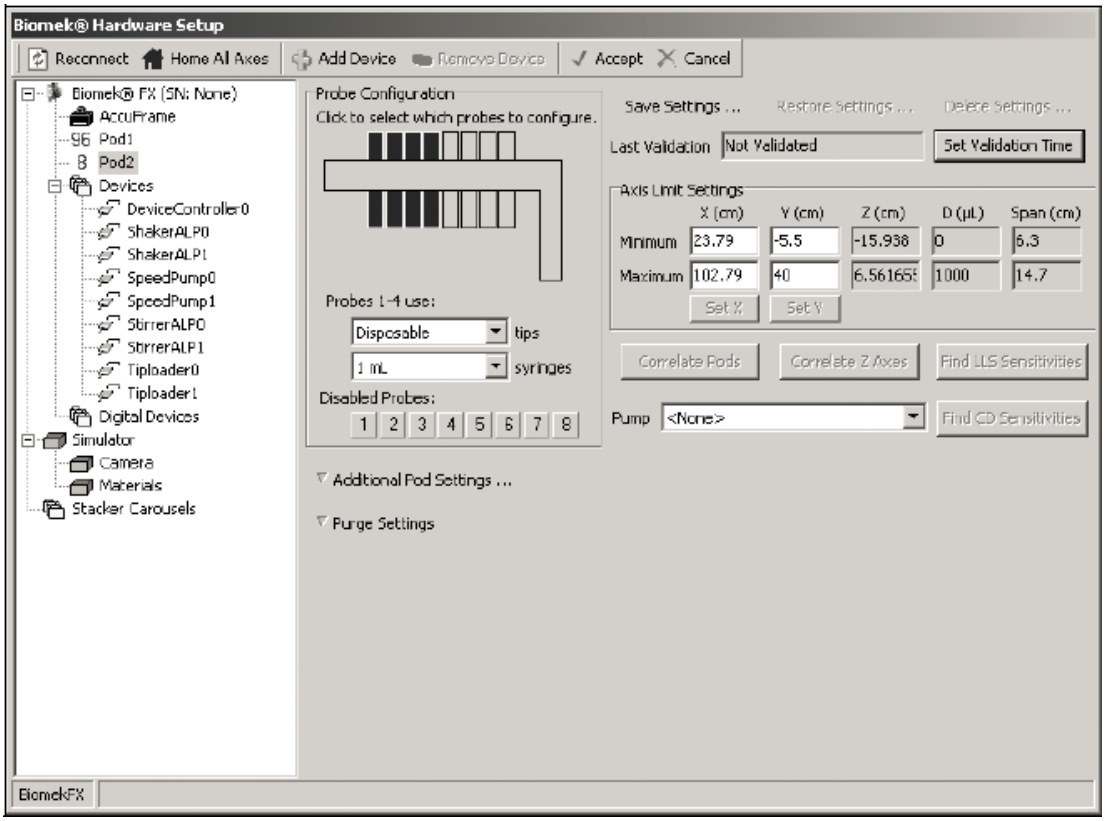
NOTE The Span-8 Pod is capable of accessing all types of labware supported by the Biomek FX instrument; however, specific types of tips are recommended to access specific types of labware (refer to CHAPTER 2, *Labware and Tip Compatibility with the Span-8 Pod*).

To configure probes:

1 In **Hardware Setup**, select the appropriate Span-8 **Pod** from the left pane to access the configuration area in the right pane (Figure 3.8).

NOTE A Multichannel Pod is identified with a **96** or **384** and a Span-8 Pod is identified with an **8**.

Figure 3.8 Hardware Setup Showing the Configuration View for a Span-8 Pod



2 To choose the probe type, click on the desired probes to configure from the graphical representation of the probes.

NOTE The graphical representation of the probes changes according to the type: disposable or fixed.

3 From the drop-down menu, choose the tips in **Probes 1- 4 use. . . tips**.

NOTE To choose probes 1 through 8 at one time, hold down (Ctrl) with probes 1 through 4 highlighted and then click on probes 5 though 8.

NOTE Probes 1 through 4 may be configured with one type of fixed tips or disposable tips and probes 5 through 8 may be configured with another type of fixed tips or disposable tips. To mix the type of tips, select probes 1 through 4 and choose the tip type. Then select probes 5 through 8 and choose the tip type.

NOTE When tips are changed from disposable to fixed or from fixed to disposable, a **Warning** (Figure 3.9) appears on **Hardware Setup** that the pod must be homed and **Find Sensitivities** performed. When **Accept** is chosen, another device is configured in **Hardware Setup**, or a dialog is chosen from Tools, another **Warning** (Figure 3.10) appears that the pod must be homed and **Find Sensitivities** performed.

Figure 3.9 Warning on **Hardware Setup** that Pod Must Be Homed and **Find Sensitivities** Performed When Tip Types are Changed

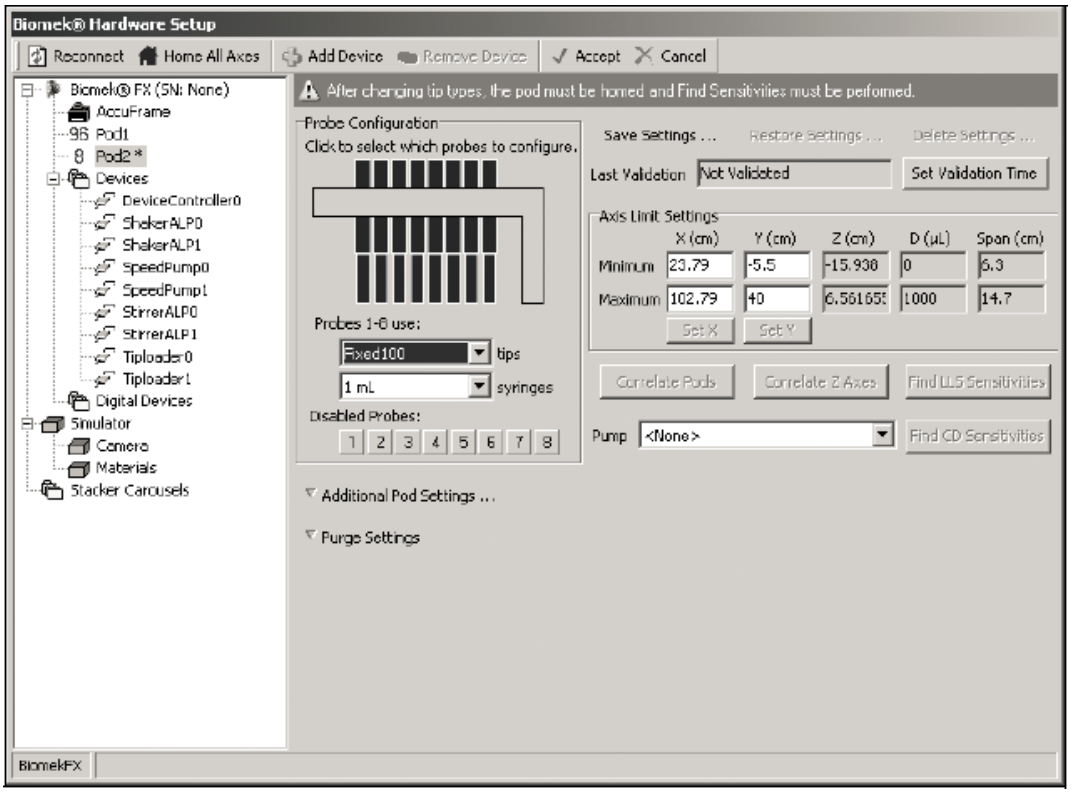


Figure 3.10 Warning That Pod Must Be Homed and Find Sensitivities Performed When Tip Types Are Changed

4 To choose the syringe type, click on the desired probes to configure from the graphical representation of the probes.

5 From the drop-down menu, choose the syringes in **Probes 1 - 4 use. . . syringes.**

NOTE To choose probes 1 through 8 at one time, hold down Ctrl with probes 1 through 4 highlighted and then click on probes 5 though 8.

NOTE Probes 1 through 4 may be configured with one size of syringe and probes 5 through 8 may be configured with another size of syringe. To mix the size of syringes, select probes 1 through 4 and choose the syringe size. Then select probes 5 through 8 and choose the syringe size.

6 In **Disabled Probes**, choose any probes that should not be used.

7 Choose **Accept. Hardware Setup** closes.

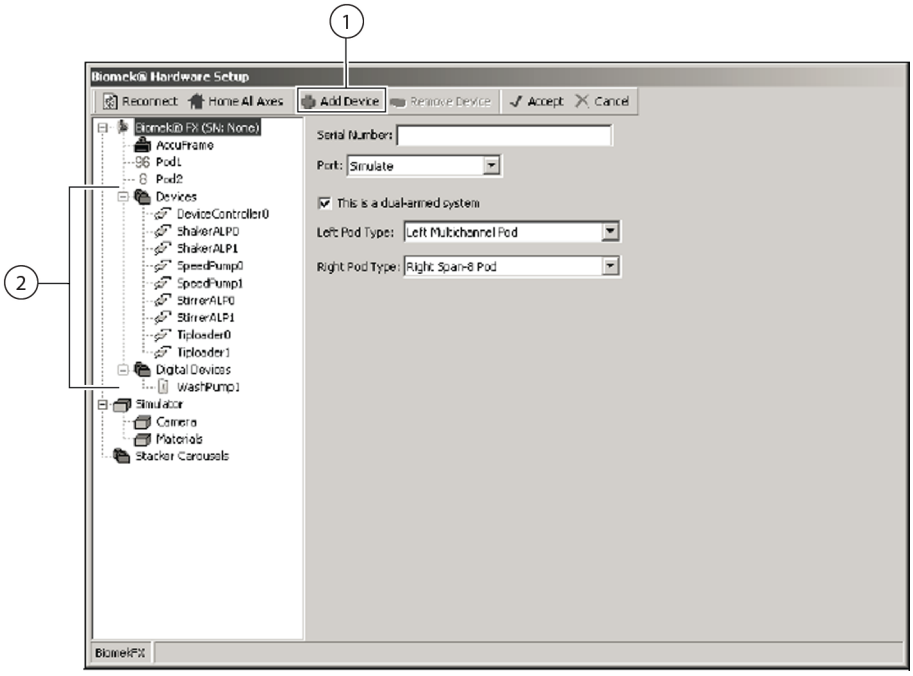
Configuring a Speed Pump

After a Speed Pump has been physically added to the Biomek FX instrument, it must be added to the system configuration (refer to CHAPTER 2, *Speed Pump*). A Speed Pump is added to the system configuration through Hardware Setup.

To add a Speed Pump to the system configuration:

1 Choose **Instrument > Hardware Setup**. **Hardware Setup** appears (Figure 3.11).

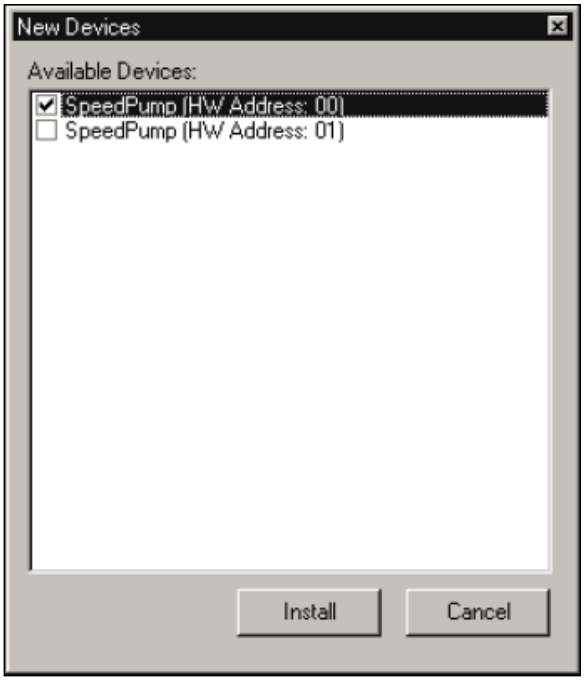
Figure 3.11 Hardware Setup



1. Add Device: Use **Add Device** to open **New Devices**.
2. List of Devices

2 Select Add Device. New Devices appears (Figure 3.12).

Figure 3.12 New Devices

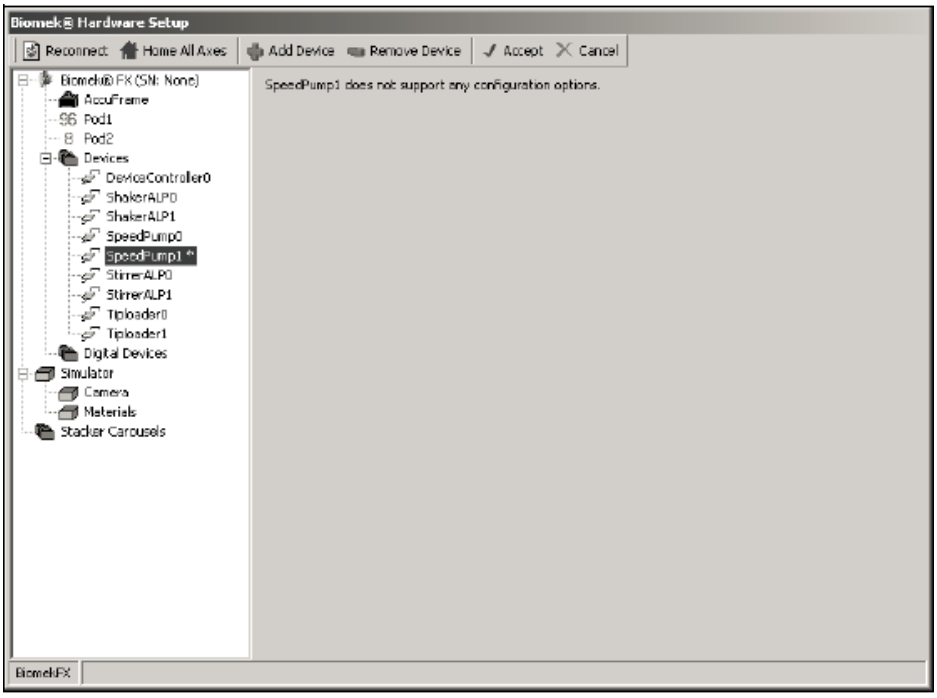


3 Select **SpeedPump (HW Address: 00)** for the first Speed Pump added to the Biomek FX instrument. Select **SpeedPump** (**HW Address: 01**) for the second Speed Pump added to the instrument and **SpeedPump (HW Address: 02)** for the third.

NOTE Only three Speed Pumps can be added to the Biomek FX instrument at one time.

4 In **New Devices**, choose **Install** to add the new Speed Pump to the **Hardware Setup** and close **New Devices**. A Speed Pump has been added to the **Hardware Setup** (Figure 3.13).

Figure 3.13 A Speed Pump Has Been Added to the Hardware Setup



OR

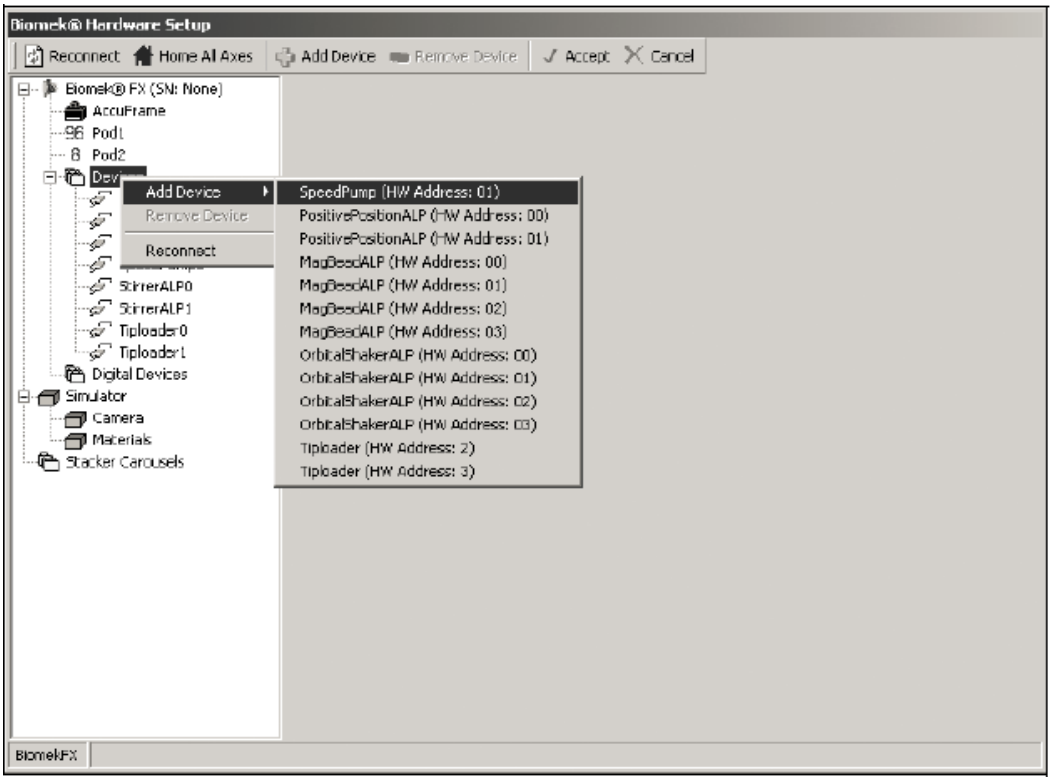
a. From **Hardware Setup**, right-click on **Devices** (Figure 3.14).

b. Select **Add Device**. A **Speed Pump** has been added to the **Hardware Setup**.

c. Select **SpeedPump (HW Address: 00)** for the first Speed Pump added to the Biomek FX instrument. Select **SpeedPump (HW Address: 01)** for the second Speed Pump added to the instrument and **SpeedPump (HW Address: 02)** for the third.

NOTE Only three Speed Pumps can be added to the Biomek FX instrument at one time.

Figure 3.14 Right Clicking on Deices to Add a Speed Pump In Hardware Setup

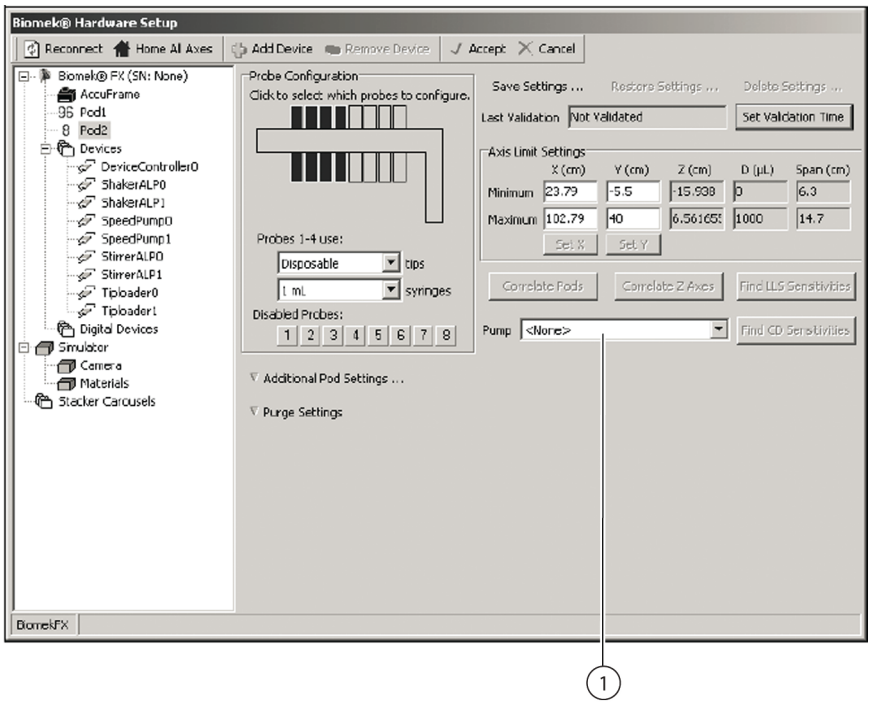


5 Select the Span-8 **Pod** in the system hierarchy displayed in the left pane of the **Hardware Setup** (Figure 3.15). The Span-8 Pod configuration appears in the right pane.

6 Select a **Pump** for the pod in the pod configuration options displayed (Figure 3.15).

NOTE A Speed Pump propels system fluid through every probe on the Span-8 Pod, not selected or individual probes.

Figure 3.15 Selecting a Speed Pump for a Span-8 Pod



1. Select a Speed Pump for the Span-8 Pod here.

7 Choose **Accept**. **Hardware Setup** closes. The Speed Pump is configured for use.

NOTE The operation of the Speed Pump is controlled through **Manual Control** prior to running a method (refer to CHAPTER 5, *Using Advanced Manual Control to Manually Control Speed Pumps*), or through a **Device Action** step during a method run (refer to the *Biomek Software User's Manual* (PN 987835), *Device Action Step*), or by selecting the Speed Pump option in a **Transfer** step using a Span-8 Pod.

Correlating the Pods

⚠ CAUTION

Do not use Correlate Pods in Hardware Setup without contacting a Beckman Coulter Representative.

To avoid collisions in a dual-pod system, the pods must be correlated. This procedure is performed during initial setup by a Beckman Coulter Representative in **Hardware Setup** and should not be repeated.

Correlating the Z Axes

⚠ CAUTION

Do not use Correlate Z Axes in Hardware Setup without contacting a Beckman Coulter Representative.

To eliminate mechanical variances, the Z axes on the probes must be correlated. This procedure is performed during initial setup by a Beckman Coulter Representative in **Hardware Setup** and should not be repeated.

Performing Find LLS Sensitivities

Performing **Find LLS Sensitivities** is necessary to test each probe on an individual system to ensure the liquid level sensing capability operates properly. This procedure adjusts the system to the individual liquid level sensitivity settings on each probe.

Although **Find LLS Sensitivities** is performed during initial setup by a Beckman Coulter Representative, the procedure must be repeated when:

- Changing from disposable to fixed tips.
- Changing from fixed to disposable tips.
- Difficulties, such as false trips or failed senses, are experienced using liquid level sensing.

To perform **Find LLS Sensitivities**:

---

1 In **Hardware Setup**, select the appropriate Span-8 **Pod** from the left pane to access the configuration area in the right pane (Figure 3.14).

NOTE A Multichannel Pod is identified with a 96 or 384 and a Span-8 Pod is identified with an 8.

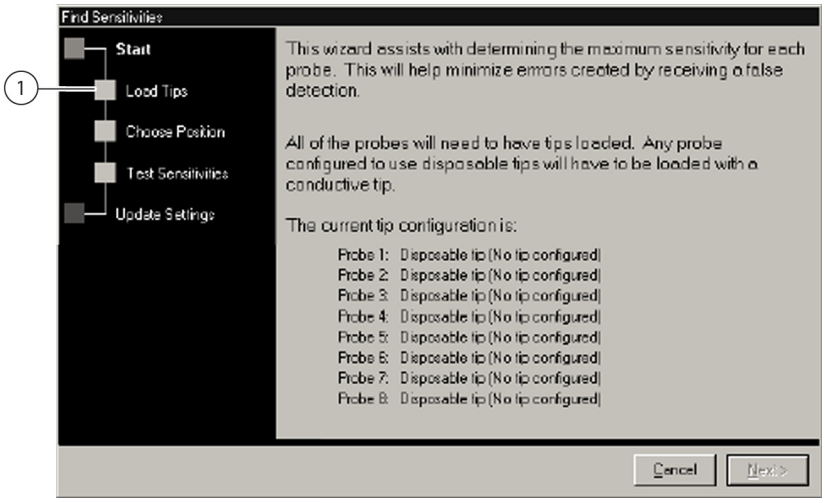
---

2 Choose **Find LLS Sensitivities**. **Find Sensitivities** opens with **Start** (Figure 3.16). After a few seconds, the tips are detected and (Figure 3.17) appears.

NOTE On the left side of Find Sensitivities, a list of steps required to complete the procedure is displayed. As the steps of Find Sensitivities are accessed, they are highlighted on the left.

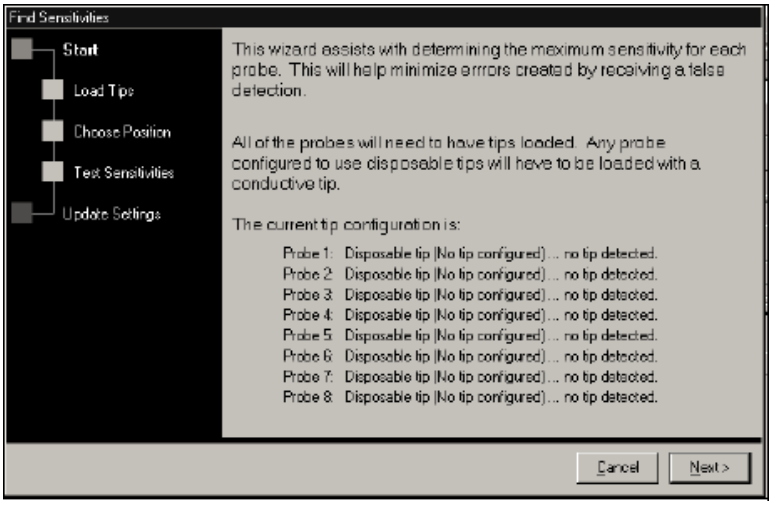
NOTE A Span-8 Pod that is configured with all fixed tips will not display **Load Tips** on the left side of **Find Sensitivities**.

Figure 3.16 Find Sensitivities (Start)



1. **Load Tips** will not be displayed here if all probes are configured with fixed tips.

Figure 3.17 Find Sensitivities (Start) Tip Detection



---

3 Choose **Next. Find Sensitivities (Load Tips)** appears (Figure 3.18).

NOTE If tips are detected that were not configured in **Hardware Setup** or if there are probes that must be calibrated, F**ind Sensitivities (Tip Configuration)** appears (Figure 3.19). (Refer to *Configuring the Probes for Fixed or Disposable Tips*, to correctly configure the probes in **Hardware Setup**.) If probes are not calibrated, configure the disposable tip in **Find Sensitivities (Tip Calibration)** to match the tip that is currently attached to the probe (Figure 3.19). Choose **Next** to proceed through the wizard.

Figure 3.18 Find Sensitivities (Load Tips)

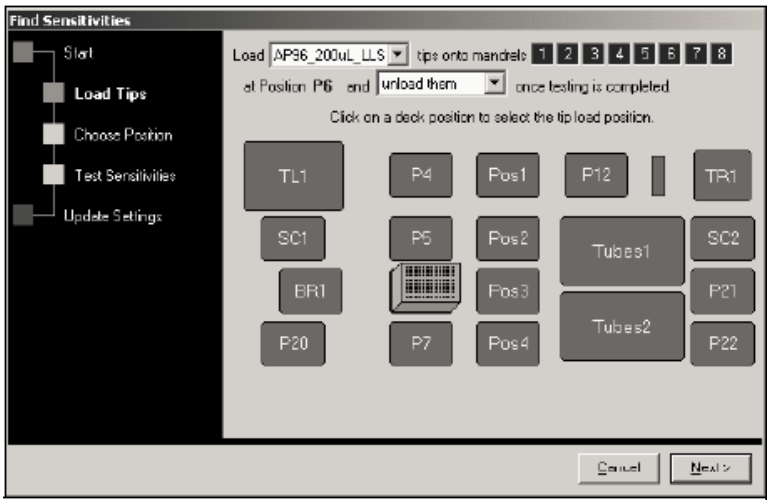
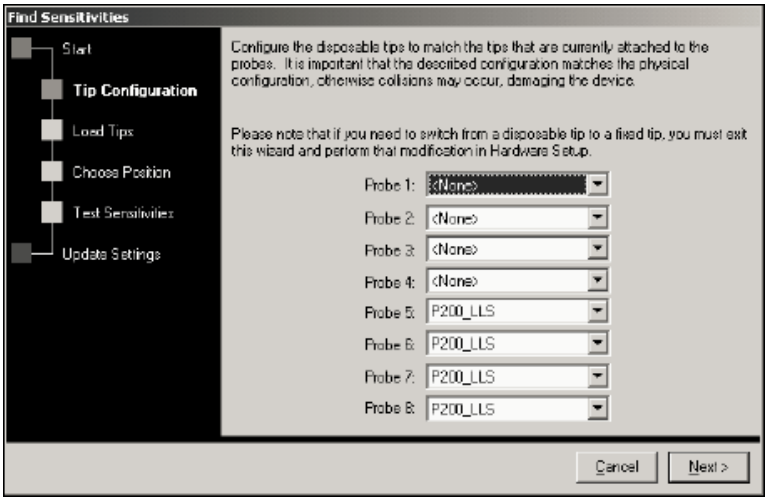


Figure 3.19 Find Sensitivities (Tip Configuration)



NOTE If all probes are configured with fixed tips, **Find Sensitivities (Choose Position)** appears rather than **Find Sensitivities (Load Tips)**. Go immediately to step 9.

4 In **Load**, choose the appropriate tip type.

NOTE Any probe configured to use disposable tips must be loaded with a conductive tip.

5 In **mandrels**, choose the desired probes.

6 Click on the position where tips should be loaded.

7 Choose **unload them** to unload tips when **Find Sensitivities** is completed.

OR

leave them on to leave tips on when **Find Sensitivities** is completed.

8 Choose **Next**. Tips are loaded. **Find Sensitivities (Choose Position)** appears (Figure 3.21).

NOTE If any tips fail to load, follow the recovery instructions displayed on **Find Sensitivities (Load Tips)** (Figure 3.20).

Figure 3.20 Find Sensitivities Load Tips Error

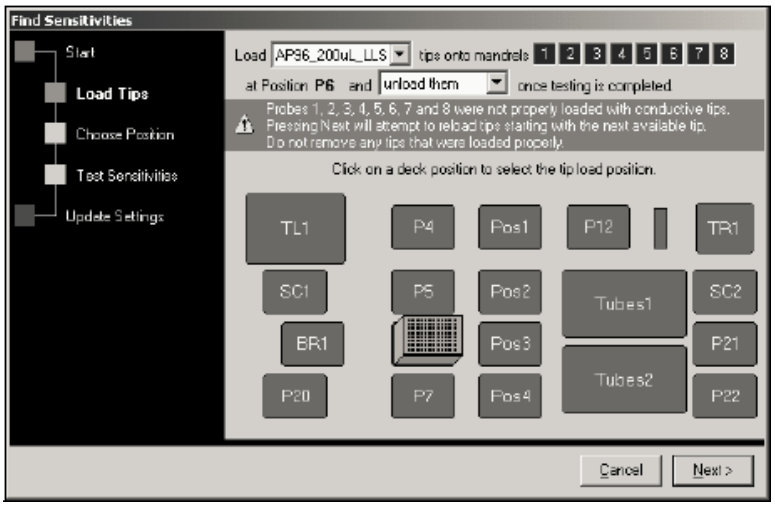
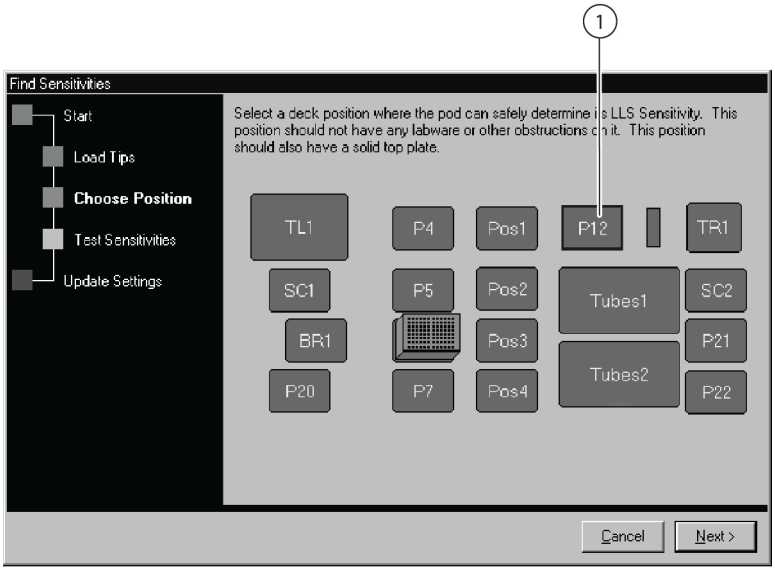


Figure 3.21 Find Sensitivities (Choose Position)



1. P12 has been selected where the pod can determine its LLS sensitivity.

9 Select a deck position by clicking on the position.

NOTE The deck position must be an ALP with a solid ground plane; for example, a 1x3 or 1x5 Passive ALP, or a 4x4 High-Density Passive ALP. If using a 1x1 Passive ALP, it must have an LLS plate installed.

10 Choose **Next**. **Find Sensitivities (Test Sensitivities)** appears (Figure 3.22). A few seconds later, Figure 3.22 appears indicating testing is in progress.

Figure 3.22 Find Sensitivities (Test Sensitivity)

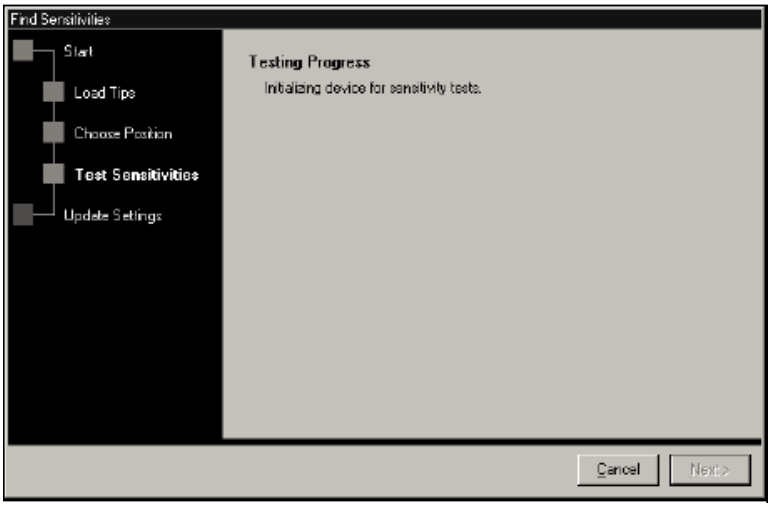
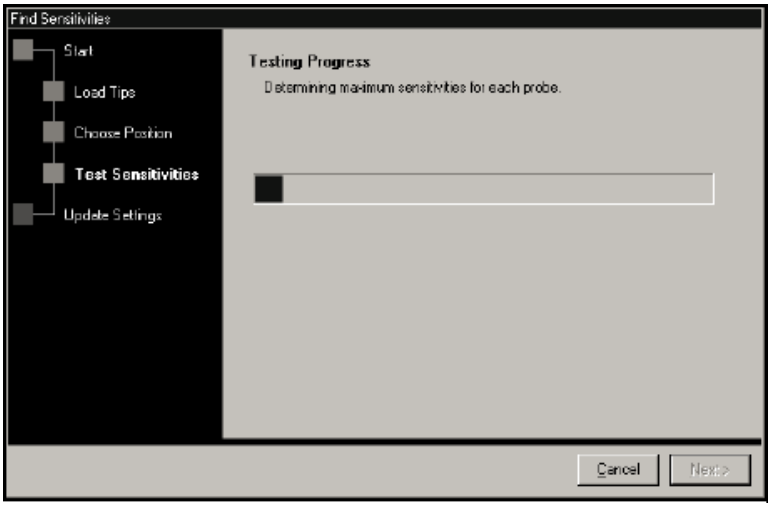


Figure 3.23 Find Sensitivities (Test Sensitivities) Indicating Testing Progress



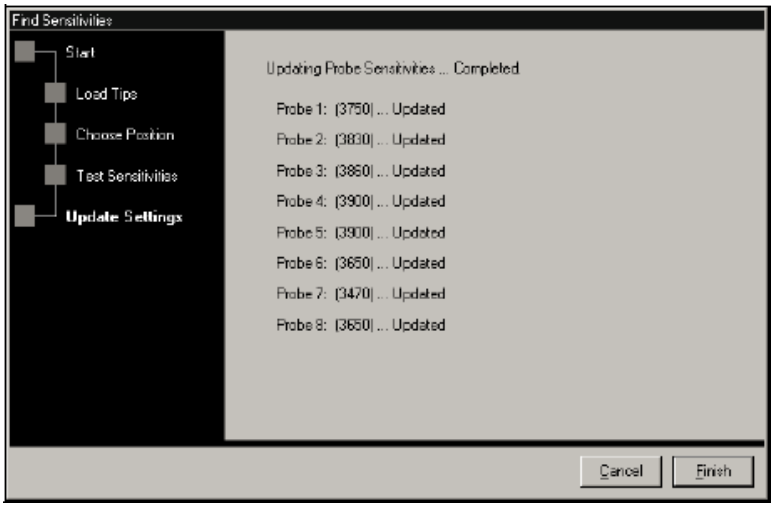
⚠ CAUTION

Do not choose Cancel; if testing is stopped before the probe sensitivities have been completed, liquid level sensing will not function and Find Sensitivities must be repeated.

NOTE It takes several minutes to complete the testing. When testing is completed, choose **Next**. **Find Sensitivities (Update Settings)** appears indicating the probe sensitivities have been completed (Figure 3.24).

NOTE If tips have been configured to unload, they will unload now.

Figure 3.24 Find Sensitivities (Update Settings)



11 Choose **Finish**. **Find Sensitivities** closes.

12 Choose **Accept**. **Hardware Setup** closes.

Performing Clot Detection Sensitivities (available only with a Biomek FX^P Instrument)

Performing **Find Clot Detection Sensitivities** is necessary to test each probe on an individual system to ensure the clot detection sensing capability is calibrated. This procedure adjusts the system to the individual clot detection sensitivity settings on each probe.

Although **Find Clot Detection Sensitivities** is performed during initial setup by a Beckman Coulter Representative, the procedure must be repeated when:

- Changing from disposable to fixed tips.
- Changing from fixed to disposable tips.

- Difficulties, such as false trips or failed senses, are experienced using clot detection.

To perform **Find CD Sensitivities**:

---

1 In Hardware Setup, select the Span-8 Pod from the left pane to access the configuration area in the right pane.

---

2 Choose **Find CD Sensitivities**. **Find Clot Detection Sensitivities** opens with **Start** (Figure 3.25). After a few seconds, the tips are detected and Figure 3.26 appears.

Figure 3.25 Hardware Setup Find CD Sensitivities Button

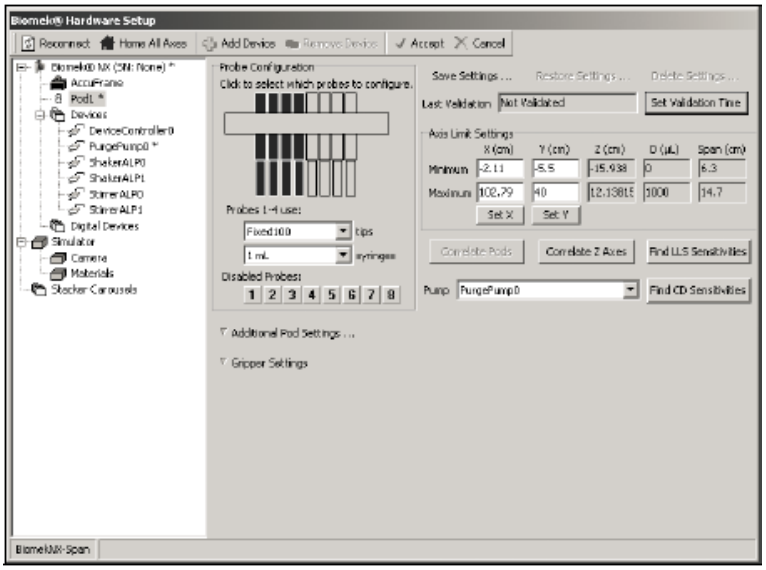
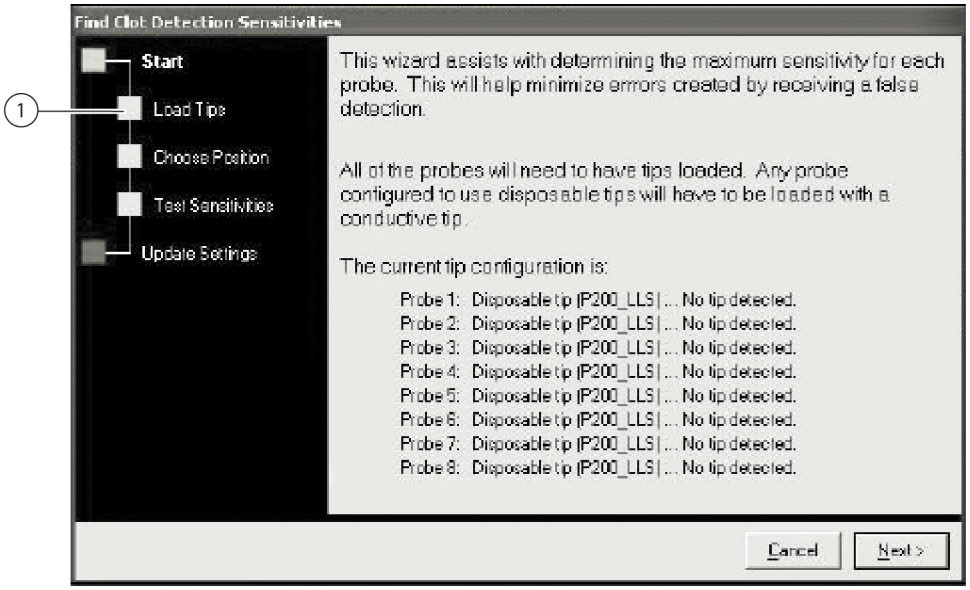


Figure 3.26 Find Clot Detection Sensitivities (Start)



1. **Load Tips** will not be displayed here if all probes are configured with fixed tips.

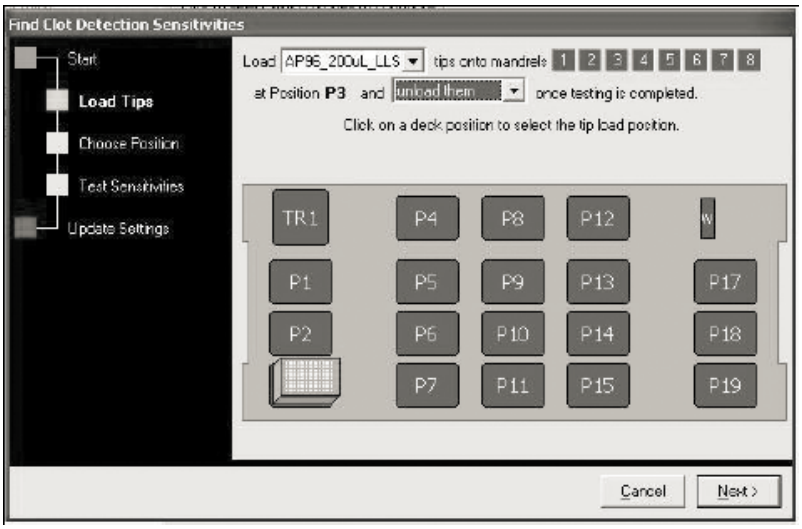
NOTE On the left side of F**ind Clot Detection Sensitivities**, a list of steps required to complete the procedure is displayed. As the steps of **Find CD Sensitivities** are accessed, they are highlighted on the left.

NOTE A Span-8 Pod that is configured with all fixed tips will not display **Load Tips** on the left side of **Find Clot Detection Sensitivities**.

---

3 Choose **Next. Find Clot Detection Sensitivities (Load Tips)** appears (Figure 3.27).

Figure 3.27 Find Clot Detection Sensitivities (Load Tips)



NOTE If all probes are configured with fixed tips, **Find Clot Detection Sensitivities (Choose Position)** appears rather than **Find Clot Detection Sensitivities (Load Tips)**. Go immediately to step 9.

4 In **Load**, choose the appropriate tip type.

NOTE Any probe configured to use disposable tips must be loaded with a conductive tip.

5 In **mandrels**, choose the desired probes.

6 Click on the position where tips should be loaded.

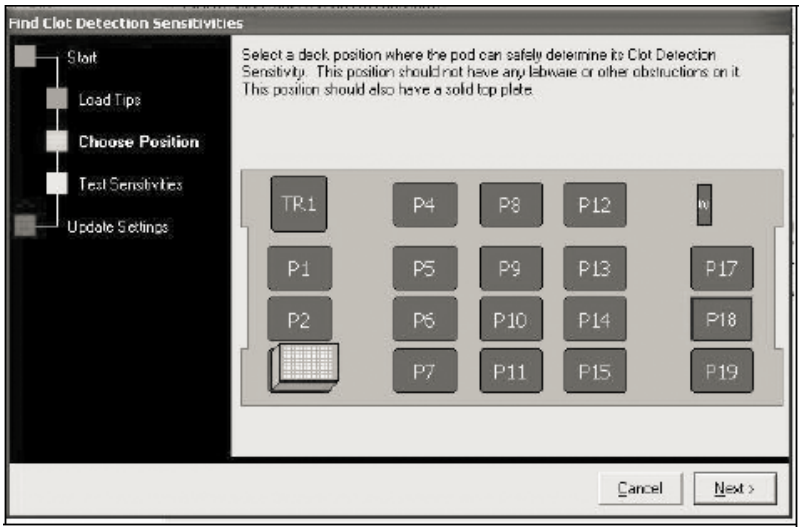
7 Choose **unload them** to unload tips when **Find Clot Detection Sensitivities** is completed.

OR

Choose **leave them on** to leave tips on when F**ind Clot Detection Sensitivities** is completed.

8 Choose **Next**. Tips are loaded. **Find Clot Detection Sensitivities (Choose Position)** appears (Figure 3.28).

Figure 3.28 Find Clot Detection Sensitivities (Choose Position)



NOTE If any tips fail to load, follow the recovery instructions displayed on **Find Sensitivities (Load Tips)** (Figure 3.20).

9 Select a deck position by clicking on the position.

NOTE The deck position must be an ALP with a solid ground plane; for example, a 1x3 Passive ALP. If using a 1x1 Passive ALP or High Density 4x3 Passive ALP, the deck position must have an LLS plate installed.

10 Choose **Next. Find Clot Detection Sensitivities (Test Sensitivities)** appears (Figure 3.29). A few seconds later, testing begins with a dialog box that tracks the test progress (Figure 3.30).

Figure 3.29 Find Clot Detection Sensitivities (Test Sensitivities)

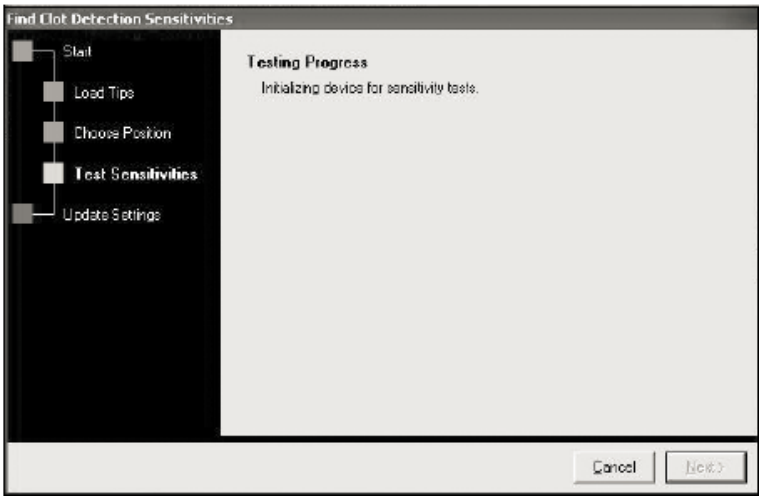
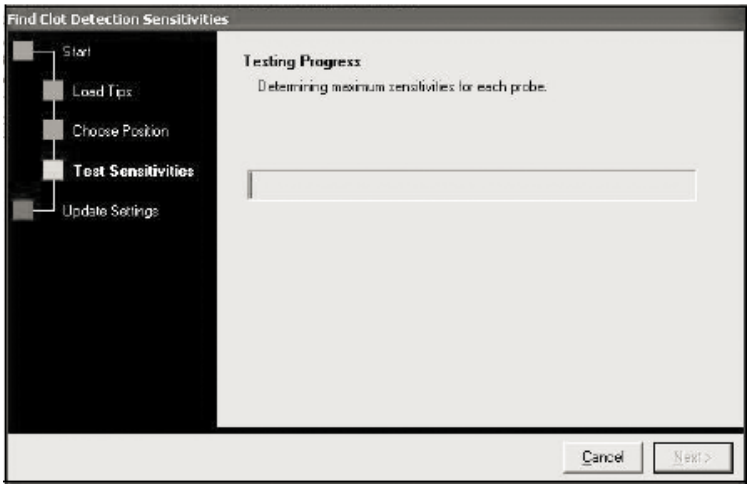


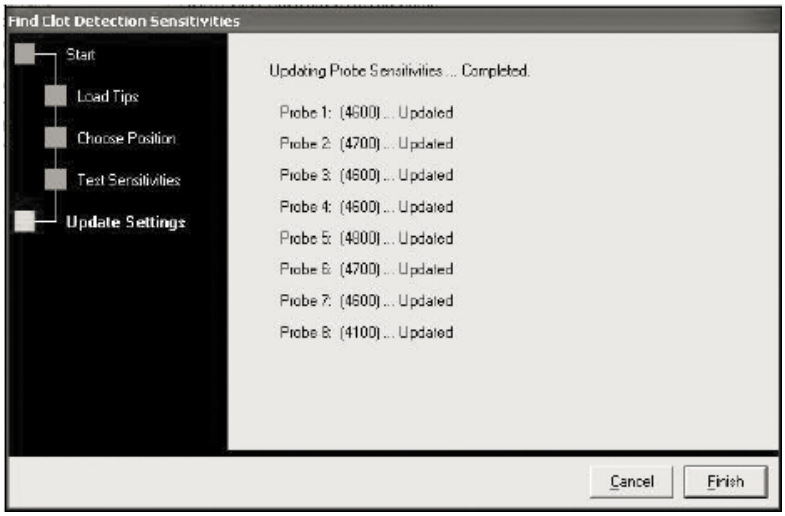
Figure 3.30 Find Clot Detection Sensitivities (Test Sensitivities) Testing Progress



IMPORTANT Do not choose **Cancel**; if testing is stopped before the probe sensitivities have been completed, clot detection will not function and **Find Clot Detection Sensitivities** must be repeated. It takes nearly 30 minutes to complete the testing.

11 When testing is completed, choose **Next. Find Clot Detection Sensitivities (Update Settings)** appears indicating the probe sensitivities have been completed (Figure 3.31).

Figure 3.31 Find Clot Detection Sensitivities (Update Setting)



NOTE If tips have been configured to unload, they will unload now.

12 Choose **Finish. Find Clot Detection Sensitivities** closes.

13 Choose **Accept. Hardware Setup** closes.

Setting Span-8 Pod Properties

Most of the properties, which include the settings and axes limits, of a Span-8 Pod are initially configured by a Beckman Coulter Representative in **Hardware Setup** and should not be modified without specific instructions from a Beckman Coulter Representative.

However, pod properties should be adjusted when physical changes have been made to the Biomek FX instrument. Always consult a Beckman Coulter Representative before changing values.

⚠ CAUTION

Do not make any changes to the axes limits and pod settings without consulting a Beckman Coulter Representative.

Table 3.3 describes the pod properties and axes limits listed in **Hardware Setup** for a Span-8 Pod.

NOTE Some of the fields listed in the following table (see Table 3.3) may be accessed by choosing **Additional Pod Settings** in **Hardware Setup**.

Table 3.3 Span-8 Pod Properties

Property	Description
Additional Roving Height	Margin above the default height for the pod as it moves over everything on the deck.
Additional Timeout	Specifies the number of seconds to wait in addition to the normal time it takes to carry out a step before a timeout error occurs. Use when experiencing timeout problems without actual hardware problems.
Always Move to Z-max when roving	Check this field to move the pod to its maximum height during any move in the X- or Y-axis.
Last Validation	Set by a Beckman Coulter Representative.
Maximum X, Y, Z, D, and Span (S)	The maximum position the pod may go to along the X-, Y-, Z-, D-, and Span (S-) axes (relative to the Home position). Set by using the appropriate buttons under the X (cm) and Y (cm) columns. Do not change the axes limits without contacting a Beckman Coulter Representative.
Minimum X, Y, Z, D, and Span (S)	The minimum position the pod may go to along the X-, Y-, D-, and Span (S-) axes (relative to the Home position). Set by using the appropriate buttons under the X (cm) and Y (cm) columns. Do not change the axes limits without contacting a Beckman Coulter Representative.
Post-Run Wash Volume	Amount of liquid in mL run through the probes after a method is run.
Probe Size	Thickness of the probe along the Y-axis.
Speed Limit	Controls the speed for pod movement based on a percentage of its maximum speed.
System Trailing Airgap	Volume of air between the system liquid and the additional air gaps that are drawn into the tip.
Unload Speed	Controls the pod speed when unloading tips, based on a percentage of its maximum pod speed. Recommended that this be modified only by a Beckman Coulter Representative.

NOTE Pod properties for a Span-8 Pod may be saved, restored, and deleted using **Save Settings**, **Restore Settings**, and **Delete Settings** (refer to *Saving, Restoring, and Deleting Settings*). Do not change axes limits without contacting a Beckman Coulter Representative.

Enabling Purge Settings

The purge settings of a Span-8 Pod are enabled via **Re-Establish Air Gap** and initially configured by a Beckman Coulter Representative in **Hardware Setup**. These settings should not be enabled or modified without specific instructions from a Beckman Coulter Representative.

When **Re-establish Air Gap** is enabled and configured, the behavior of the Span-8 Pod is noticeably different during liquid pipetting. Depending on the **Cycle Threshold** setting, the pod moves to the Span-8 Tip Wash ALP during pipetting operations to purge liquid and air to re-establish an acceptable air gap. If using disposable tips, they will be shucked and new tips loaded.

⚠ CAUTION

Do not make any changes to the purge settings without consulting a Beckman Coulter Representative.

Table 3.4 describes the purge settings listed in **Hardware Setup** for a Span-8 Pod.

Table 3.4 Purge Settings

Property	Description
Re-establish Air Gap	When checked, allows the purge settings to be enabled and configured to allow an acceptable air gap to be re-established.
Cycle Threshold	Number of aspirate and dispense cycles before the air gap is re-established.
Post-Purge Delay	Amount of time in milliseconds the system waits after purging air and liquid to the Span-8 Tip Wash ALP.
Dispense	Amount of liquid in milliliters that is dispensed to the reservoir of the Span-8 Tip Wash ALP.
Wash	Amount of liquid in milliliters that is used to wash the tips of the Span-8 Tip Wash ALP in the eight cleaning wells.
Use speed pump	When checked, uses the speed pump to bypass the pump valves to accelerate the speed of the system fluid as it passes through the tubing and is dispensed from the tips into the Span-8 Tip Wash ALP.

Saving, Restoring, and Deleting Settings

The axes limits and pod settings may be saved, restored, and deleted using the **Save Settings**, **Restore Settings**, and **Delete Settings** options in **Hardware Setup**.

NOTE These options are particularly useful when changing heads on a Multichannel Pod. Because a new D-axis limit must be established when a head is changed, these options allow the D-axis limit to be saved and restored for specific head types. When settings are no longer needed, they may be deleted.

Saving Pod Settings

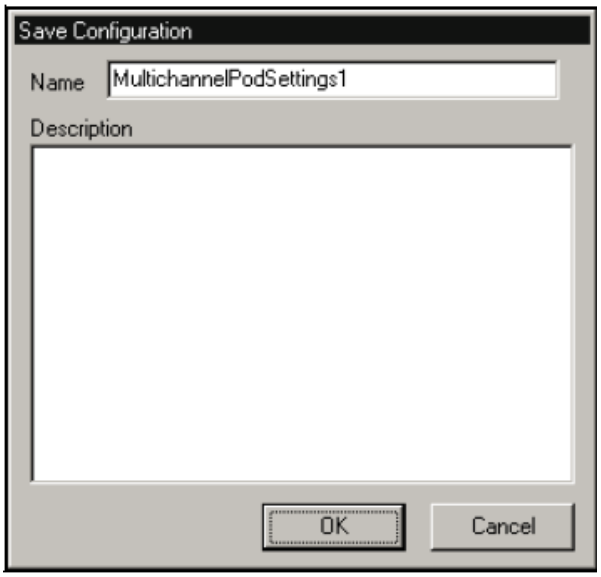
To save settings:

1. In **Hardware Setup**, select the appropriate **Pod** from the left pane to access the configuration area in the right pane.

   NOTE A Multichannel Pod is identified with a **96** or **384** and a Span-8 Pod is identified with an **8**.

2. Choose **Save Settings**. **Save Configuration** appears (Figure 3.32).

   Figure 3.32 Save Configuration



3. If desired, enter a description of the configuration.

4. Choose **OK**. The settings are saved.

Restoring Pod Settings

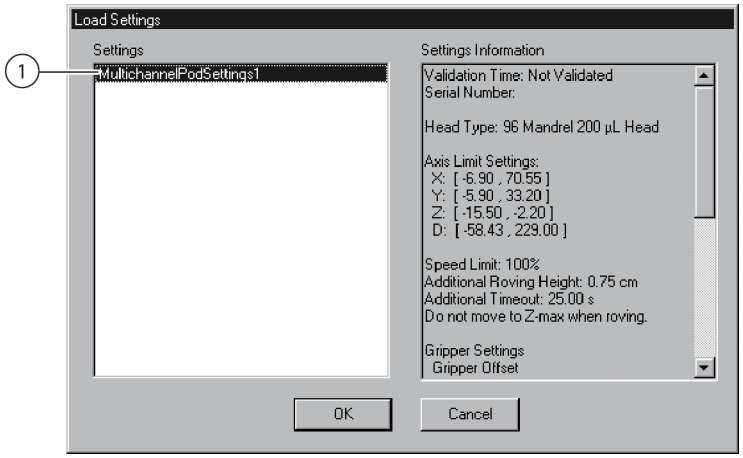
To load the saved settings:

1. In **Hardware Setup**, select the appropriate **Pod** from the left pane to access the configuration area in the right pane.

   NOTE A Multichannel Pod is identified with a **96** or **384** and a Span-8 Pod is identified with an **8**.

2 Choose **Restore Settings**. **Load Settings** appears (Figure 3.33).

Figure 3.33 Load Settings

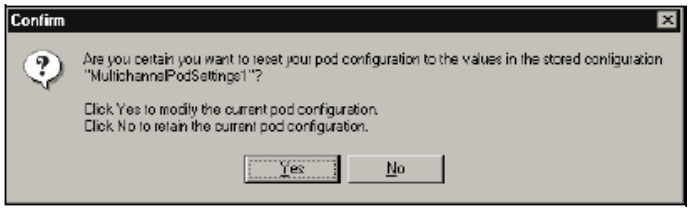


1. Desired settings to load are selected here.

3 Select the desired settings.

4 Choose **OK**. The following **Confirm** appears (Figure 3.34).

Figure 3.34 Confirmation to Reset Stored Configuration



5 Choose **Yes**. The stored configuration is reset.

Deleting Pod Settings

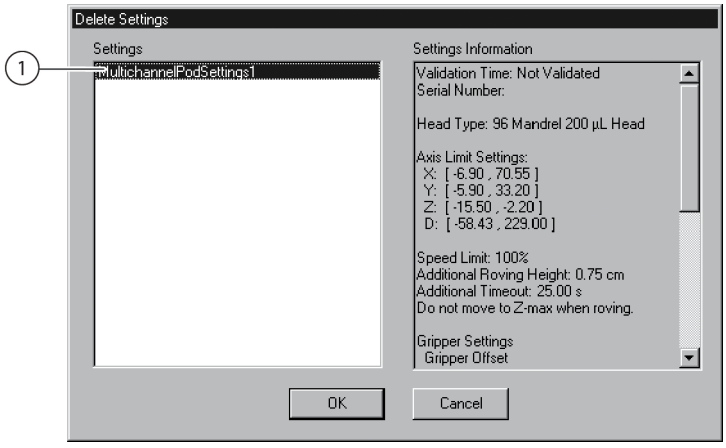
To delete settings:

1 In **Hardware Setup**, select the appropriate **Pod** from the left pane to access the configuration area in the right pane.

NOTE A Multichannel Pod is identified with a **96** or **384** and a Span-8 Pod is identified with an **8**.

2 Choose **Delete Settings**. **Delete Settings** appears (Figure 3.35).

Figure 3.35 Delete Settings

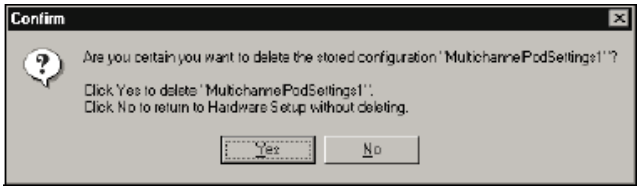


1. Select desired settings to delete here.

3 Select the desired settings to delete.

4 Choose **OK**. The following **Confirm** appears (Figure 3.36).

Figure 3.36 Confirmation to Delete Stored Configuration



5 Choose **Yes**. The stored configuration is deleted.

CHAPTER 4

Framing the Biomek FX

Overview

Framing is the procedure of teaching Biomek Software the location of the ALPs and devices positioned on the deck. Biomek Software uses this framing information to move the pod(s) to the appropriate positions to perform liquid-handling operations and manipulate labware.

A Beckman Coulter Representative frames the Biomek FX instrument during system installation. It may be necessary to repeat the framing if:

- ALPs or devices are added, moved, or removed from the deck.
- the head on the Multichannel Pod is changed.
- the probes on the Span-8 Pod are changed.

Framing deck positions can be performed automatically using the AccuFrame framing tool, or manually using a piece of labware to visually align the pod to the wells. The gripper on the Multichannel Pod may also be framed manually using the AccuFrame framing tool.

Framing the Biomek FX instrument includes:

- *Framing Deck Positions on the Biomek FX Using AccuFrame*
- *Manually Framing Deck Positions on the Biomek FX*
- *Framing the Gripper on a Multichannel Pod*

Precision When Teaching Two Pods

After framing with a pod, Pod 1 for example, Pod 2 **Coordinates** change to match those of Pod 1. The **Precision** field for Pod 2, however, still displays **Not Framed** until Pod 2 is actually framed for that position. When precision is critical, as when using 384-well plates, each position accessed must be framed by both pods.

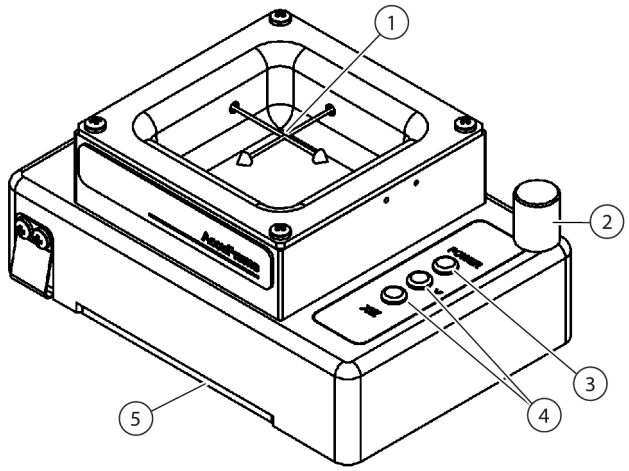
NOTE If Pod 2 in the example above is framed before Pod 1, the **Coordinates** of Pod 2 do not change to match those of Pod 1.

NOTE After teaching both pods, the coordinates displayed for the two pods typically are slightly different.

Framing Deck Positions on the Biomek FX Using AccuFrame

The AccuFrame is a tool used for framing ALP and labware positions on the Biomek FX deck (Figure 4.1). Framing using the AccuFrame tool requires no human judgment of alignment and is reproducible.

Figure 4.1 AccuFrame Framing Tool



1. AccuFrame Light Beams
2. Hard Stop
3. Power Light
4. AccuFrame Light Beam Indicators
5. Gripper Cutout: Gripper fingers are framed in the cutout at the bottom of both sides of frame tool.

The AccuFrame fits snugly on an ALP, and a teaching process is performed through Biomek Software to obtain the coordinates for each deck position. The framing is completed by breaking two light sensors on the AccuFrame at their intersection point.

The coordinates for each ALP are generated automatically through the software based upon teaching one position; however, when precision is critical, as when using 384-well plates, each pod must be used to frame each position before using the Biomek FX instrument. This ensures that the pods and gripper locate each position reliably.

There are three indicator lights on the AccuFrame:

- First light indicates that the AccuFrame is powered on.
- Middle light indicates the framing status of the Y-axis.
- Third light indicates the framing status of the X- and Z-axes.

NOTE The AccuFrame is calibrated by a Beckman Coulter Representative. The calibration values are stored on the AccuFrame and read as necessary by Biomek Software.

Framing the deck positions of the Biomek FX using AccuFrame is performed in the same manner for either a Multichannel Pod or Span-8 Pod, except a framing fixture is attached to the head of a Multichannel Pod while a framing shaft is attached to a probe of a Span-8 Pod.

NOTE When framing multiple position ALPs such as the 1 X 3 Passive ALP, all positions on the ALP should be framed to increase precision.

To frame the deck positions of the Biomek FX, the following operations must be completed:

- *Homing All Axes of the Pods*
- *Attaching the Framing Fixture to the Pod*
- *Installing AccuFrame*
- *Framing the Position*

NOTE Some ALPs require additional or slightly modified procedures to frame properly. Consult the *ALPs User's Manual* (PN 987836) for the specific ALP to frame for any special instructions.

NOTE Deck positions on the Biomek FX can also be framed by choosing **Manual Teach** on **Position Properties**. **Manual Teach** involves loading tips and visually aligning them with the wells on a piece of labware (refer to *Manually Framing Deck Positions on the Biomek FX*). **Manual Teach** is useful if specialized or very high density labware is used, or when **Auto Teach** yields unsatisfactory results. Some ALPs, such as the Span-8 Tip Wash ALP and the Positive Position ALP, must be framed manually.

Homing All Axes of the Pods

⚠ CAUTION

Before selecting OK to home all axes, the following conditions must be met:

- **Make sure there is no liquid present in the tips.**
- **Make sure there are no disposable tips loaded.**
- **Make sure the Framing Probe is NOT installed on the Multichannel Pod.**
- **Make sure the gripper on the Multichannel Pod is retracted.**
- **Make sure either disposable tip mandrels or fixed tips ARE Installed on the Span-8 Pod.**
- **Make sure that the two arms are not near each other at either end of the rail.**

Prior to framing the Biomek FX deck with either a Multichannel Pod or a Span-8 Pod, all axes must be homed. Homing the pods gives Biomek FX a point of reference from which to make subsequent moves. For a single-pod system, home position is left, back. For a dual-pod system, home position for the first (left) pod is left, back and for the second (right) pod is right, back.

NOTE Home the pods each time the Biomek FX instrument is powered on. When attempting to use the pod, error messages result until the pod is homed.

NOTE While it is necessary to home the pods after the Biomek FX instrument is powered on, it is not necessary to home the pods each time the host computer is turned on or the software is accessed.

⚠ CAUTION

Always ensure that the gripper is retracted before homing.

To home the pods:

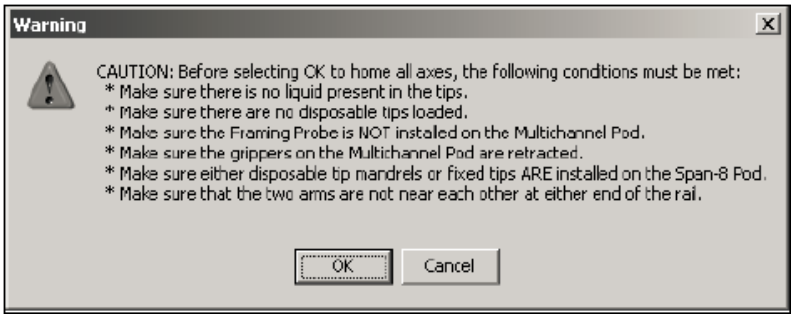
1 Choose **Start > Programs > Beckman Coulter > Biomek Software** to open the Biomek Software.

2 From the **Instrument** menu, choose **Home All Axes. Warning** appears (Figure 4.2).

NOTE **Home All Axes** may also be accessed by choosing **Instrument > Manual Control > Home All Axes** or **Hardware Setup > Home All Axes**.

NOTE Choosing **Home All Axes** homes all of the axes for all pods.

Figure 4.2 Warning to Address Before Homing Process Begins



3 Choose **OK** on each **Warning** and **Information** after confirming that the actions have been addressed appropriately.

Attaching the Framing Fixture to the Pod

After homing the pod(s), the appropriate framing fixture must be installed on the pod used for framing. The type of framing fixture required depends on the type of pod and head installed.

- Multichannel Pod with a 96-channel or 384-channel head (refer to *Attaching the Framing Fixture to the 96-Channel or 384-Channel Head of a Multichannel Pod*)
- Multichannel Pod with the HDR Tool Body (refer to *Attaching the Framing Fixture to the HDR Tool Body of a Multichannel Pod*)
- Span-8 Pod (refer to *Attaching the Framing Shaft to the Span-8 Pod*)

Attaching the Framing Fixture to the 96-Channel or 384-Channel Head of a Multichannel Pod

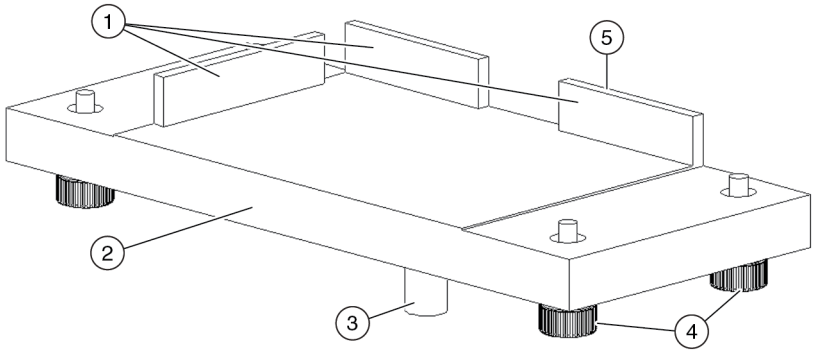
When positioning the framing fixture, the framing probe must be pointed down and away from the mandrels of the head. From the front perspective, the framing guides on the framing fixture must be to the back and left.

To install the framing fixture on the multichannel head:

1 Hold the framing fixture (Figure 4.3) against the head with the framing guides pressed to the outside of the back row and left column of mandrels.

NOTE Make sure the front of the framing fixture is to the front of the instrument, and the framing guides are to the back and left of the instrument (Figure 4.3).

Figure 4.3 Framing Fixture



1. Framing Guides
2. Front of Framing Fixture
3. Framing Probe
4. Thumbscrews: Four thumb screws attach the framing fixture to the Multichannel head.
5. Back of Framing Fixture

2 Gently pull the framing fixture to the front and right. Verify the framing guides are touching the mandrels.

3 Tighten each thumb screw by turning to the right until the framing fixture is firmly attached to the head. The pod is now ready for framing.

4 Install AccuFrame in the position to frame (refer to *Installing AccuFrame*) and frame the Multichannel Pod according to the procedure in *Framing the Position*.

Attaching the Framing Fixture to the HDR Tool Body of a Multichannel Pod

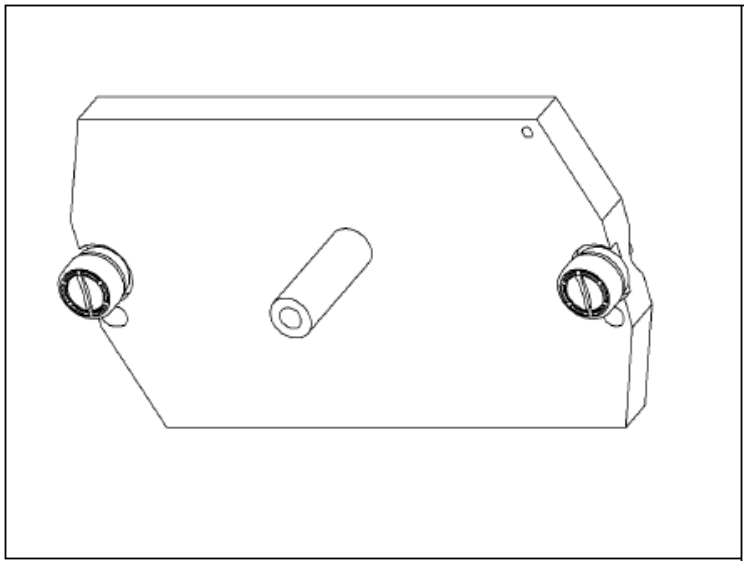
When positioning the HDR Framing Fixture (Figure 4.4), the framing probe must be pointed down and away from the mandrels of the head. From the front perspective, the framing guides on the framing fixture must be to the back and left.

⚠ CAUTION

When using Manual Teach to frame a position with the HDR Tool Body, move the D-axis all the way down to prevent the gripper from crashing into the microplate.

NOTE **Manual Teach** should be used only to frame the HDR Tool Body with a 384-pin plate installed. Automated framing is the recommended mode of framing when using a 96-pin plate.

Figure 4.4 HDR Framing Fixture



To frame the HDR Tool Body:

⚠ CAUTION

To prevent damage due to electrical static discharge (ESD), wear a wrist ground strap when installing the HDR Framing Fixture.

NOTE A wrist ground strap, which must be attached to the instrument deck (base plate) using the "alligator" clip, is supplied with the Biomek FX instrument.

1 Using **Manual Control**, lower the pod along the D-axis 0.9 cm from the maximum height and extend the grippers.

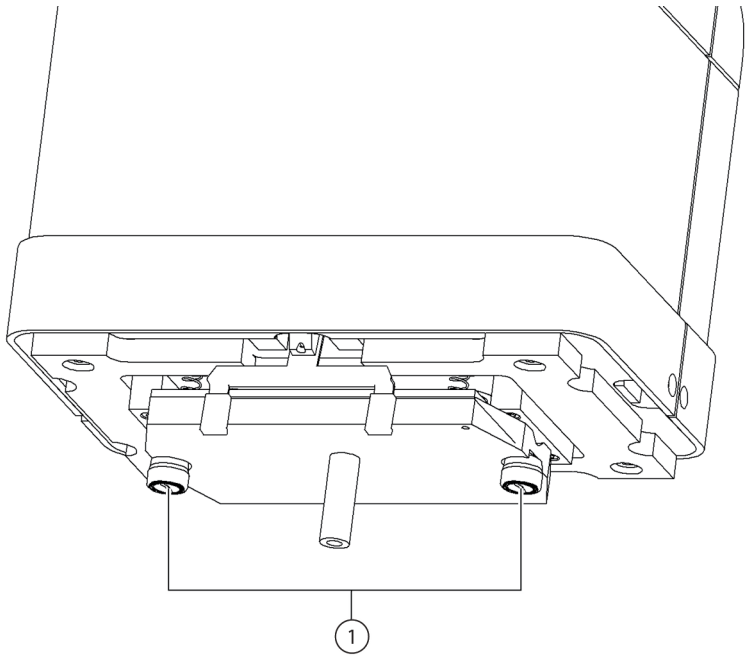
2 Turn off power to the Biomek FX instrument.

3 Slide the HDR Framing Fixture up between the gripper fingers to the HDR Tool Body such that the holes in the HDR Framing Fixture line up with the locating pins on the HDR Tool Body.

NOTE If a pin plate is already installed on the HDR Tool Body, remove the pin plate before installing the HDR Framing Fixture (refer to CHAPTER 1, *Removing Pin Plates*).

4 Tighten the two thumb screws to fasten the HDR Framing Fixture to the HDR Tool Body (Figure 4.5).

Figure 4.5 Fastening HDR Framing Fixture to the HDR Tool Body



1. Thumbscrews

5 Install AccuFrame in the position to frame (refer to *Installing AccuFrame*) and frame the Multichannel Pod according to the procedure in *Framing the Position*.

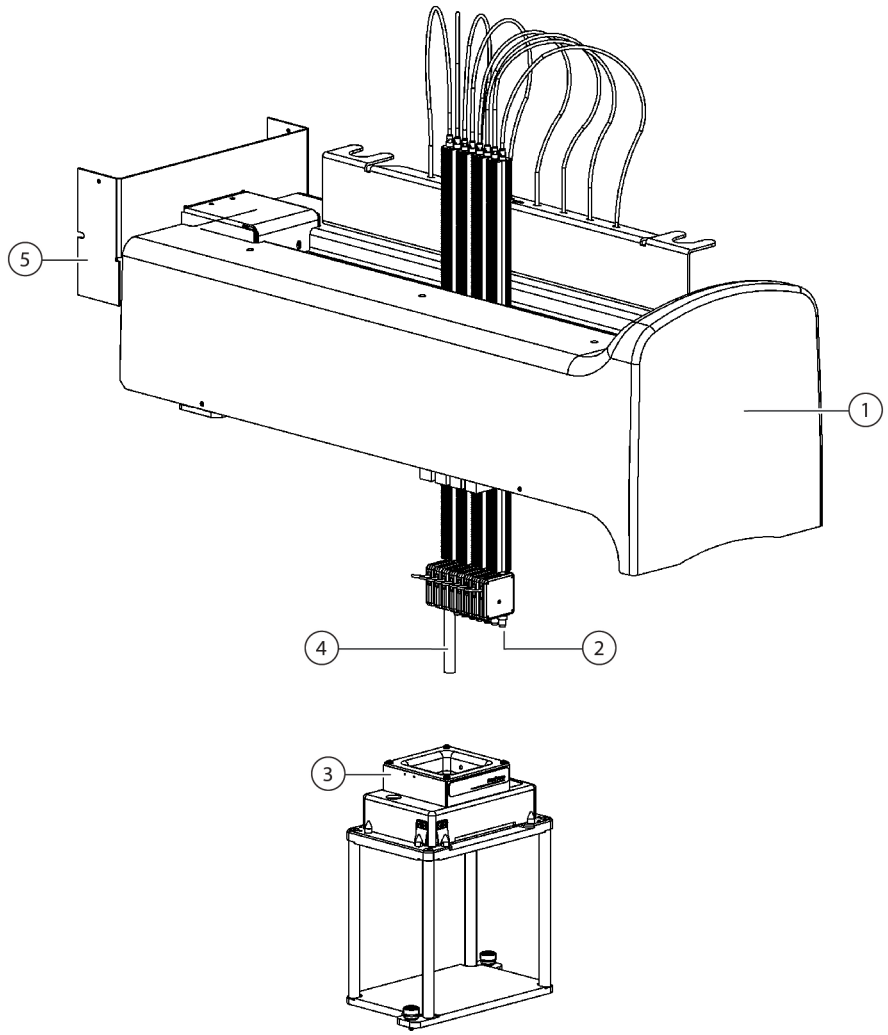
Attaching the Framing Shaft to the Span-8 Pod

After homing all axes of the pod and installing and positioning the AccuFrame, the framing shaft is attached to either probe #1 or probe #7 on the Span-8 Pod.

The framing shaft is attached to probe #1 when all positions, except those along the front of the deck, are framed (Figure 4.6). Because probe #1 is unable to reach the AccuFrame when it is placed in the front deck positions, probe #7 must be used to frame positions along the front of the deck.

NOTE Probes on the Span-8 Pod are numbered from back to front; more specifically, probe #1 is at the back of the Span-8 Pod and probe #8 is at the front of the pod.

Figure 4.6 Framing a Span-8 Pod



1. Front of the Biomek FX instrument.
2. The framing shaft is attached to probe #7 to frame positions in the front row of the Biomek FX deck.
3. AccuFrame on ALP
4. The framing shaft is attached to prove #1 to frame all deck positions, except those in the front row of the Biomek FX deck.
5. Back of the Biomek FX instrument.

To attach the framing shaft to a probe:

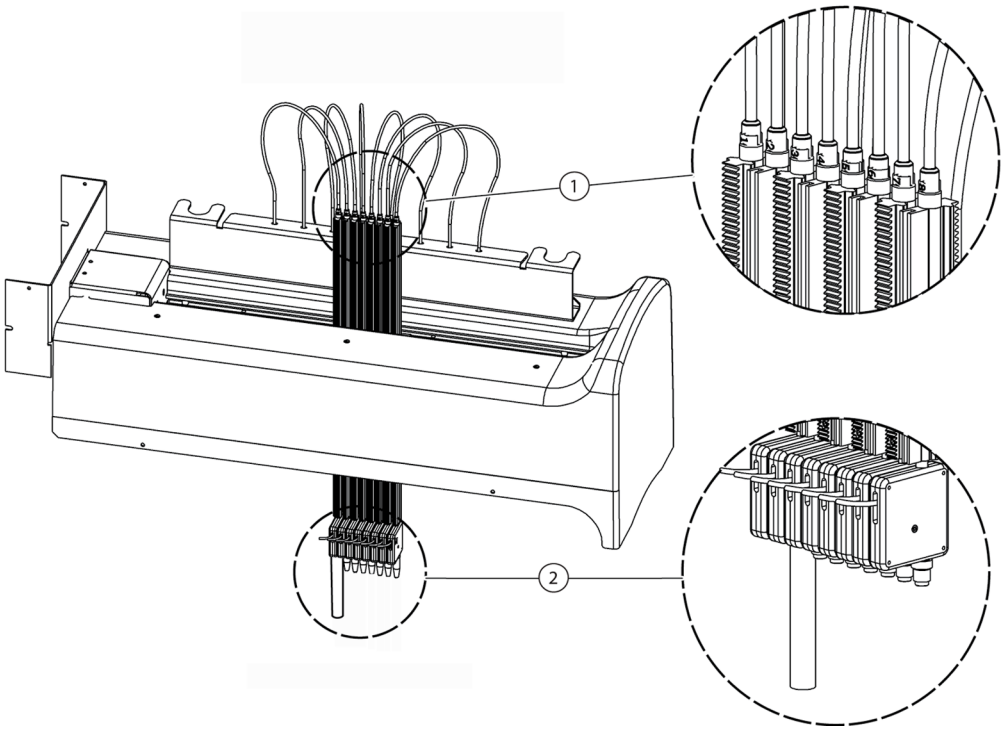
---

1 Remove the tip from the desired Span-8 probe (probe #1 or #7) (refer to CHAPTER 2, *Interchangeable Tips*).

---

2 Screw the framing shaft onto the appropriate probe (Figure 4.7).

Figure 4.7 Attaching a Framing Shaft (Details)



1. Probes
2. Framing Shaft

3 Install AccuFrame in the position to frame (refer to *Installing AccuFrame*) and frame the Span-8 Pod according to the procedure in *Framing the Position*.

Installing AccuFrame

The AccuFrame is used during the framing process of the Multichannel Pod, and the AccuFrame and Framing Shaft are used to frame the Span-8 Pod. After these tools are attached to the ALP and Pod respectively, the framing process is completed through the software.

⚠ WARNING

Turn off power to the Biomek FX instrument before attaching or removing AccuFrame from the instrument deck.

1 Turn off power to the Biomek FX instrument before connecting the AccuFrame.

2 Plug AccuFrame into an available CAN port on the Biomek FX tower.

⚠ WARNING

Make sure the light curtain is not violated by the AccuFrame cable. If the light curtain is violated, the framing process halts immediately.

⚠ WARNING

Make sure the AccuFrame cable does not interfere with pod movement.

3 Turn on power to the Biomek FX instrument.

4 Manually place the AccuFrame onto the ALP position that requires framing by placing the back right corner first and pushing the AccuFrame gently down onto the ALP position.

NOTE The deck is usually framed from left to right, starting at the back left position. However, ALPs may be framed in any order.

5 Make sure that the AccuFrame is fully seated along the posts along the top and right sides of the position.

NOTE When framing a dual-pod system, frame both pods to each position.

NOTE Some ALPs require a framing adaptor to accommodate using AccuFrame to frame the position. Make sure the correct adaptor is used for each type of ALP. Framing proceeds as normal once the AccuFrame is placed on the appropriate adaptor.

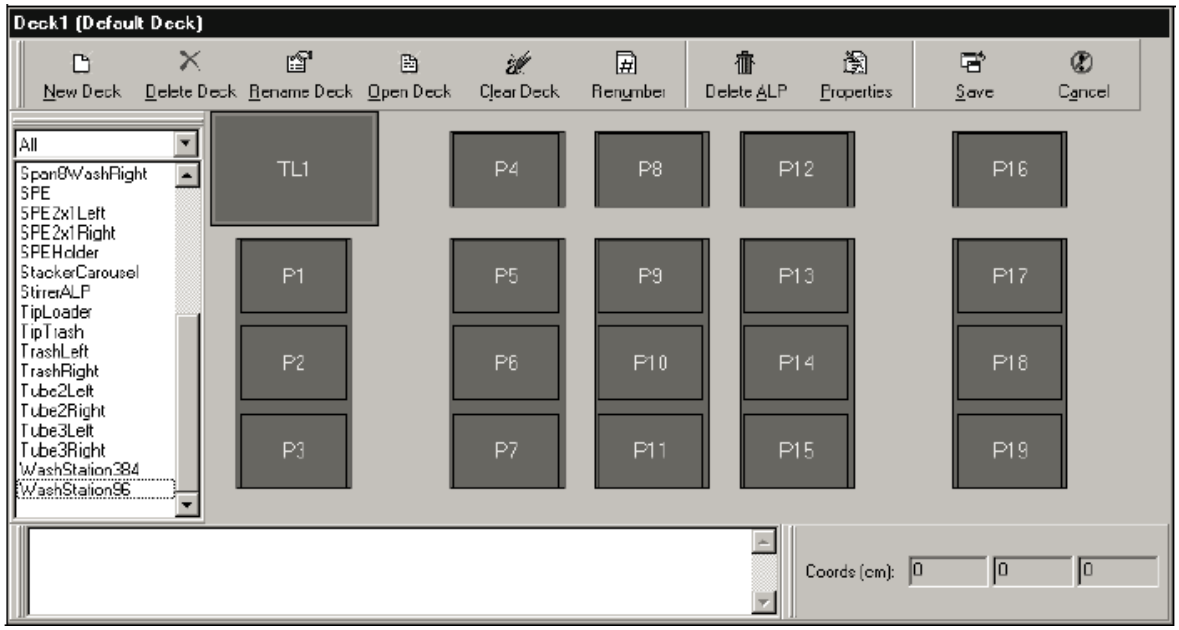
Framing the Position

To frame the Biomek FX deck position:

NOTE Some ALPs require additional or slightly modified procedures to frame properly. Consult the *ALPs User's Manual* (PN 987836) for the specific ALP to frame for any special framing instructions.

1 In Biomek Software, choose **Instrument > Deck Editor**. **Deck Editor** appears (Figure 4.8)

Figure 4.8 Deck Editor

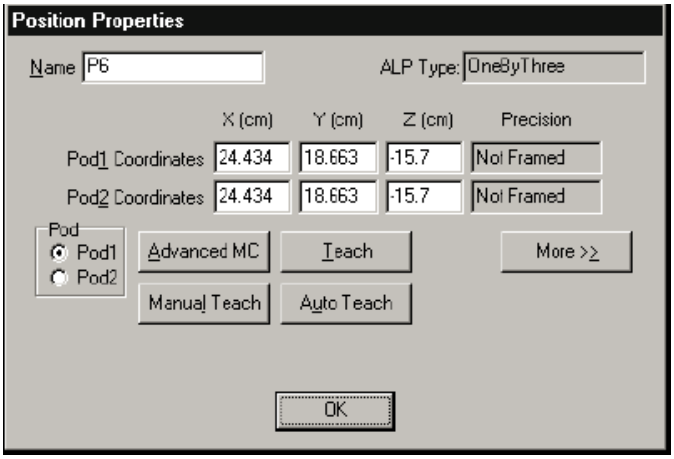


2 In Biomek Software, open the deck that requires framing in the **Deck Editor**. Verify that it reflects the current configuration of ALPs on the physical deck. If it does not reflect the current physical deck configuration, place devices on the appropriate deck locations in the **Deck Editor** by dragging and dropping from the list onto the deck. When the **Deck Editor** reflects the configuration of the current physical deck, proceed to step 3.

3 Double-click on the deck position containing the AccuFrame. **Position Properties** appears (Figure 4.9).

NOTE The coordinates displayed are default values, so the software must be taught precisely where the position is on the physical deck.

Figure 4.9 Position Properties

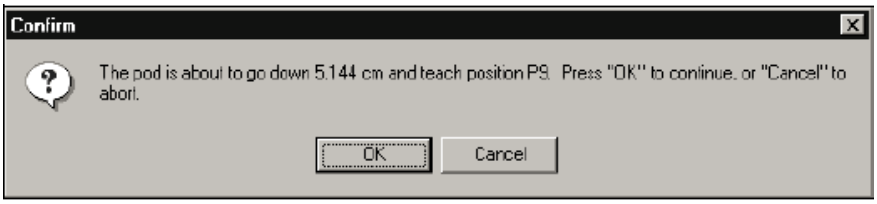


4 If using a dual-pod system, choose the pod being taught: **Pod 1** or **Pod 2**.

5 Choose **Auto Teach**. A Confirm similar to Figure 4.10 appears.

NOTE This moves the pod to the position being taught. The framing probe should be above the AccuFrame in that position.

Figure 4.10 Confirm



6 Visually verify that the framing probe is positioned to avoid hitting the wall of the AccuFrame and that it is positioned to lower within the AccuFrame tool.

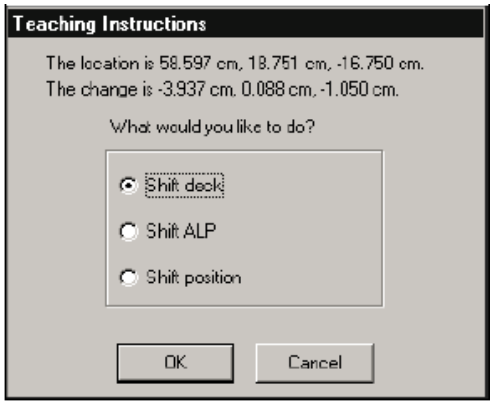
7 Choose **OK**.

NOTE The pod lowers and moves around inside the AccuFrame automatically until it breaks both light beams (Figure 4.1). The pod stops after teaching (framing) is completed, and the two light beam indicators are illuminated.

NOTE An error message appears if both light beams are not broken when the pod is lowered into the AccuFrame. If this occurs, using **Advanced Manual Control** (if necessary, refer to CHAPTER 5, *Manually Controlling the Biomek FX in Biomek Software*), move the pod until the probe breaks both light beams and all the indicator lights are on. Choose **Teach**, and the pod continues the teaching process. The pod may also be moved by hand until the probe breaks both light beams and all the indicator lights are on.

8 Wait until the pod stops moving and **Teaching Instructions** appears (Figure 4.11).

Figure 4.11 Teaching Instruction



9 Choose from **Shift deck**, **Shift ALP**, or **Shift position** for appropriate teaching instructions (refer to *Selecting Appropriate Teaching Instructions*).

10 If the coordinates displayed appear reasonable, choose **OK**. **Position Properties** appears again, and the position is framed for the selected pod

11 Choose **OK** to close **Position Properties**.

12 For framing additional positions, move the AccuFrame to the next position to frame (refer to *Installing AccuFrame*) and repeat steps 3 through 11.

NOTE When framing positions using the Span-8 Pod, the framing shaft must be moved to probe #7 to frame positions in the front row of the deck (refer to *Attaching the Framing Shaft to the Span-8 Pod*).

13 Choose **Save** to save framing information for all positions and close the **Deck Editor** (Figure 4.8).

NOTE Choosing **Cancel** loses all changes to the deck, including framing information, since the **Deck Editor** was opened.

14 Remove the framing fixture from the head of the Multichannel Pod.

OR

Remove the framing shaft from the probe on the Span-8 Pod.

Selecting Appropriate Teaching Instructions

In **Teaching Instructions** (Figure 4.11), the entire deck, a deck position, or an ALP can be shifted by the teaching process. Determine what should be shifted using the following information:

⚠ CAUTION

Use Shift deck only before other ALPs or positions are taught. Shift deck shifts all ALPs and positions, resulting in incorrect coordinates if applied to previously framed ALPs and positions.

- **Shift deck** — shifts all ALPs and positions associated with the deck by the change amounts shown. Choose **Shift deck** when framing the first location of a new deck. The shift amount required typically is not large, but everything on the deck may need to move 1 cm, for example.
- **Shift ALP** — shifts the entire ALP and all deck positions associated with the ALP by the change amounts shown. **Shift ALP** typically is precise enough for using 96-well plates.
- **Shift position** — shifts only the deck position containing the AccuFrame by the amounts shown. **Shift position** is the most precise teaching procedure, and it is useful when 384-well microplates are used (especially on larger ALPs, such as the 4x4); otherwise, **Shift ALP** is usually sufficient.

NOTE When framing a multiple-position ALP (1x3, 1x5, 4x3, or 4x4), **Shift ALP** on the first position, then **Shift position** on the rest.

Manually Framing Deck Positions on the Biomek FX

Manual Teach is a wizard-type interface that is used manually frame deck positions, primarily for using high density labware. Since the wells of high density labware are relatively small, using **Manual Teach** helps to ensure that the tips can access the wells without causing any damage to the tips, probes, pod, or ALP.

NOTE Some ALPs, such as the Positive Position ALP, must be framed using Manual Teach to improve pipetting accuracy to high density labware.

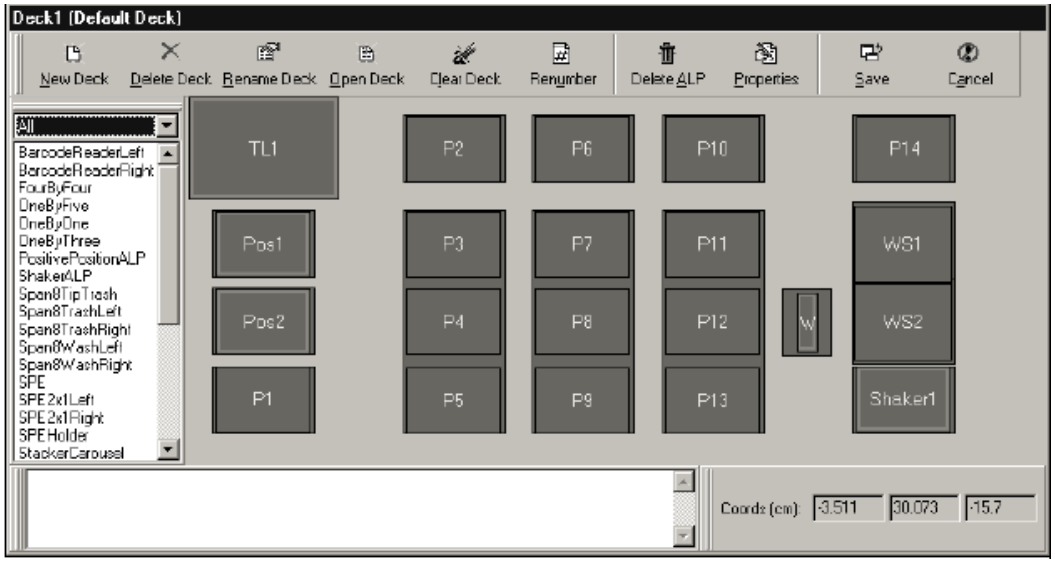
NOTE When not using high density labware, the standard framing procedure using the AccuFrame is acceptable. To frame using the AccuFrame, refer to *Framing Deck Positions on the Biomek FX Using AccuFrame*.

To frame using **Manual Teach**:

1 Choose **Start > Programs > Beckman Coulter > Biomek Software** to open the Biomek Software.

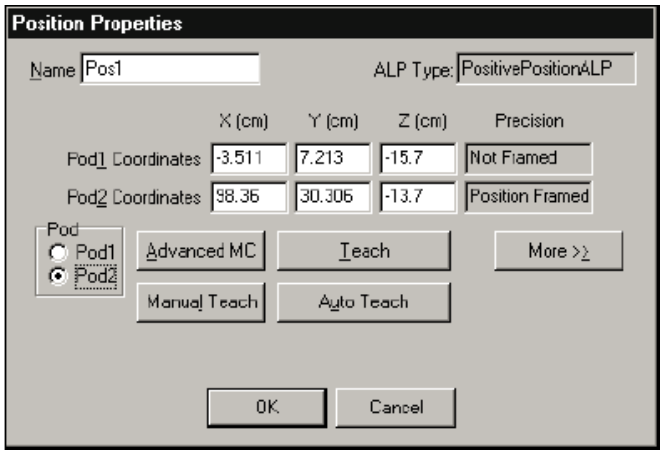
2 Choose **Instrument > Deck Editor**. **Deck Editor** appears (Figure 4.12).

Figure 4.12 Deck Editor



3 Open **Position Properties** for the desired deck position by double-clicking on the deck position. **Position Properties** appears (Figure 4.13).

Figure 4.13 Position Properties for a Positive Position ALP



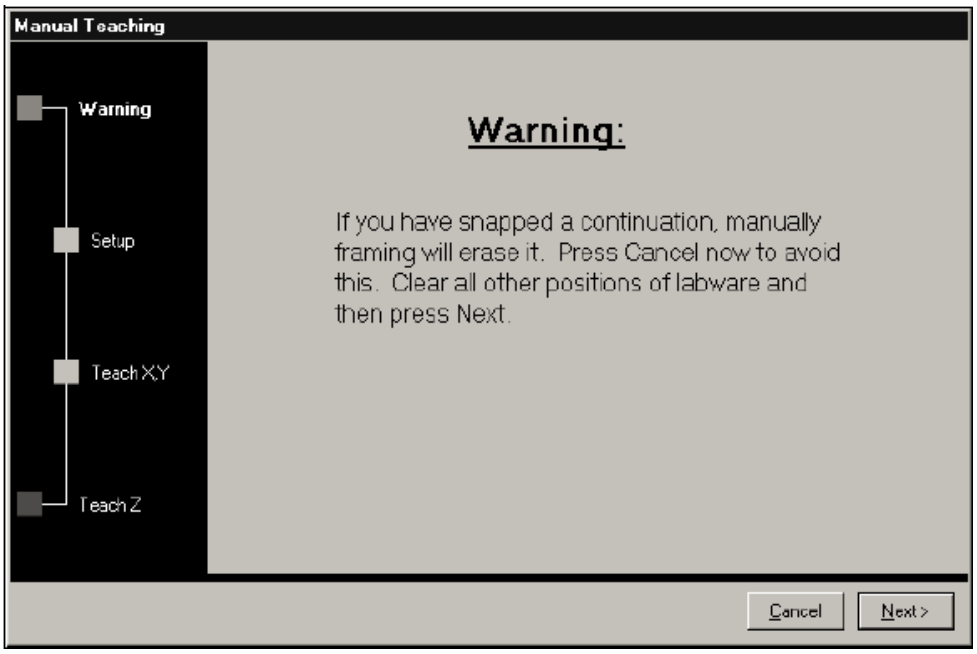
4 In **Name**, verify that the ALP is assigned a unique name.

5 In **Pod**, select the pod used to frame the desired position.

6 Choose **Manual Teach. Manual Teaching** opens with a **Warning** (Figure 4.14).

NOTE On the left side of **Manual Teaching**, a list of steps required to complete the teaching process is displayed. As the steps of **Manual Teaching** are accessed, the steps are highlighted on the left.

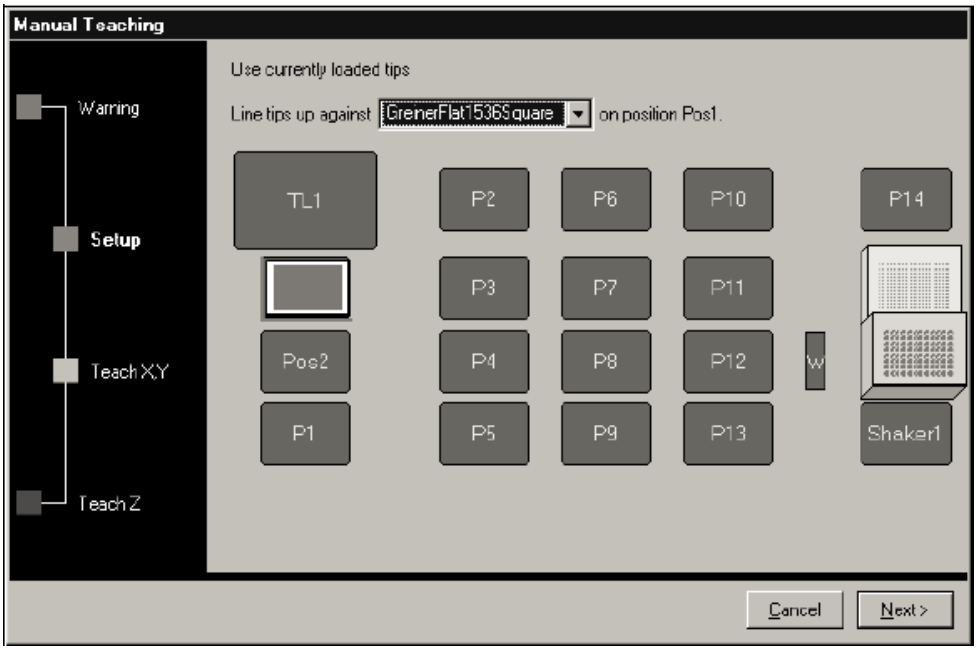
Figure 4.14 Manual Teaching (Warning)



7 Choose **Next** and either Figure 4.15 or Figure 4.16 appears, depending on whether or not tips are already loaded onto the pod.

Figure 4.15 Manual Teaching if Tips Are Not Already Loaded

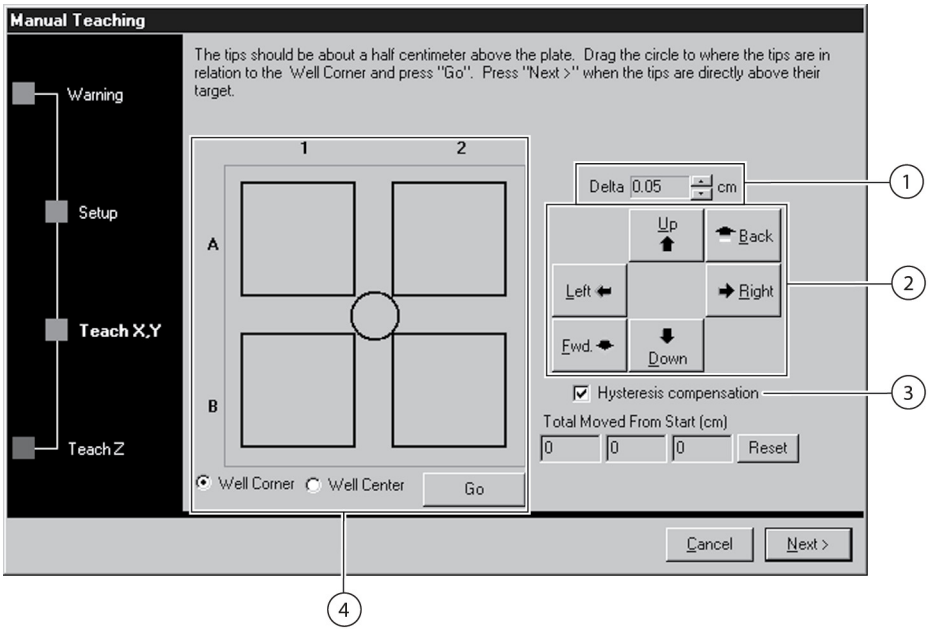
Figure 4.16 Manual Teaching if Tips Are Loaded



8 In **Line tips up against**, select the appropriate labware type of the labware placed in the position to frame.

9 Choose **Next. Teach X,Y** appears (Figure 4.17).

Figure 4.17 Manual Teaching



1. **Delta Value**: The magnitude of change applied to the tips each time a directional button is selected.
2. **Directional Buttons**: The directional buttons move the pod by the amount shown in Delta with each press of a button.
3. **Hysteresis Compensation**: Leave Hysteresis compensation at the default setting of On. This compensates for any variance along the X-axis from the front of the bridge to the back of the bridge. The Biomek FX determines a pods position in the X-axis based on the position of the bridge at the back of the Biomek FX instrument).
4. **Graphic Alignment Tool**: The graphic alignment tool is a visual representation of the tip (small circle) and the wells of the microplate (the four squares). The small circle is moved until it represents the tip's current physical location in relation to the wells of the microplate on the ALP.

10 To align the tips in the X- and Y-axes with the wells of the microplate on top of the ALP, lower the tips in the Z-axis until they are approximately 1 mm above the top of the ALP.

NOTE Since tip height is set in the next step in the **Manual Teaching** process, it is safe to move the pod to any height to make aligning the tips with the microplate easier.

11 Visually verify the physical position of the tips in relation to the physical position of the wells of the microplate on top of the ALP.

12 Select **Well Corner** to align the tips to the corners, or junction, of four wells.

NOTE **Well Corner** is available only when framing to a deck position occupied by a piece of labware with square wells.

OR

Select **Well Center** to align the tips to the center of the wells.

13 In **Delta**, select the magnitude of change applied to the tips each time a directional button is selected (Figure 4.17).

NOTE The default **Delta** value is 0.05 cm. If the tips are a considerable distance from the desired location, increase the distance traveled by increasing the **Delta** value (maximum setting is 1.0 cm). If the tips are almost to the desired location, reduce the **Delta** value to fine tune the position (minimum setting is 0.005 cm).

14 Select the directional button representing the motion required to physically move the tip into position over the wells of the microplate on top of the ALP (Figure 4.17).

NOTE Each time a directional button is selected, the pod and tips move the distance specified in **Delta** in the indicated direction.

NOTE The tips can be can physically positioned over the wells of a microplate using:

- the directional buttons in **Manual Teach**.
- the directional keys on the keyboard.
- the directional keys on the numeric keypad.

  The directional buttons displayed in **Manual Teach** parallel the keys on the numeric keypad. More specifically, **Fwd**. correlates to the '1' on the numeric keypad, while **Down** is found on the '2', Left is found on the '4', **Right** on '6', **Up** on '8', and **Back** on '9'.

OR

Using the graphic alignment tool (Figure 4.17), **drag the center (small) circle** until it represents the tip's physical position in relation to the wells of the microplate on top of the ALP.

NOTE The small circle represents the tips on the pod. The objective is to provide the software with a representation of the tip's position in relation to the wells of the microplate on top of the ALP. The software uses this graphical representation to know approximately how far in any direction the tips must move.

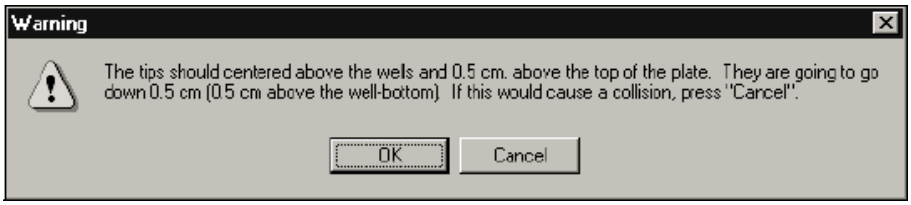
15 Select **Go**. The pod moves in accordance with the position of the small circle in relation to the large circle.

NOTE When the move is completed, the small circle resets itself to the center of the large circle. The values displayed in **Total Moved from Start (cm)** changes each time steps 10 through 15 are completed. If desired, the values in **Total Moved from Start (cm)** can be reset to zero by selecting **Reset**.

16 Visually verify the position of the tips on the Biomek FX instrument in relation to the wells of the microplate on top of the ALP. If the tips are still not accurately positioned above the microplate, repeat steps 10 through 16 until they are accurately positioned above the microplate.

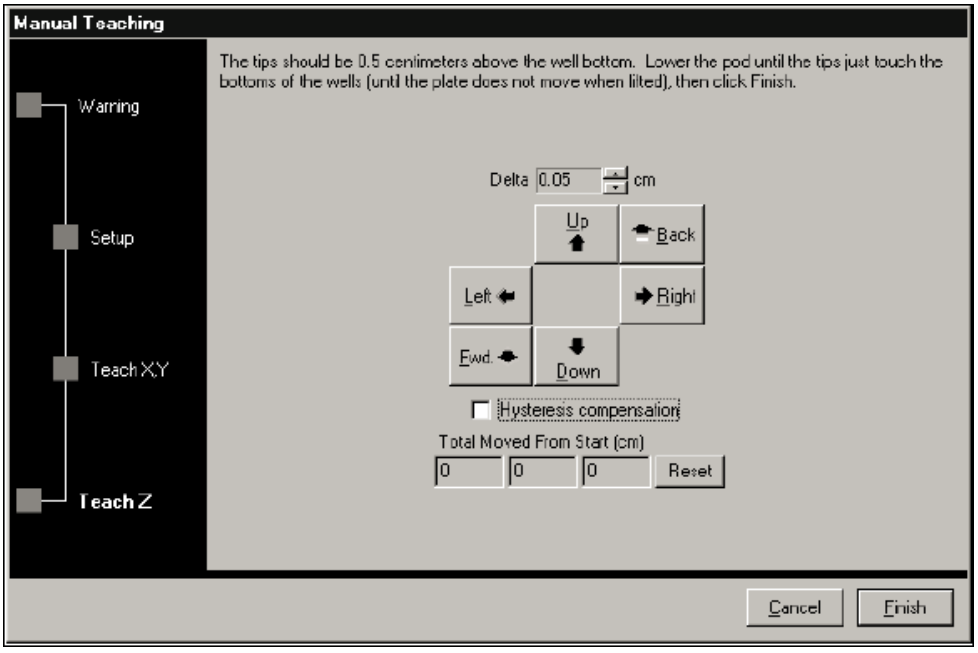
17 Choose **Next** and Figure 4.18 appears.

Figure 4.18 Manual Teach Warning on Tips Descending into a Microplate



18 Address the Warning and choose **OK**. **Teach Z** appears (Figure 4.19).

Figure 4.19 Manual Teaching (Teach Z)



19 In **Delta**, select the magnitude of change applied to the tips each time a directional button is selected (Figure 4.19).

NOTE The default **Delta** value is 0.05 cm. If the tips are a considerable distance above the ALP, increase the distance traveled by increasing the **Delta** value (maximum setting is 1.0 cm). If the tips are almost to the desired location, reduce the **Delta** value (minimum setting is 0.005 cm).

NOTE Since the X and Y axes were framed previously, it is safe to move the pod in the X and Y axes if it makes framing the pod in the Z- axis easier.

20 Select the **directional button** representing the motion required to physically move the tip down into the wells of the microplate until the tips touch the bottom of the wells.

NOTE Each time a directional button is selected, the pod and tips move the distance specified in **Delta** in the indicated direction.

NOTE The tips can be can physically positioned over the wells of a microplate using:

- the directional buttons in **Manual Teach**.
- the directional keys on the keyboard.
- the directional keys on the numeric keypad.

The directional buttons displayed in **Manual Teach** parallel the keys on the numeric keypad. More specifically, **Fwd**. correlates to the '1' on the numeric keypad, while **Down** is found on the '2', **Left** is found on the '4', **Right** on '6', Up on '8', and **Back** on '9'.

21 Select **Finish**. The pod moves up to its maximum height in the Z-axis, **Manual Teaching** closes, and **Position Properties** appears (Figure 4.13).

22 Choose **OK** to save the framing information and close **Position Properties**.

NOTE Both pods on a dual-pod Biomek FX instrument must frame the same deck position.

23 Repeat steps 3 to 22 to frame additional deck positions using manual teach.

24 Choose **Save** to save framing information for all positions and close the **Deck Editor** (Figure 4.15).

NOTE Choosing **Cancel** loses all changes to the deck, including framing information, since the **Deck Editor** was opened.

Framing the Gripper on a Multichannel Pod

A Beckman Coulter Representative frames the gripper on a Multichannel Pod during system installation; however, it may be necessary to repeat the framing procedure if:

- the head on a Multichannel Pod is changed.
- gripper is replaced.
- extraordinary circumstances occur, such as accidentally bending a gripper finger.

Before framing the gripper, make sure:

- instrument is homed (refer to *Homing All Axes of the Pods*).
- deck position is framed prior to framing the gripper to that location (refer to *Framing Deck Positions on the Biomek FX Using AccuFrame*).
- AccuFrame is installed on the appropriate position (refer to *Installing AccuFrame*).
- framing fixture is not attached to the Multichannel Pod.

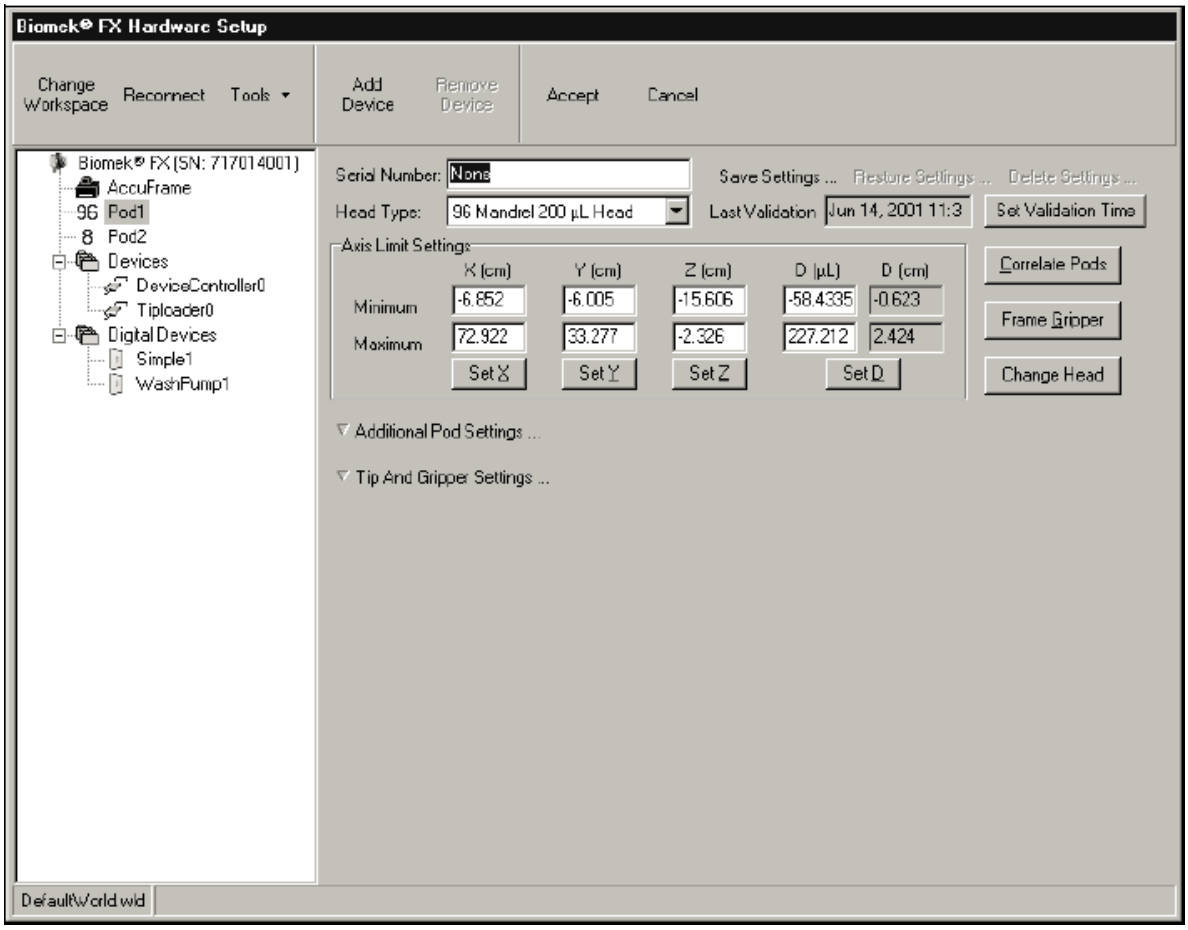
To frame the grippers:

1 Choose **Start > Programs > Beckman Coulter > Biomek Software** to start the Biomek Software.

2 From the **Instrument** menu, choose **Hardware Setup**. **Hardware Setup** appears.

3 Choose the desired Multichannel Pod. The configuration to frame the gripper appears on the right (Figure 4.20).

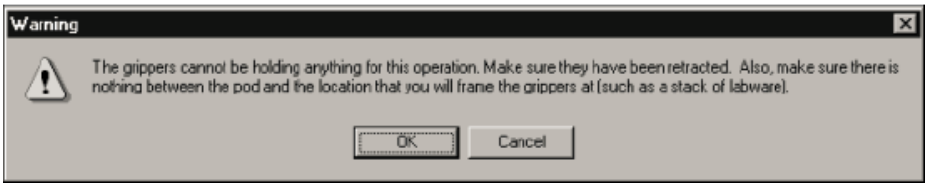
Figure 4.20 Hardware Setup



4 Choose **Frame Gripper.**

5 When a **Warning** appears, make sure the topics that appear in the **Warning** are addressed and choose **OK** (Figure 4.21).

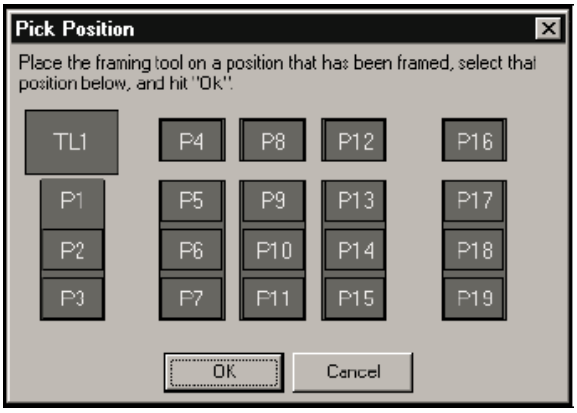
Figure 4.21 Warning to Make Sure Grippers are Ready for Framing



6 In **Pick Position** (Figure 4.22), select a previously framed deck position and frame the gripper to that location. The deck position must be framed first and should be a small passive ALP, if possible.

NOTE Make sure that the AccuFrame is correctly placed on the selected position (refer to *Installing AccuFrame*).

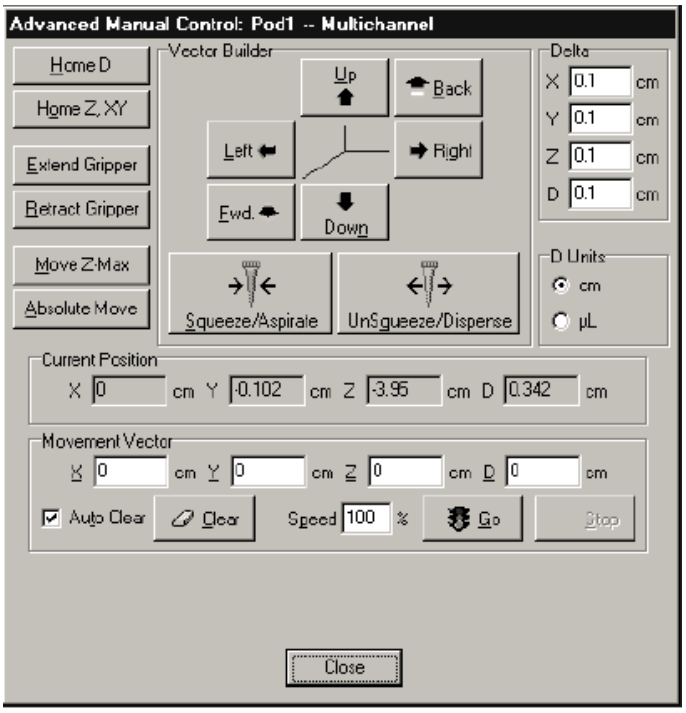
Figure 4.22 Pick Previously Framed Deck Position to Frame the Grippers



7 Choose **OK**. This moves the pod to that position and extends the grippers. **Advanced Manual Control** (Figure 4.23) and **Frame Gripper** (Figure 4.24) appear side by side.

NOTE The gripper is extended a little high and opened a little wide at the end of the move initiated by step 6.

Figure 4.23 Advanced Manual Control for Moving Gripper During Framing



NOTE Do not select **Close**; if **Advanced Manual Control** closes, the framing process must be completed again, beginning with step 1.

Figure 4.24 Moving Pod Into Gripping Position

8 Use **Advanced Manual Control** to move the gripper fingers until they are aligned with the bottom of the AccuFrame (Figure 4.25), and squeeze the gripper fingers until they firmly touch the AccuFrame inside the notches at the bottom of the AccuFrame (Figure 4.26). (If necessary, refer to CHAPTER 5, *Manually Controlling the Biomek FX in Biomek Software*).

NOTE Both front and rear gripper fingers must touch at the same time when squeezing, which usually necessitates a move along the Y-axis.

NOTE Assessing the position of the gripper fingers in step 7 is a visual task (Figure 4.23).

Figure 4.25 Gripper Framing Position on the AccuFrame

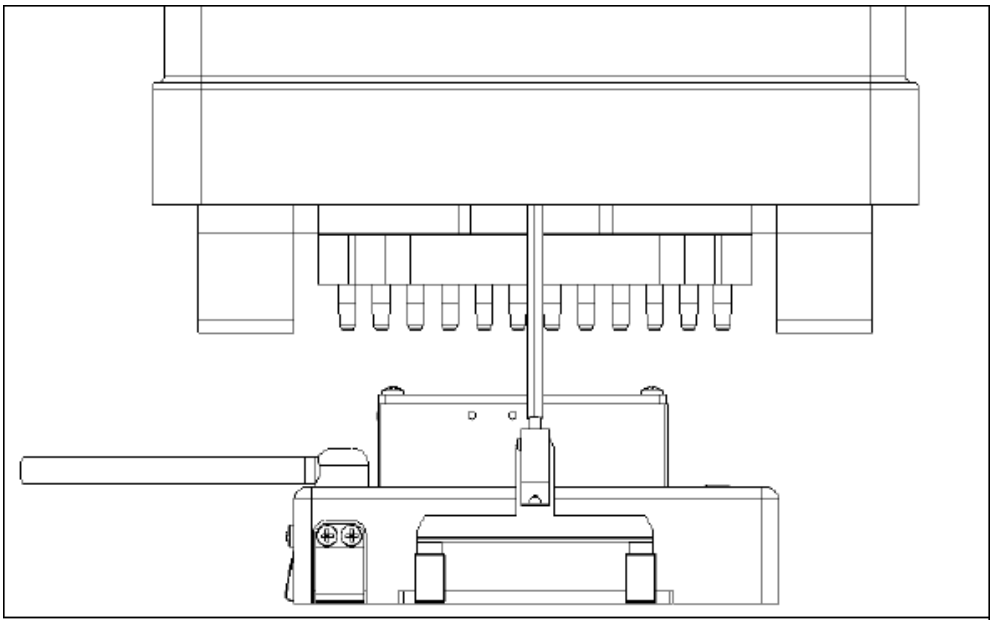
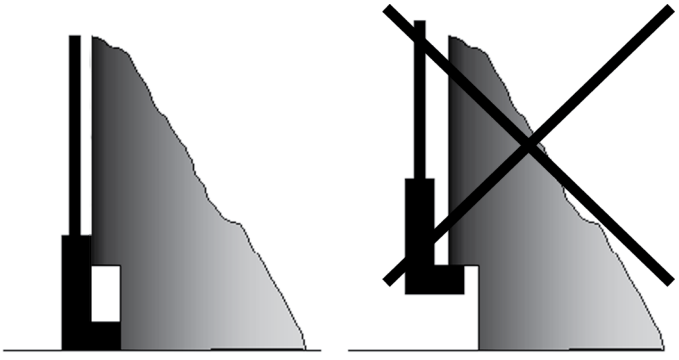


Figure 4.26 Correct and Incorrect Gripper Framing Alignment



1. **Correct Gripper Alignment**: Bottom of gripper finger aligned to bottom of AccuFrame and aligned to the inside of cut-out.
2. **Incorrect Gripper Alignment**: Top of gripper finger aligned to top of cut-out of AccuFrame without aligning to inside of cut-out.

9 In **Frame Gripper**, choose **OK** (Figure 4.24).

NOTE The gripper is now framed for the selected pod. If necessary, complete the gripper framing process for the other Multichannel pod in a dual-pod system.

10 From **Hardware Setup**, choose **Accept**. **Hardware Setup** closes.

11 From the **Instrument** menu, choose **Manual Control**. **Manual Control** appears.

12 Choose **Advanced Controls** and select the Multichannel Pod. **Advanced Manual Control** appears (Figure 4.23).

13 Choose **Move Z-Max**.

NOTE Choosing **Move Z-Max** raises the pod to access the AccuFrame.

14 Choose **Close** to close **Advanced Manual Control**.

15 Choose **Exit** to close **Manual Control**.

16 Remove the AccuFrame from the ALP position.

Testing Gripper Framing Accuracy

To make sure the gripper works properly, create and run a method at reduced speed (around 10%) to move a piece of labware from one framed deck position to another (refer to CHAPTER 3, *Setting Multichannel Pod Properties*). If problems occur, repeat the gripper framing process until the gripper is working correctly.

Troubleshooting

Perform the troubleshooting techniques provided in Table 4.1 when necessary.

NOTE In the case of any other framing-related problems, contact a Beckman Coulter Representative

Table 4.1 Troubleshooting Framing

If...	Then...
AccuFrame power light not on	Check the CAN connection to make sure the AccuFrame is connected to Biomek FX instrument.
The Y-axis and the X/Z-axes Light Beams cannot be broken when moving a finger around the interior of AccuFrame	Make sure the AccuFrame is receiving power.
One or both beam indicator lights on AccuFrame stay on when no objects are breaking the light beams	There is most likely an internal obstruction to sensors. Call a Beckman Coulter Representative.

CHAPTER 5

Manually Controlling the Biomek FX in Biomek Software

Overview

Manual Control and **Advanced Manual Control** are used to control:

- Movement of the bridge, head, and gripper independently of a method.

  NOTE Many activities performed in **Advanced Manual Control** are the same for the Multichannel Pod and the Span-8; however, the dialogs are different and the buttons for performing these activities may be placed in different areas.

- Pod when teaching the deck, framing the grippers, and recovering from errors.
- HDR Pin Drying, Tip Loader, Magnetic Bead, Microplate Shaking, Positive Position, Orbital Shaker, and Stirring ALP and the Speed Pump independently of a method.

  NOTE Refer to the *ALPs User's Manual* (PN 987836) for information on manually controlling specific ALPs.

The sections in this chapter include:

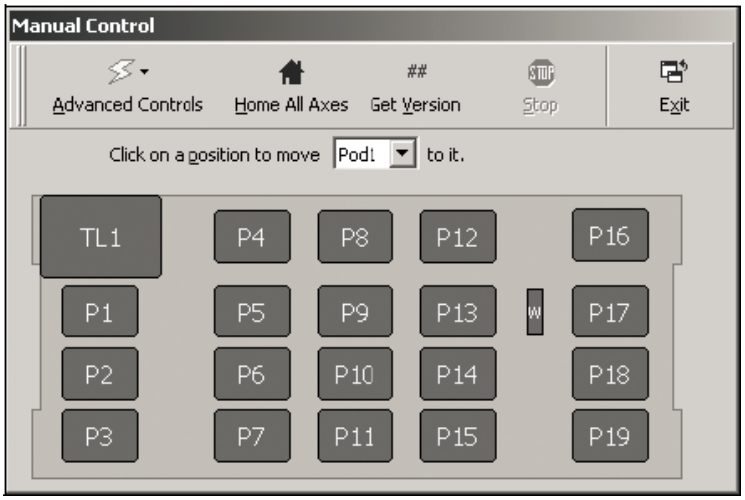
Accessing Manual Control

To open **Manual Control**, choose **Instrument > Manual Control.** An Information dialog (Figure 5.1) appears briefly as the connection is made with the Biomek FX instrument, immediately followed by **Manual Control** (Figure 5.2).

NOTE **Manual Control** is available only when a method is not being executed. If a need for manual control is realized during a method run, stop the method using the **Stop** button or **Snap Continuation** button (refer to the *Biomek Software User's Manual* (PN 987835), *Snapping a Continuation*) on the toolbar before accessing **Manual Control**.

Figure 5.1 Confirms Manual Control is Connecting

Figure 5.2 Manual Control



Using Manual Control

Use **Manual Control** for:

- *Homing All Axes of the Pod or Pods*
- *Moving a Pod to a Specific Deck Position*
- *Stopping a Pod*
- *Viewing the Firmware Version*
- *Accessing Advanced Manual Control*

Homing All Axes of the Pod or Pods

⚠ CAUTION

Before selecting OK to home all axes, the following conditions must be met:

- **Make sure there is no liquid present in the tips.**
- **Make sure there are no disposable tips loaded.**
- **Make sure the Framing Probe is NOT installed on the Multichannel Pod.**
- **Make sure the gripper on the Multichannel Pod is retracted.**
- **Make sure either disposable tip mandrels or fixed tips ARE Installed on the Span-8 Pod.**
- **Make sure that the two arms are not near each other at either end of the rail.**

Home the pods each time the Biomek FX instrument is powered on. Homing the pods gives Biomek FX a point of reference from which to make subsequent moves. For a single-pod system, home position is left, back. For a dual-pod system, home position for the first (left) pod is left, back and for the second (right) pod is right, back.

NOTE When attempting to use the pod, error messages result until the pod is homed.

NOTE While it is necessary to home the pods after the Biomek FX instrument is powered on, it is not necessary to home the pods each time the host computer is turned on or the software is accessed.

⚠ CAUTION

Always ensure that the gripper is retracted before homing.

To home the pods:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Home All Axes**. The following **Warnings** and **Information** appear, depending on the type of pods on the system (Figure 5.3), (Figure 5.4), (Figure 5.5), (Figure 5.6), and (Figure 5.7):

Figure 5.3 Warnings Must be Addressed Before the Homing Process Begins

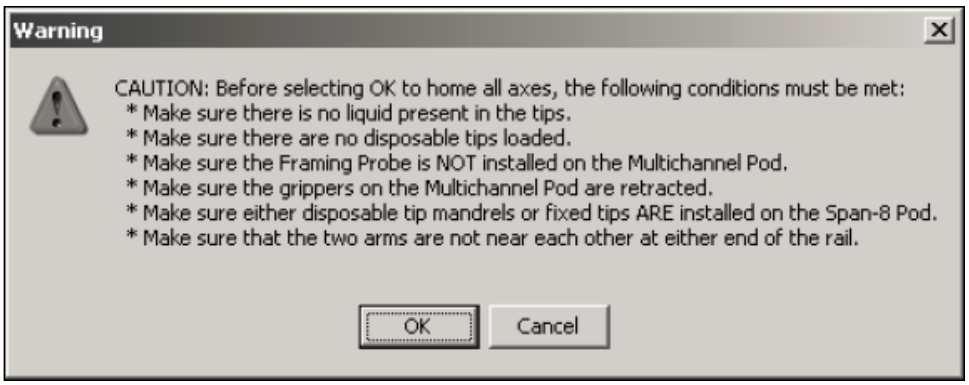


Figure 5.4 Warning to Address if the System is Dual-Pod

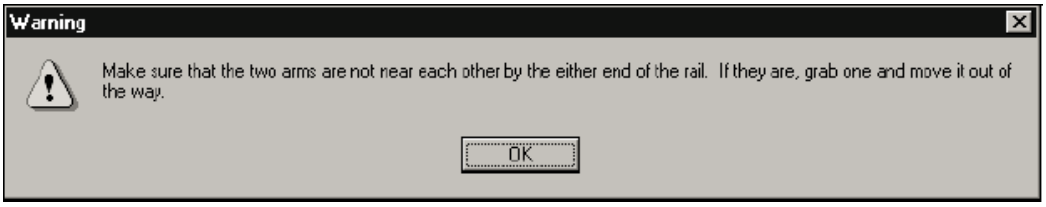


Figure 5.5 Warning to Address if a Span-8 Tip Wash ALP Has Not Been Added to the Deck Configuration

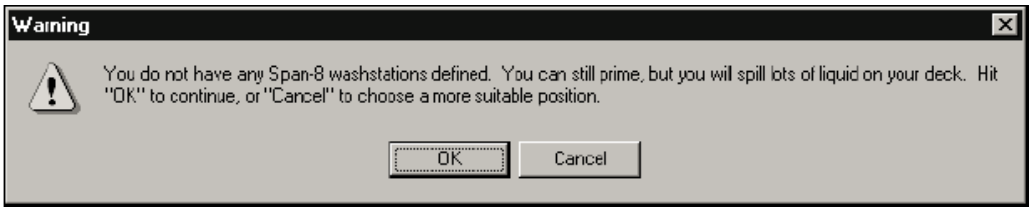


Figure 5.6 Warning that the Span-8 Probes Are about to Go Down to the Washstation

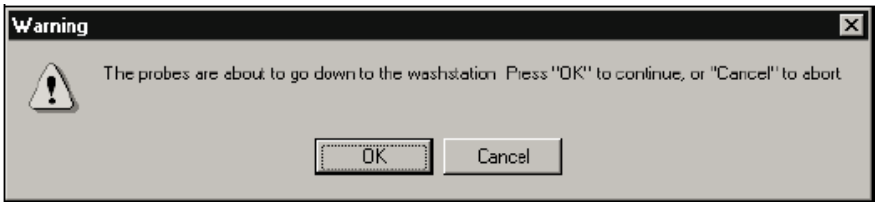
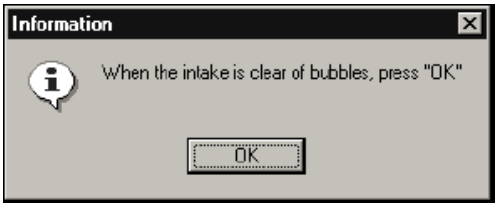


Figure 5.7 Information for a Span-8 Pod



NOTE Choosing **Home All Axes** homes all of the axes for all pods.

3 Choose **OK** on each **Warning** and **Information** after confirming that the actions have been addressed appropriately.

Moving a Pod to a Specific Deck Position

Use **Manual Control** to easily move the pod to a specific deck position. **Manual Control** moves the pod to the top of the Z-axis, then centers it over the selected position.

To move a pod to a specific deck position:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 In **Click on a position to move**, select the desired pod.

3 Click on the desired deck position on the **Manual Control** Deck Display (Figure 5.2).

Stopping a Pod

To stop a pod once a movement has started:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 In **Click on a position to move**, select the desired pod.

3 Choose **Stop**.

Viewing the Firmware Version

Get Version shows the current firmware version for installed devices, pods, and main firmware.

To view the firmware version:

1 Choose **Instrument > Manual Control. Manual Control** appears (Figure 5.2).

2 Choose **Get Version.** The firmware version displays in an Information dialog similar to Figure 5.8.

Figure 5.8 Firmware Version Information

3 To close **Information**, choose **OK.**

Accessing Advanced Manual Control

To access **Advanced Manual Control:**

1 Choose **Instrument > Manual Control. Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls.**

3 Select a device from the menu. **Advanced Manual Control** for the selected device appears.

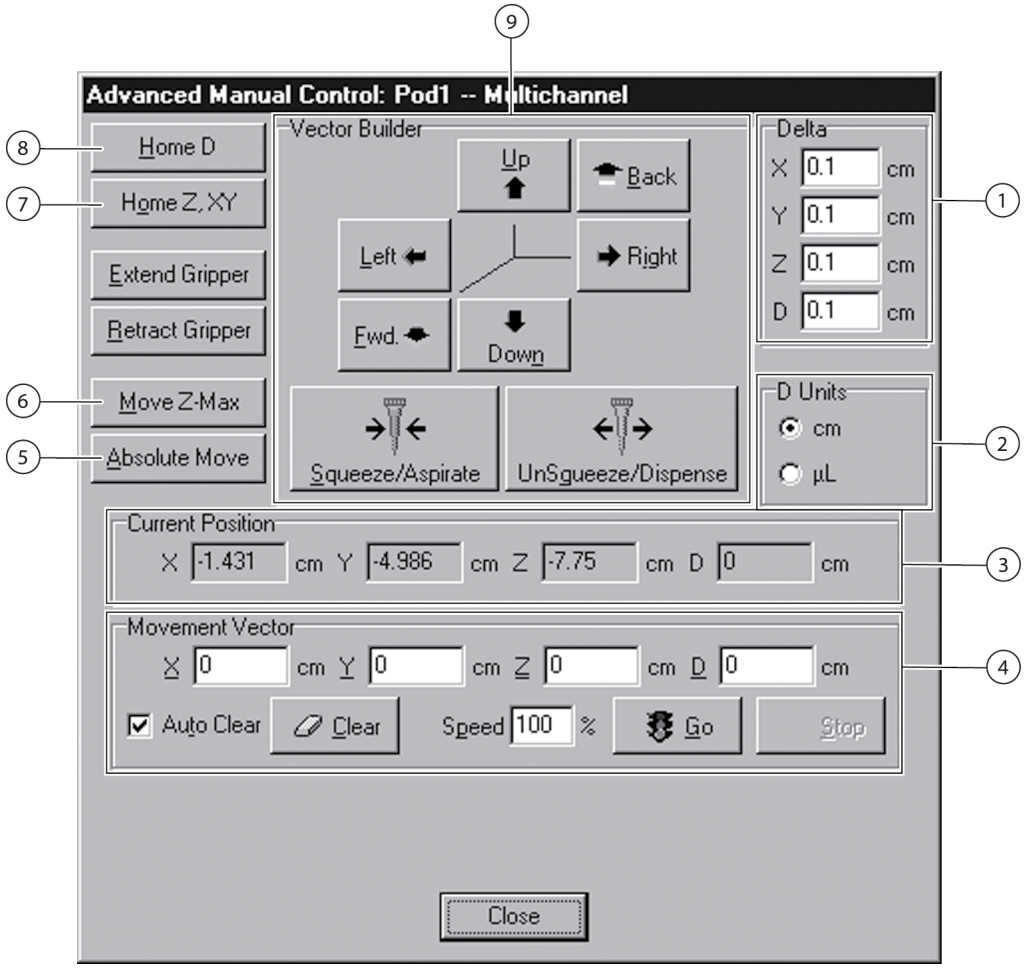
Using the Advanced Manual Control with the Multichannel Pod

Use **Advanced Manual Control** for the Multichannel Pod to:

- *Viewing the Current Position of a Multichannel Pod*
- *Moving a Multichannel Pod to a Safe Roving Height*
- *Performing Relative Moves for the Multichannel Pod*
- *Performing Absolute Moves for the Multichannel Pod*
- *Extending and Retracting the Gripper*

NOTE Many activities performed in **Advanced Manual Control** are the same for the Multichannel Pod and the Span-8; however, the dialogs are different and the buttons for performing these activities may be placed in different areas.

Figure 5.9 Overview Advanced Manual Control for a Multichannel Pod



1. **Delta**: Controls the amount of change applied to the Movement Vector when the Vector Builder is used.
2. **D Units**: Sets the D-axis units. Choose cm to set squeeze units and or µL to set aspirate units.
3. **Current Position**: Displays the current position of the selected pod.
4. **Movement Vector**: Indicates the amount the pod moves when Go is selected.
5. **Absolute Move**: Builds a vector to an absolute coordinate from the current coordinate.
6. **Move Z-Max**: Moves pod to highest configured height.
7. **Home Z, XY**: Moves Z and then X and Y axes to home positions.
8. **Home D**: Moves D-axis to the home position.
9. **Vector Builder**: Builds a movement vector — controls the direction and distance the pod moves. These choices change the values in the Movement Vector displayed below.

NOTE See Table 5.1 for further descriptions of fields.

Refer to specific subsections for instructional use.

Table 5.1 Advanced Manual Control Selection Areas for the Multichannel Pod

Area	Description
Absolute Move	Builds a vector to an absolute coordinate from the current coordinate.
Auto Clear	When checked, each time **Go** is selected the **Movement Vector** resets to the 0 vector (no movement). **NOTE** **Auto Clear** is on by default.
Clear	Sets movement vector entries to **0**.
Current Position	Current location of the pod (after the pod has been homed).
D Units	Sets the D-axis units. **NOTE** Choose cm to set squeeze units or µL to set aspirate units.
Delta	Sets the magnitude of change the **Vector Builder** applies to the **Movement Vector** for each axis.
Extend Gripper	Extends the grippers.
Home D	Moves D-axis to home position.
Home Z, XY	Moves Z- and then X- and Y-axes to home position.
Move Z-Max	Moves the pod to highest configured height.
Movement Vector	The amount of movement that occurs when **Go** is selected. Movement vectors are relative to the current position.
Retract Gripper	Retracts the grippers.
Speed	Sets the speed of the pod, with 0 percent meaning use current speed.
Vector Builder	Relative moves, which allow the pod to move from its current location to anywhere on the deck, are created using the **Vector Builder**. Each time a **Vector Builder** button is pressed, the **Movement Vector** is changed in the corresponding axis by the amount indicated in **Delta**. **Up** and **Down** move the pod in the Z-axis, **Left** and **Right** move the pod in the X-axis, and **Back** and **Fwd** move the pod in the Y-axis. **Squeeze**/**Aspirate** and **UnSqueeze**/**Dispense** move the head in the D-axis based upon the selection made in **D Units**.

Viewing the Current Position of a Multichannel Pod

The current position of a Multichannel Pod is displayed as four coordinates. Each axis coordinate is the distance from the home position.

X, Y, and Z are displayed in centimeters. The D-axis is displayed in either centimeters (cm) or microliters (µL). (Refer to the description for D Units in Table 5.1.)

To view the current position of a pod:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Multichannel Pod appears (Figure 5.9). The current position is shown in **Current Position**.

4 Choose **Close** to close **Advanced Manual Control**.

5 Choose **Exit** to close **Manual Control**.

Moving a Multichannel Pod to a Safe Roving Height

Use **Move Z-Max** in **Advanced Manual Control** for a selected Multichannel Pod to move it to its highest configured height. This helps to avoid collisions when moving the pod around the deck manually.

NOTE The possibility of collisions is not completely eliminated by this command; for example, if the gripper is extended and holding a microplate, and the pod is moved over a tip box on a tip loader, a collision could occur.

1 Choose **Instrument** > **Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Multichannel Pod appears (Figure 5.9).

4 Choose **Move Z-Max**.

5 Choose **Close** to close **Advanced Manual Control**.

6 Choose **Exit** to close **Manual Control**.

Performing Relative Moves for the Multichannel Pod

Relative moves allow the pod to move from its current location to anywhere on the deck. Relative moves are created in the **Vector Builder** using the **Delta** values, or the vector can be manually edited.

NOTE Use **Auto Clear** when the values in the **Movement Vector** fields must be reset to zero after the move is performed. Turn off **Auto Clear** to retain the values after the move has occurred. Choose **Clear** to set the values back to zero at any time.

To move a pod relative to its current position:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2)

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Multichannel Pod appears (Figure 5.9).

4 Choose **Clear** to change the **Movement Vector** values to **0**.

5 Enter the desired **X**, **Y**, **Z**, and **D** values in **Movement Vector**.

OR

Set the **Delta** values as desired (refer to *Setting Delta Values for the Multichannel Pod*) and click the appropriate buttons on **Vector Builder** (refer to *Understanding and Using the Vector Builder for the Multichannel Pod*), until the desired values appear in **Movement Vector**.

NOTE Hold the button down to quickly add **Delta** value to the **Movement Vector**.

NOTE Positive values move the pod to the right (X), toward the front of the deck (Y), up (Z) and squeeze/aspirate (D). Negative values move the pod to the left (X), towards the back of the deck (Y), down (Z) and unsqueeze/dispense (D).

NOTE Minimum and Maximum X, Y, Z, and D values displayed in **Hardware Setup** indicate how far the pod is able to move. These values are also displayed as a tool tip when hovering over the fields in **Movement Vectors**.

6 Enter a value in **Speed** to specify the percent of the pod's maximum speed.

7 Choose **Go**. The pod moves from its current position to a new position by the values displayed in the **Movement Vector**. The new position is displayed in **Current Position**.

8 Choose **Close** to close **Advanced Manual Control**.

9 Choose **Exit** to close **Manual Control**.

Setting Delta Values for the Multichannel Pod

A **Delta** value is the amount of change in an axis that is applied to the **Movement Vector** when a button in the **Vector Builder** is pressed. For example, if the Delta value for **X** is **3**, each time **Right** is clicked in the Vector Builder, 3 cm is added to the X-axis of the **Movement Vector**.

NOTE The move does not occur until **Go** is selected in the **Movement Vector** area of **Advanced Manual Control**.

To set **Delta** values:

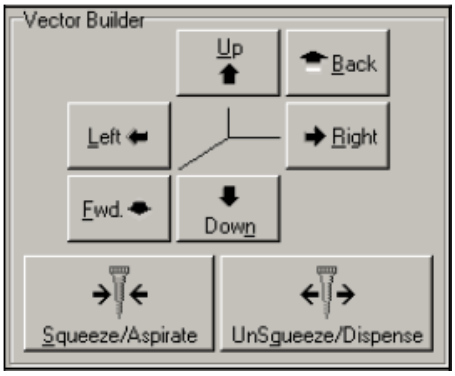
1. Choose **Instrument > Manual Control**. **Manual Control** appears.
2. Choose **Advanced Controls**.
3. Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Multichannel Pod appears (Figure 5.9).
4. Enter a value in **X**, **Y**, **Z**, and **D** to set the **Delta** value for each axis.
5. In **D Units**, select **cm** or **µL**.
6. Choose **Close** to close **Advanced Manual Control** for the selected pod.
7. Choose **Exit** to close **Manual Control**.

Understanding and Using the Vector Builder for the Multichannel Pod

The use of **Advanced Manual Control** for the Multichannel Pod centers around the building and applying of movement vectors. A movement vector simply indicates the magnitude and direction of motion applied to the pod.

Use the **Vector Builder** buttons (Figure 5.10) to add positive or negative values to the **Movement Vector** for the pod. Each time a **Vector Builder** button is pressed, the Delta value for that axis is added or subtracted from the appropriate **Movement Vector** for the pod. With the point of reference at the front and center of the unit, positive and negative values for the pod are as follows:

Figure 5.10 Vector Builder



- **Right**: Positive value X = right motion of the pod
- **Fwd**: Positive value Y = forward motion of the pod
- **Up**: Positive value Z = up motion of the probes
- **Squeeze/Aspirate**: Positive value D = squeezing of the gripper or aspirating motion of the probes
- **Widen**: Positive Span = widening motion between the probes
- **Left**: Negative value X = left motion of the pod
- **Back**: Negative value Y = back motion of the pod
- **Down**: Negative value Z = down motion of the probes
- **Unsqueeze/Dispense**: Negative value D = unsqueezing of the gripper or dispensing motion of the probes
- **Narrow**: Negative Span = narrowing motion between the probes

Performing Absolute Moves for the Multichannel Pod

Absolute Move allows the pod to move to a specific coordinate position in the workspace of the instrument. Use **Absolute Move** when the coordinates of the desired position are known.

NOTE When an **Absolute Move** is entered, the values displayed in **Movement Vector** reflect the relative move required to physically move the pod to the desired position. Make sure the physical location of the pod is not changed between the time the vector is built and the time the **Go** button is pressed.

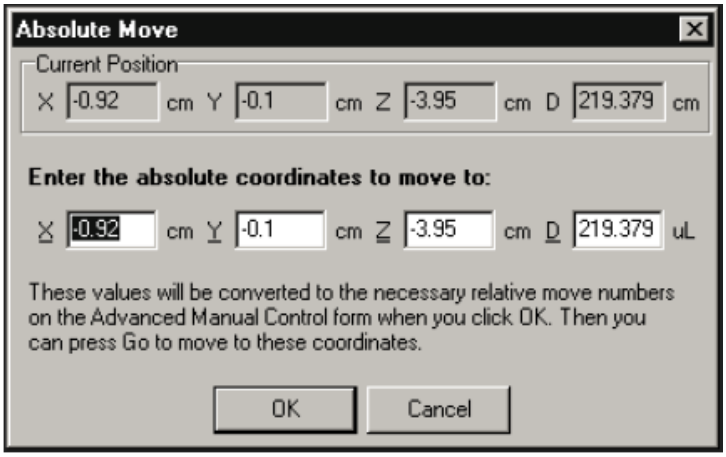
1 Choose **Instrument > Manual Control. Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls.**

3 Select **Pod1** or **Pod2. Advanced Manual Control** for the selected Multichannel Pod appears (Figure 5.9).

4 Choose **Absolute Move**. **Absolute Move** appears (Figure 5.11).

Figure 5.11 Enter Absolute Move Coordinates



5 Enter the **X**, **Y**, **Z**, and **D** values for the desired position.

NOTE Minimum and Maximum X, Y, Z, and D values displayed in **Hardware Setup** indicate how far the pod is able to move. These values are also displayed as a tool tip when hovering over the fields in **Movement Vectors**.

6 Choose **OK**. The **Movement Vector** changes to reflect the necessary relative move.

7 Enter a value in **Speed** to specify the percent of the pod's maximum speed to use for the move.

8 Choose **Go**. The pod moves from its current position to a specified absolute position. The new position is displayed in **Current Position**.

9 Choose **Close** to close **Advanced Manual Control**.

10 Choose **Exit** to close **Manual Control**.

Extending and Retracting the Gripper

Use **Advanced Manual Control** to extend or retract the gripper when changing the head on the pod.

⚠ CAUTION

Select Move Z-Max to move the pod to its highest point before extending the gripper. To avoid breaking labware or bending the gripper fingers, make sure the gripper will not hit any labware when extended.

⚠ CAUTION

Do not retract gripper when it is holding labware.

From **Advanced Manual Control** for the selected Multichannel Pod:

- Choose **Extend Gripper** to extend the gripper.
- Choose **Retract Gripper** to retract the gripper.

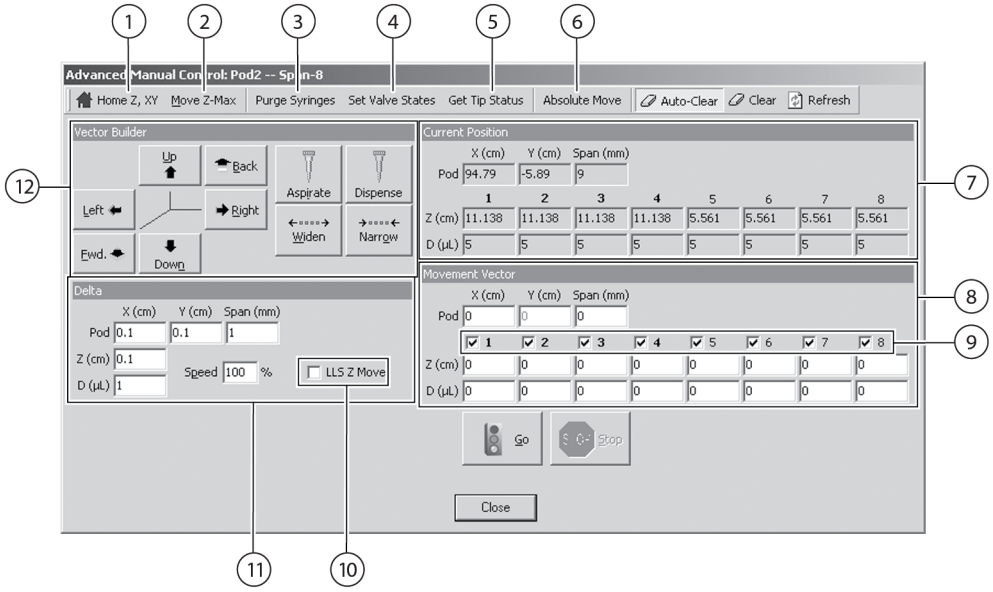
Using Advanced Manual Control with the Span-8 Pod

Use **Advanced Manual Control** for the Span-8 Pod to:

- *Viewing the Current Position of a Span-8 Pod*
- *Moving a Span-8 Pod to a Safe Roving Height*
- *Performing Relative Moves for the Span-8 Pod*
- *Performing Absolute Moves for the Multichannel Pod*
- *Setting Valve States*
- *Verifying Liquid Level Sensing*
- *Purging Air from the Syringes and Tubing*

NOTE Many activities performed in **Advanced Manual Control** are the same for the Multichannel Pod and the Span-8 Pod; however, the dialogs are different and the buttons for performing these activities may be placed in different areas.

Figure 5.12 Overview Advanced Manual Control for a Span-8



1. **Home Z, XY**: Moves Z- and then X- and Y-axes to the home positions.
2. **Move Z-Max**: Moves pod to highest configured height.
3. **Purge Syringes**: Removes air from the tubing and syringes.
4. **Set Value States**: Sets valves on the pump to allow system fluid to input, output, or bypass the syringes.
5. **Get Tip Status**: Indicates which probes have tips.
6. **Absolute Move**: Builds a vector to an absolute coordinate from the current coordinate.
7. **Current Position**: Displays the current position of the selected pod.
8. **Movement Vector**: Indicates the amount the pod and/or probes move when Go is selected.
9. Check marks select probes that descend when **Go** is selected.
10. **LLS Z Move**: Verifies liquid level sensing.
11. **Delta**: Controls the amount of change applied to the Movement Vector when the Vector Builder is used.
12. **Vector Builder**: Used to build a movement vector — controls the direction and amount the pod and/or probes move. These choices change the values in the Movement Vector.

NOTE See Table 5.2 for further descriptions.

Table 5.2 Advanced Manual Control Selection Areas for the Span-8 Pod

Area	Description
Absolute Move	Builds a vector to an absolute coordinate from the current coordinate.
Active Axes	Check marks disable any probes that should not descend when **Go** is clicked.
Auto Clear	When checked, each time **Go** is selected the **Movement Vector** resets to the **0** vector (no movement). **NOTE** **Auto Clear** is on by default.
Clear	Sets movement vector entries to 0.
Current Position	Current location of the pod (after the pod has been homed).
Delta	Sets the magnitude of change the **Vector Builder** applies to the movement vector for each axis.

Table 5.2 Advanced Manual Control Selection Areas for the Span-8 Pod

Area	Description
Get Tip Status	Indicates which probes have tips.
Home Z, XY	Moves **Z**, then **X** and **Y** to the home positions.
LLS Z Move	Verifies liquid level sensing by allowing probes to descend and then stop once they hit liquid.
Move Z-Max	Moves pod to highest configured height.
Movement Vector	The amount of movement that occurs when **Go** is selected. Movement vectors are relative to the current position.
Purge Syringes	Removes air from the tubing and syringes and ensures lines are filled with system fluid.
Refresh	Updates the current position of the pod after it has been physically moved without using **Manual Control**.
Set Values States	Sets valves on the pumps to allow system fluid to fill, empty, or bypass the syringes.
Speed	Sets the speed of the pod, with 0 percent meaning use current speed.
Vector Builder	Relative moves are created using the **Vector Builder**. Each time a **Vector Builder** button is pressed, the **Movement Vector** is changed in the corresponding axis by the amount indicated in the **Delta** box. **Up** and **Down** move the pod in the Z-axis, **Left** and **Right** move the pod in the X- axis, and **Back** and **Fwd** move the pod in the Y-axis. **Widen**/**Narrow** change the Span of the probes. **Aspirate**/**Dispense** move the probes on the Span-8 Pod in the D-axis based upon the selection made in **D Units**.

Viewing the Current Position of a Span-8 Pod

The current position of a Span-8 Pod is displayed as five coordinates. The X,Y, Z, and D axes coordinates are the distances from the home position. The Span is the distance between the probes.

X, Y, and Z are displayed in centimeters; the D-axis is displayed in microliters; and the Span is displayed in millimeters.

To view the current position of a pod:

1. Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2. Choose **Advanced Controls**.

3. Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Span-8 Pod appears (Figure 5.12). The current position is shown in **Current Position**.

4. Choose **Close** to close **Advanced Manual Control**.

5 Choose **Exit** to close **Manual Control**.

Moving a Span-8 Pod to a Safe Roving Height

Use **Move Z-Max** in **Advanced Manual Control** for a selected Span-8 Pod to move it to its highest configured height. This helps to avoid collisions when moving the pod around the deck manually.

NOTE The possibility of collisions is not completely eliminated by **Move Z-Max**.

1 Choose **Instrument** > **Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Span-8 Pod appears (Figure 5.12).

4 Choose **Move Z-Max**.

5 Choose **Close** to close **Advanced Manual Control** for the selected pod.

6 Choose **Exit** to close **Manual Control**.

Performing Relative Moves for the Span-8 Pod

Relative moves allow the pod to move from its current location to anywhere on the deck. Relative moves are created in the **Vector Builder** using the **Delta** values, or the vector can be manually edited.

NOTE Use **Auto Clear** when the values in **Movement Vector** must be reset to zero after the move is performed. Turn off **Auto Clear** to retain the values after the move has occurred. Choose **Clear** to set the values back to zero at any time.

To move a pod relative to its current position:

1 Choose **Instrument** > **Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Span-8 Pod appears (Figure 5.12).

4 Choose **Clear** to change the **Movement Vector** values to **0**.

5 Enter the desired **X**, **Y**, **Z**, **D**, and **Span** values in **Movement Vector**.

OR

Set the **Delta** values as desired (refer to *Setting Delta Values for the Multichannel Pod*) and click the appropriate buttons on **Vector Builder** (refer to *Understanding and Using the Vector Builder for the Multichannel Pod*), until the desired values appear in **Movement Vector**.

NOTE Hold the button down to quickly add Delta value to the **Movement Vector**.

NOTE Positive values move the pod to the right (X) and toward the front of the deck (Y). Positive values also move the probes up (Z), aspirate (D), and widen (Span) the distance between the probes. Negative values move the pod to the left (X) and towards the back of the deck (Y). Negative values also move the probes down (Z), dispense (D), and narrow (Span) the distance between the probes.

NOTE Minimum and Maximum X, Y, Z, and D values displayed in the **Hardware Setup** indicate how far the pod is able to move. These values are also displayed as a tool tip when hovering over the fields in **Movement Vectors**.

6 Enter a value in **Speed** to specify the percent of the pod's maximum speed.

7 Choose **Go**. The pod moves from its current position to a new position by the values displayed in the **Movement Vector**. The new position is displayed in **Current Position**.

8 Choose **Close** to close **Advanced Manual Control**.

9 Choose **Exit** to close **Manual Control**.

Setting Delta Values for the Span-8 Pod

A **Delta** value is the amount of change applied to the **Movement Vector** when a button in the **Vector Builder** is pressed. For example, if the Delta value for **X** is **3**, each time **Right** is clicked in the **Vector Builder**, 3 cm is added to the X-axis of the Movement Vector.

NOTE The move does not occur until **Go** is selected in **Movement Vector** of **Advanced Manual Control**.

To set Delta values:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Span-8 Pod appears (Figure 5.12).

4 Enter a value in **X**, **Y**, **Z**, **D**, and **Span** to set the **Delta** value for each axis.

5 Choose **Close** to close **Advanced Manual Control**.

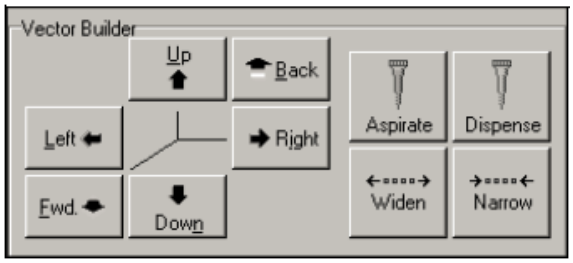
6 Choose **Exit** to close **Manual Control**.

Understanding and Using the Vector Builder for the Span-8 Pod

The use of **Advanced Manual Control** for the Span-8 Pod centers around building and applying movement vectors using the **Vector Builder**. A movement vector indicates the magnitude and direction of motion applied to the pod or probes.

Use the **Vector Builder** buttons (Figure 5.13) to add positive or negative values to the **Movement Vector** for the pod. Each time a **Vector Builder** button is pressed, the **Delta** value for that axis is added or subtracted from the appropriate **Movement Vector** for the pod. With the point of reference at the front and center of the unit, positive and negative values for the pod are as follows:

Figure 5.13 Vector Builder for the Span-8 Pod



- **Positive value X**: right motion of the pod
- **Positive value Y**: forward motion of the pod
- **Positive value Z**: up motion of the probes
- **Positive value D**: aspirating motion of the probes
- **Positive Span**: widening motion between the probes
- **Negative value X**: left motion of the pod
- **Negative value Y**: back motion of the pod
- **Negative value Z**: down motion of the probes
- **Negative value D**: dispensing motion of the probes
- **Negative Span**: narrowing motion between the probes

Performing Absolute Moves for the Span-8 Pod

Absolute Move allows the pod to move to a specific coordinate position in the workspace of the instrument. Use **Absolute Move** when the coordinates of the desired position are known.

NOTE When an **Absolute Move** is entered, the values displayed in **Movement Vector** reflect the relative move required to physically move the pod to the desired position. Make sure the physical location of the pod is not changed between the time the vector is built and the time the **Go** button is pressed.

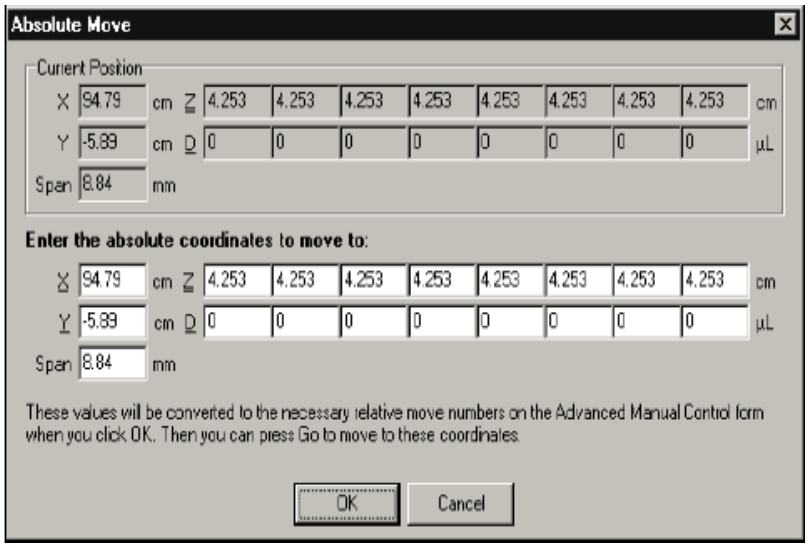
1 Choose **Instrument > Manual Control. Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2. Advanced Manual Control** for the selected Span-8 Pod appears (Figure 5.12).

4 Choose **Absolute Move. Absolute Move** appears (Figure 5.14).

Figure 5.14 Absolute Move for Span-8 Pod



5 Enter the desired **X**, **Y**, **Z**, **D**, and **Span** values.

NOTE Minimum and Maximum X, Y, Z, and D values displayed in **Hardware Setup** indicate how far the pod is able to move. These values are also displayed as a tool tip when hovering over the fields in **Movement Vectors**.

6 Choose **OK**. The Movement Vector changes to reflect the necessary relative move.

7 Enter a value in **Speed** to specify the percent of the pod's maximum speed to use for the move.

8 Choose **Go**. The pod moves from its current position to a specified absolute position. The new position is displayed in **Current Position**.

9 Choose **Close** to close **Advanced Manual Control**.

10 Choose **Exit** to close **Manual Control**.

Setting Valve States

The valves on the pumps may be set to allow system fluid to flow:

- To and from the syringe with the supply container as the source/destination of the fluid.
- To and from the syringe with tip as the source/destination of the fluid.
- Through the valve without activating (bypassing) the syringe.

To set the valves on the probes:

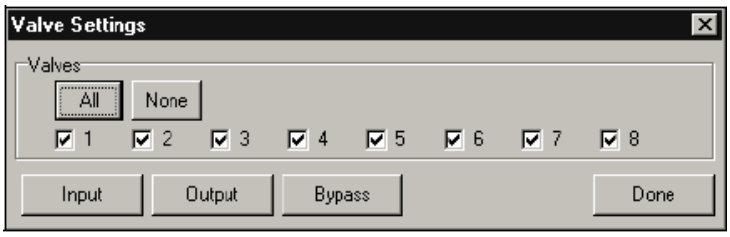
1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Span-8 Pod appears.

4 Choose **Set Valve States**. **Valve Setter** appears (Figure 5.15).

Figure 5.15 Valve Settings



5 Select the valves by placing a check mark next to the valve(s) to be set.

NOTE Choosing **All** selects all of the valves; choosing **None** selects none.

6 Choose **Input** to open the valve and allow system fluid to flow to and from the syringe with the supply container as the source/destination of the fluid.

OR

Choose **Output** to open the valve and allow system fluid to flow to and from the syringe with the tip as the source/destination of the fluid.

OR

Choose **Bypass** to open the valve and allow system fluid to flow through the valve without activating (bypassing) the syringe.

7 Choose **Done** after the valves have been set as desired. **Valve Setter** closes.

8 Choose **Close** to close **Advanced Manual Control**.

9 Choose **Exit** to close **Manual Control**.

Verifying Liquid Level Sensing

It may be useful to verify the operation of liquid level sensing. Use **LLS Z Move** to allow probes to descend and then stop once they hit liquid.

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Span-8 Pod appears.

4 Check **LLS Z Move**.

5 In **Movement Vector**, enter the maximum **Z** distance each probe should descend.

NOTE Use **Active Axes** (Figure 5.12) to disable any probes that should not descend. Check marks next to the probe number indicate the probe will descend when **Go** is chosen. Choosing **All** selects all the probes; choosing **None** selects none of the probes.

6 Choose **Go**.

7 Choose **Close** to close **Advanced Manual Control**.

8 Choose **Exit** to close **Manual Control**.

Purging Air from the Syringes and Tubing

To accurately transfer liquid using a Span-8 Pod, air must be purged from the syringes and tubing.

NOTE It is necessary to purge air from the syringes and tubing before running all methods.

To purge air from the syringes and tubing:

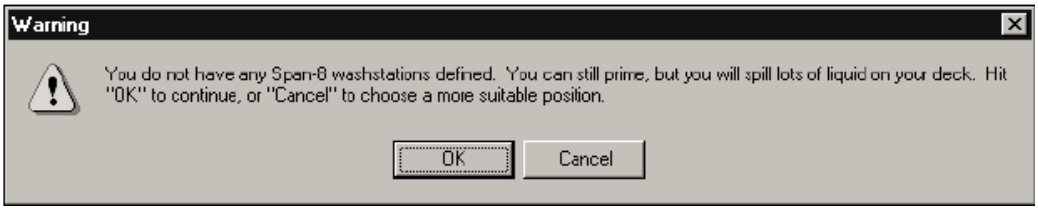
1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select **Pod1** or **Pod2**. **Advanced Manual Control** for the selected Span-8 Pod appears.

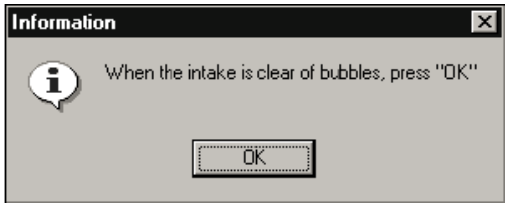
4 Choose **Purge Syringes**. The following warning appears if a Span-8 Tip Wash Station is not defined (Figure 5.16).

Figure 5.16 Warning to Address if a Span-8 Tip Wash ALP is Not Defined



5 If necessary, take the appropriate action to address the warning and choose **OK**. **Information** appears (Figure 5.17).

Figure 5.17 Information



6 Follow the instructions displayed in Information. When completed choose **OK**. The air is purged from the syringes and tubing.

7 Choose **Close** to close **Advanced Manual Control**.

8 Choose **Exit** to close **Manual Control**.

Using Advanced Manual Control to Manually Control Speed Pumps

Use **Advanced Manual Control** for a selected Speed Pump to:

- Turn on the Speed Pump.
- Turn off the Speed Pump.

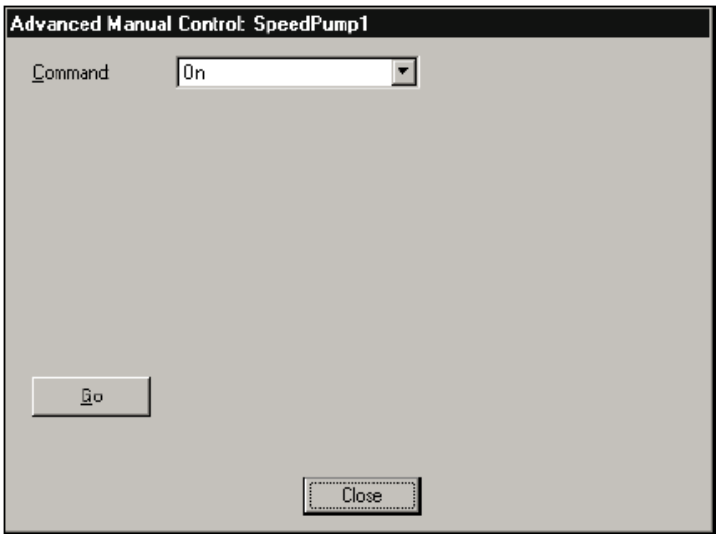
To turn on a Speed Pump:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select the desired **Speed Pump**. **Advanced Manual Control** for the selected Speed Pump appears (Figure 5.18).

Figure 5.18 Advanced Manual Control for a Selected Speed Pump



4 From **Command**, choose **On**.

5 Choose **Go**.

6 Choose **Close** to close **Advanced Manual Control**.

7 Choose **Exit** to close **Manual Control**.

Turn off the Speed Pump:

1 Choose **Instrument > Manual Control**. **Manual Control** appears (Figure 5.2).

2 Choose **Advanced Controls**.

3 Select the desired **Speed Pump**. **Advanced Manual Control** for the selected Speed Pump appears (Figure 5.18).

4 From **Command**, choose **Off**.

5 Choose **Go**.

6 Choose **Close** to close **Advanced Manual Control**.

7 Choose **Exit** to close **Manual Control**.

APPENDIX A

Specifications

System Specifications

Table A.1 System Specifications

Item	Description
Environment	• Indoor use only
Power Requirements	• **US**: 100-120VAC, 60Hz • **Europe**: 200-240VAC, 50Hz
Pneumatic Requirements	**Air Pressure**: • 40 - 100 psi of compressed air — • 275 - 690 kPa of compressed air **Air Flow**: • 2.25 cfm @ 40 psi — 0.064 m3/min @ 275 kPa
System Fluid Requirements	• De-ionized or distilled water • Ambient operating temperature is 59-86°F (15-30°C). • System Fluid should be degassed for 24 hours prior to use.
Dimensions — Base Unit	• **Wth Canopy**: 152 cm (L) x 81.28 cm (W) x 139.7 cm (H) • **Without Caonpy**: 152 cm. (L) x 81.28 cm (W) x 109.22 cm (H)
Weight	• 250 lbs., with one bridge, one pod, and a canopy • 330 lbs., with two bridges, two pods, and a canopy
Ambient Operating Temperature	• 5-30°C (41-86°F)
Humidity Restrictions	• <85% (non-condensing) @ 30°C (86°F)
Altitude Restrictions	• up to 2000m (6562ft)
Installation Category	• Category II
Pollution Degree	• 2
Sound Pressure Level	• Maximum sound pressure: 79 dB • Maximum sound pressure at 1 meter: 76 dB
Fuses	• **US**: 250VAC, 5 amp, 5x20 mm, SLO-BLO, UL recognized, CSA certified • **Europe**: 250VAC, 5 amp, 5x20 mm, SLO-BLO, CENELEC approved
Communications to Host	• RS-232 port

Table A.1 System Specifications

Item	Description
Communications to Tip Loader	• CAN
Communications to Active ALPs	• CAN
Biomek Controller Host PC	**The following specifications are the minimum requirements needed for the IBM PC.** • CPU: Pentium IV, 2 GHz • RAM: 512 MB • Hard Drive: 13.5 GB • CD ROM Drive: 24X • Monitor: 17", Super VGA, 1024 x 768, small fonts, w/ 16-bit color • Operating System: Windows XP with Service Pack 1a • Other Software: SQL Server Personal Edition

APPENDIX B

Using a Stacker Carousel

Overview

The Stacker Carousel (Figure B.1) is integrated into the system to dispense and load labware onto the Biomek FX deck. It provides expanded labware capacity and increases walk-away automation in genetic analysis and drug discovery applications.

Each carousel contains locations for four stackers. A shuttle is incorporated for transporting labware to and from the carousel.

NOTE For a more comprehensive description of the Stacker Carousel, its components, functionality, and operations, refer to the *Stacker Carousel User's Manual* (PN 148598).

A bar code reader may be mounted to the Stacker Carousel to scan any one of the four sides of a microplate.

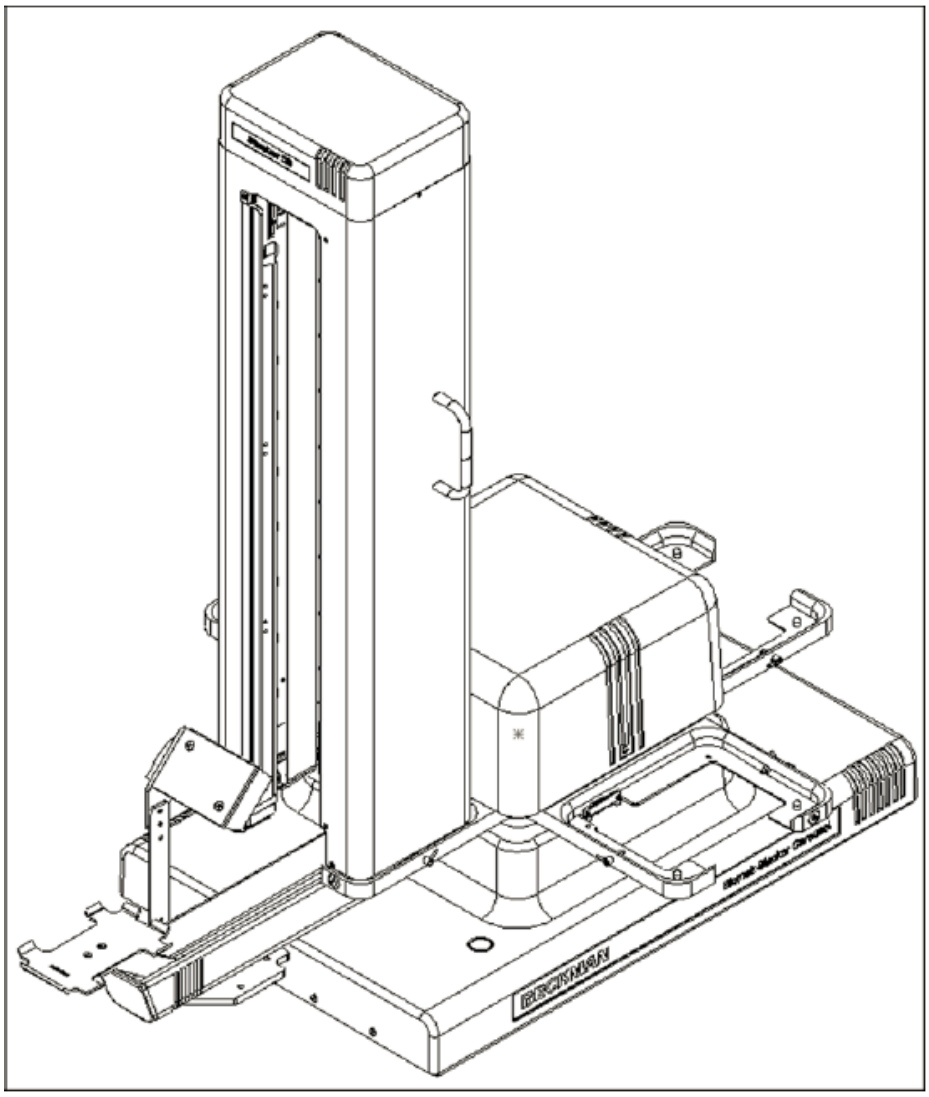
NOTE For maximum scanning reliability, it is recommended that labels be applied to the narrow sides of the microplate. This label orientation accommodates scanning of skewed labels and requires less adjustment of the bar code reader position.

The sections in this appendix include:

Integrating the Stacker Carousel

NOTE Install only in conjunction with the Biomek FX model incorporating Plexiglas safety shields along the sides of the instrument in lieu of side light curtains.

Figure B.1 Stacker Carousel



Integrating the Stacker Carousel into the system requires:

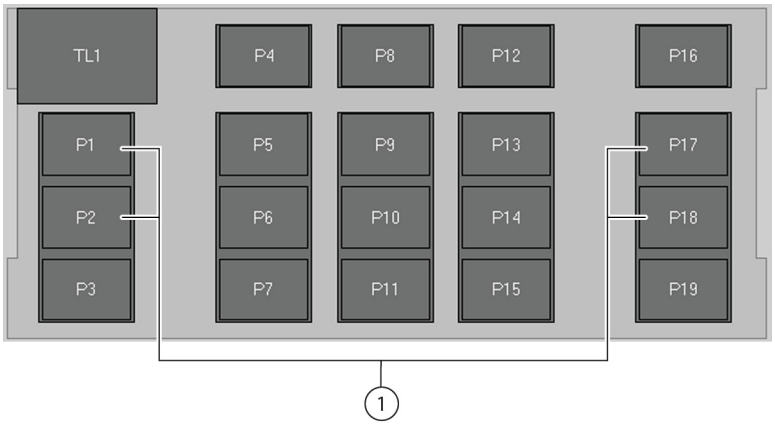
- *Positioning the Stacker Carousel on the Deck*
- *Mounting the Stacker Carousel*
- *Attaching the Side Shield*
- *Operating the Stacker Carousel*

Positioning the Stacker Carousel on the Deck

The Stacker Carousel shuttle can be positioned using the following deck positions (Figure B.2):

- Left side — Position 1 or 2
- Right side — Position 17 or 18

Figure B.2 Stacker Shuttle Position

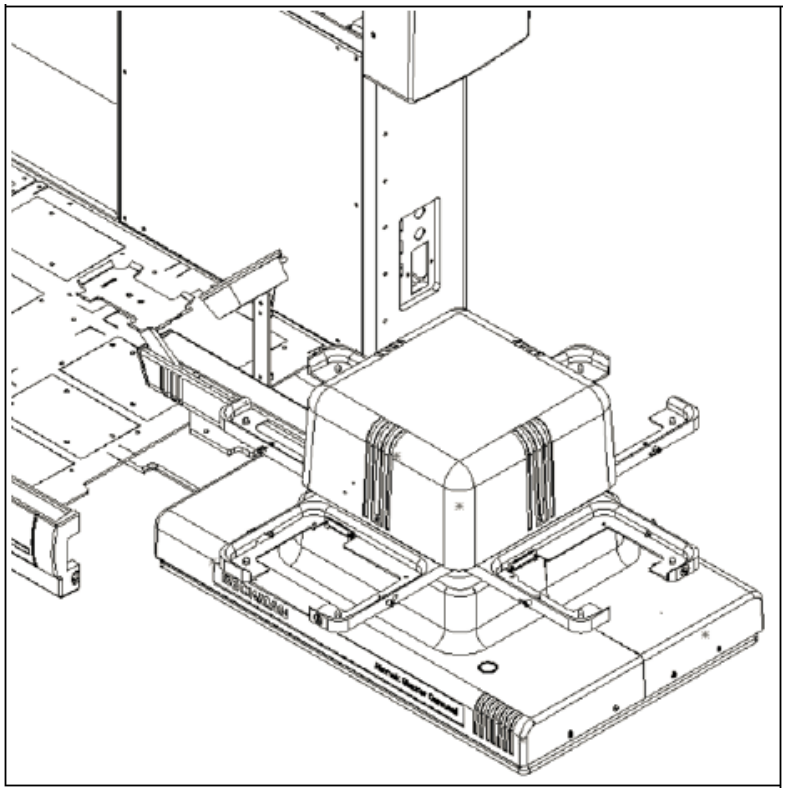


1. Mount Stacker Carousel on P1, P2, P17, or P18.

NOTE Do not pipette liquid into labware that is sitting on the Stacker Carousel shuttle.

To position the Stacker Carousel, position the Stacker Carousel outside the Biomek FX deck (Figure B.3).

Figure B.3 Stacker Carouse Integration

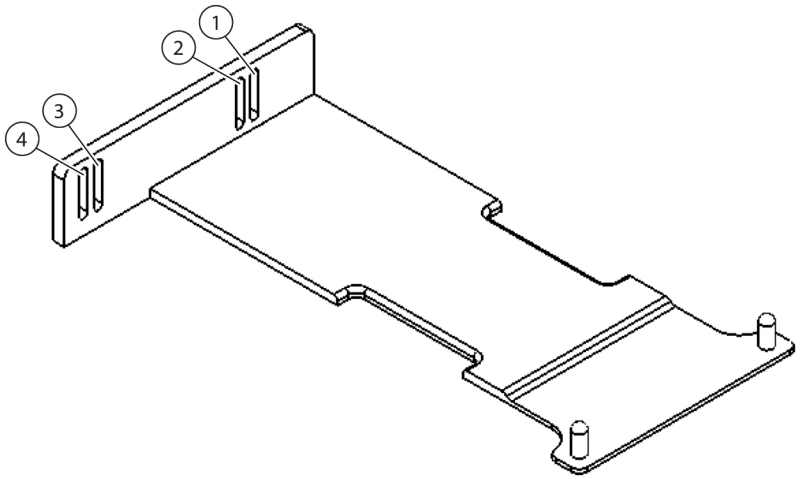


Mounting the Stacker Carousel

Mounting the Stacker Carousel to the Biomek FX requires attaching an upper alignment bracket, a right or left horizontal alignment bracket, and a riser plate. Then the Stacker Carousel is positioned and leveled.

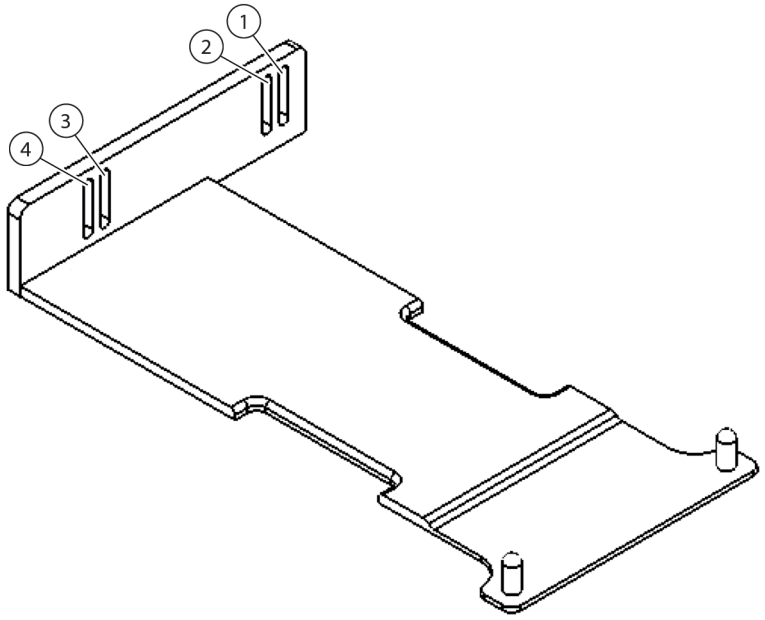
NOTE There is a specific horizontal alignment bracket for mounting the Stacker Carousel on the right side of the Biomek FX instrument (Figure B.4) and a specific horizontal alignment bracket for mounting on the left side of the instrument (Figure B.5).

Figure B.4 Right Horizontal Alignment Bracket



1. Slot for P17 Mounting
2. Slot for P18 Mounting
3. Slot for P17 Mounting
4. Slot for P18 Mounting

Figure B.5 Left Horizontal Alignment Bracket



1. Slot for P2 Mounting
2. Slot for P1 Mounting
3. Slot for P2 Mounting
4. Slot for P1 Mounting

Also included with the alignment bracket is the following mounting hardware:

- Two 1/4-20 x 1” long stainless steel socket-head cap screws
- Two 1/4” flat washers
- Two 1/4” lock washers
- Upper alignment bracket
- Two 1/4-20 x 1” long stainless steel flat-head cap screws

Attaching Alignment Brackets

Attach the upper alignment bracket, the right or left alignment bracket, and the riser plate to prepare for positioning and leveling the Stacker Carousel as follows:

1 Choose the right or left side of the Biomek FX instrument on which the Stacker Carousel will be located.

2 Choose the deck position the shuttle will occupy (Figure B.2).

NOTE Position P1 or P17 (back mount) or Position P2 or P18 (front mount).

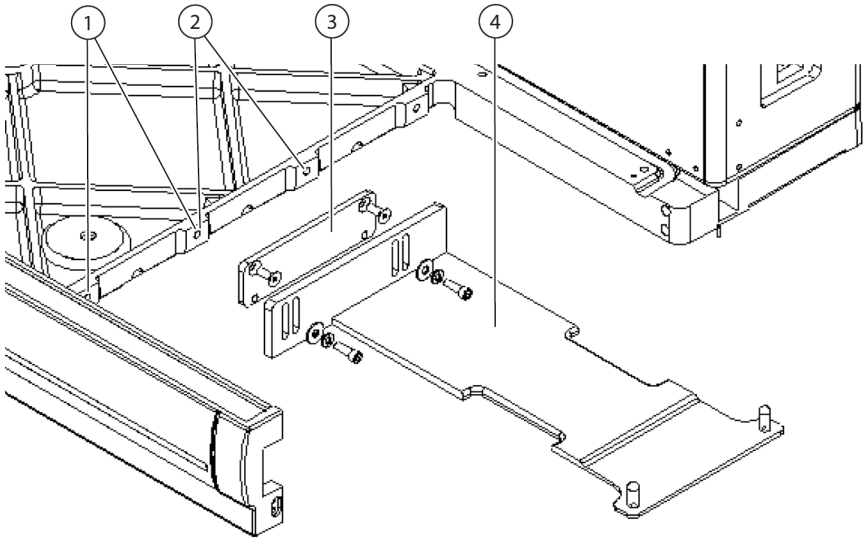
3 Remove the deck plate from the Biomek FX deck.

4 Attach the upper alignment bracket to the Biomek FX deck in the appropriate base mounting holes for front or back mounting (Figure B.6).

5 Using the appropriate mounting slots (Figure B.4 or Figure B.5), attach the right or left horizontal alignment bracket to the upper alignment bracket.

6 Adjust the height of the horizontal alignment bracket so that the bottom surface of the bracket is sitting flush on the surface on which the Biomek FX is mounted, then tighten the fasteners (Figure B.6).

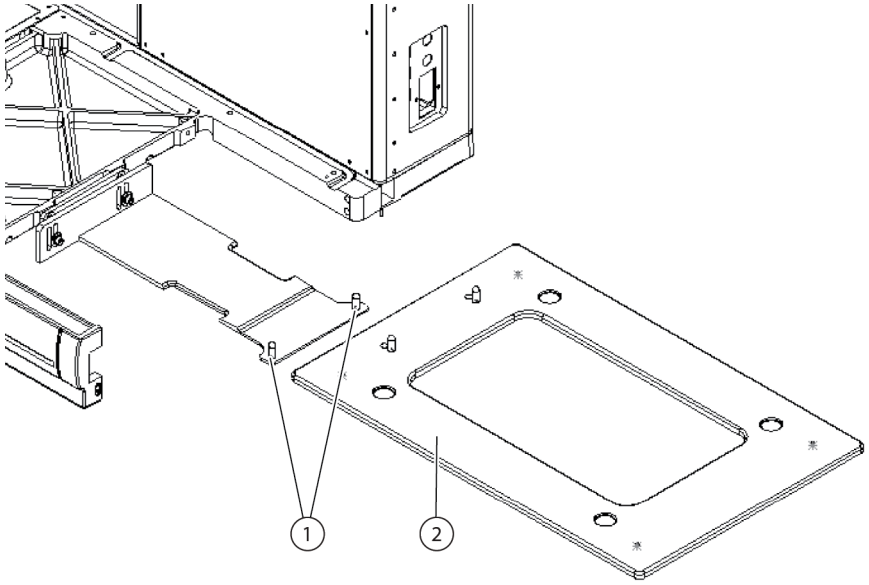
Figure B.6 Attach Alignment Bracket



1. Use front two base mounting holes for front mount.
2. Use middle two base mounting holes for back mount.
3. Upper Alignment Bracket
4. Horizontal Alignment Bracket

7 Place the riser plate over the alignment pins of the horizontal alignment bracket (Figure B.7).

Figure B.7 Attaching Riser Plate



1. Riser alignment pins
2. Riser plate

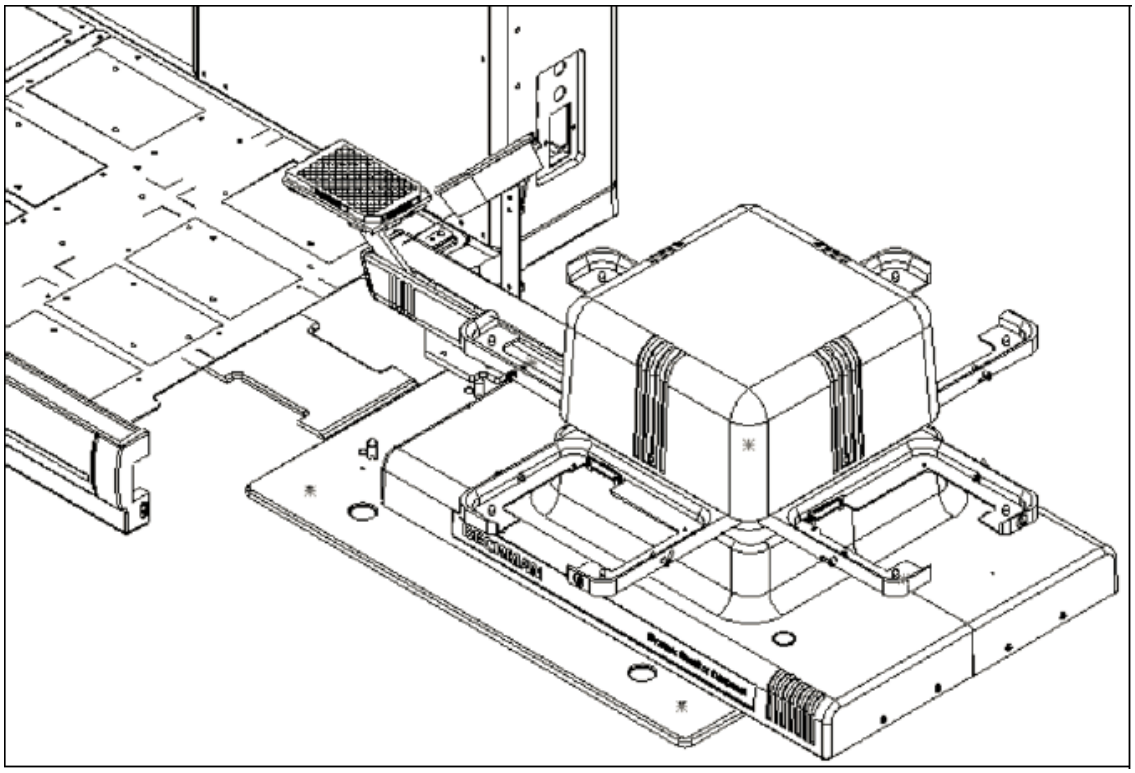
8 Verify that the riser plate is set firmly on the Biomek FX alignment bracket and the table.

Attaching the Stacker Carousel

Attach the stacker as follows:

1 Place the stacker onto the riser plate over the riser alignment pins (Figure B.8).

Figure B.8 Stacker Attachment



2 Level the stacker.

3 Adjust the height of the stacker until the distance between the Biomek FX deck surface and the top of the flat surface of the stacker shuttle measures 5 in. + 1/8 in.

NOTE If necessary, refer to the *Stacker Carousel User's Manual* (PN 148598), for instructions on how to adjust the height of the stacker.

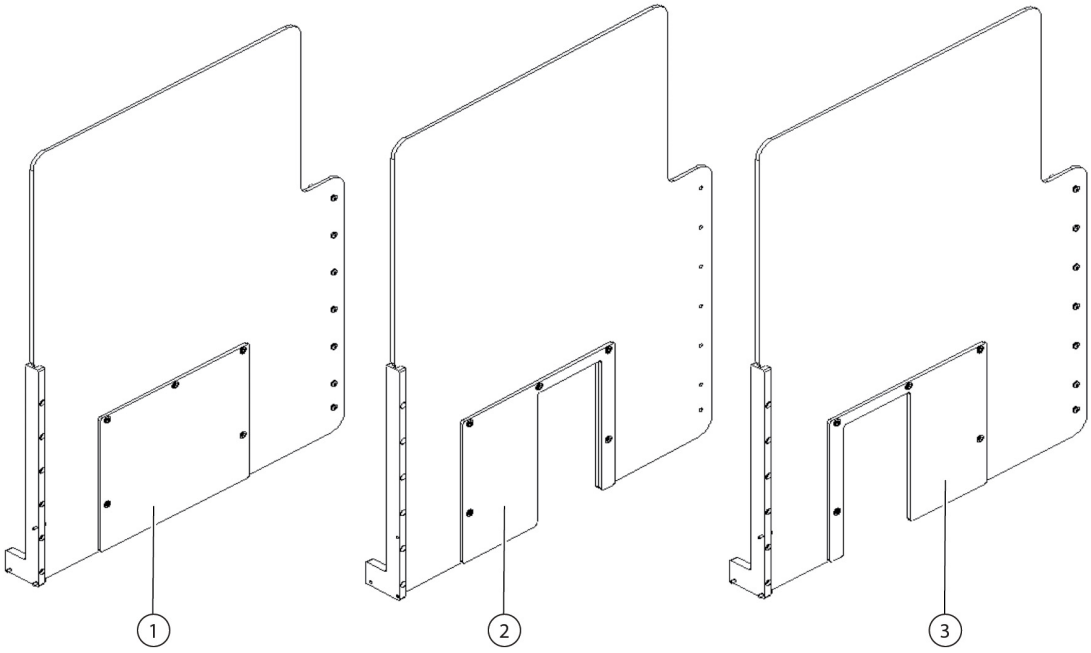
Attaching the Side Shield

Attach the side shield as follows:

1 Attach the cutout blank and Plexiglas side shield in the appropriate orientation for the shuttle to access the cutout without obstruction (Figure B.9 through Figure B.12).

NOTE Use the same cutout blank to form either the rear or front cutout orientations by turning the blank 180° in the appropriate direction.

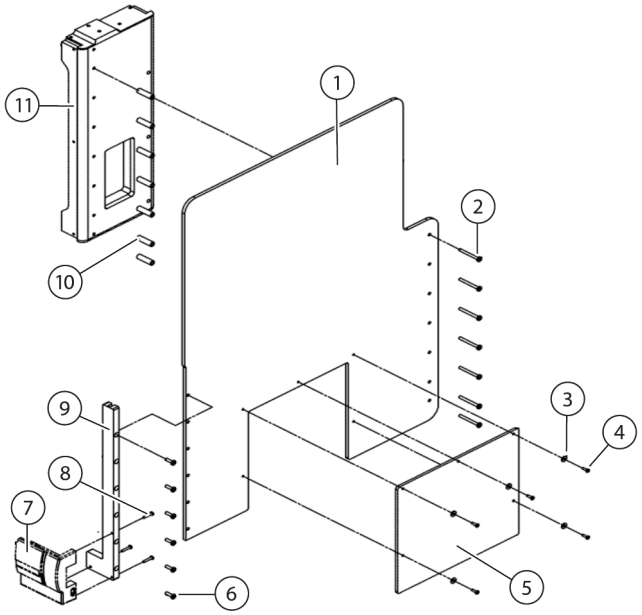
Figure B.9 Plexiglas Side Shield Cutout Blank Orientations



1. **Right Side Shield with Cutout Blanked**
2. **Right Side Shield with Rear Cutout Blank** — Use for Deck Position P1 or P17
3. **Right Side Shield with Front Cutout Blank** — Use for Deck Position P2 or P18

2 Following this diagram in (Figure B.10), attach the cutout blank to the Plexiglas shield.

Figure B.10 Diagram for Attaching Blank to Shield and Shield to Biomek FX



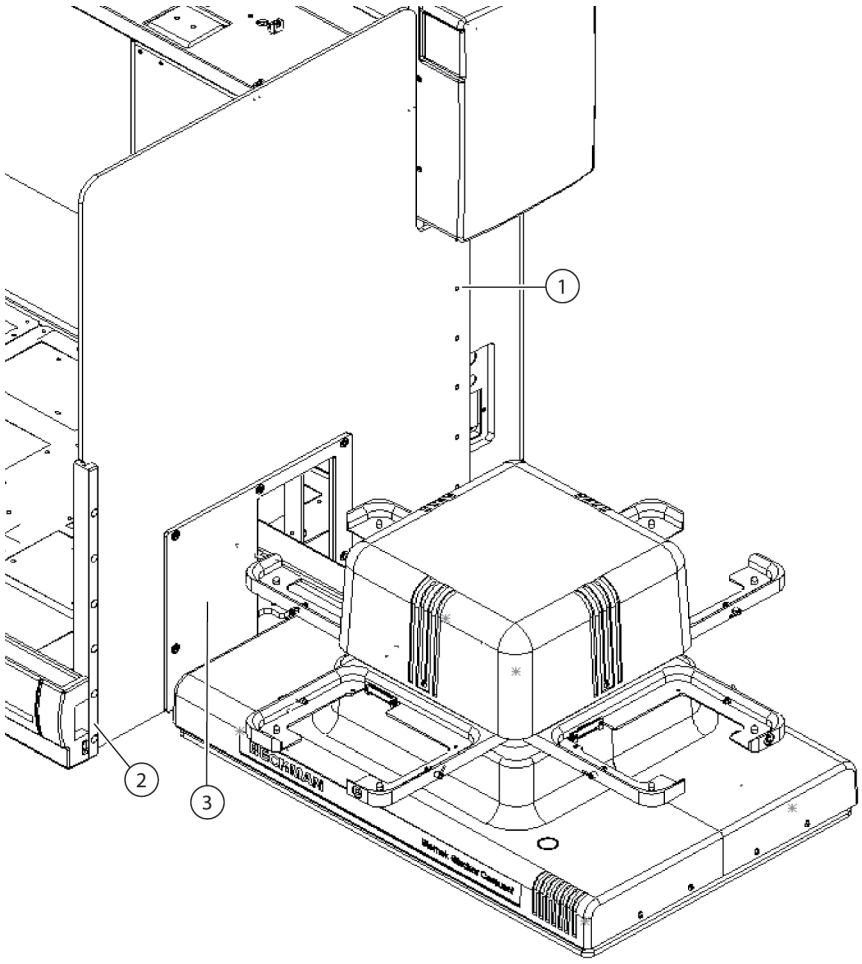
1. 719318
2. 804514 (7)
3. 810590 (5)
4. 864678 (5)
5. 719296
6. 804491 (6)
7. Biomek FX Right Front Rail End
8. 804409a (3)
9. 717710
10. 717750 (7)
11. Biomek FX Right Tower Side

3 Attach the shield to the Biomek FX.

NOTE Use the same attachment procedure for either side of the instrument.

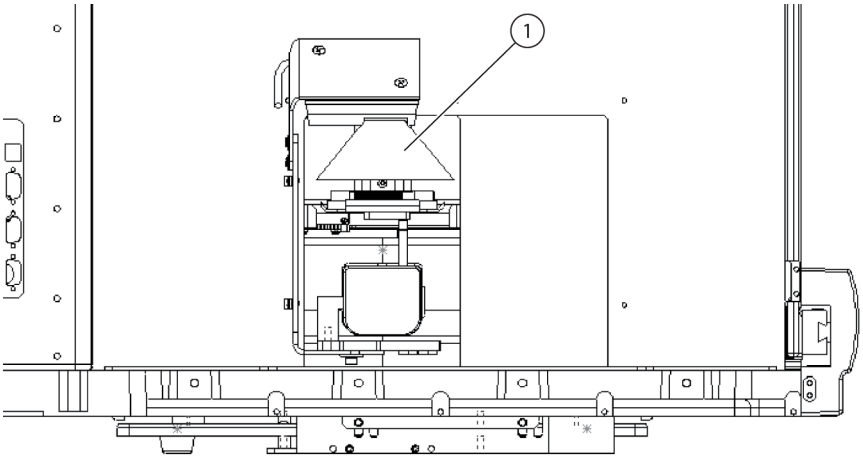
4 Align the shuttle to load and dispense labware through the Plexiglas side panel opening (Figure B.11) and (Figure B.12).

Figure B.11 Attach Side Shield



1. Side Shield Fasteners
2. Mount Bracket
3. Blanking Plate (Rear Orientation)

Figure B.12 Side View with Side Panel Attached

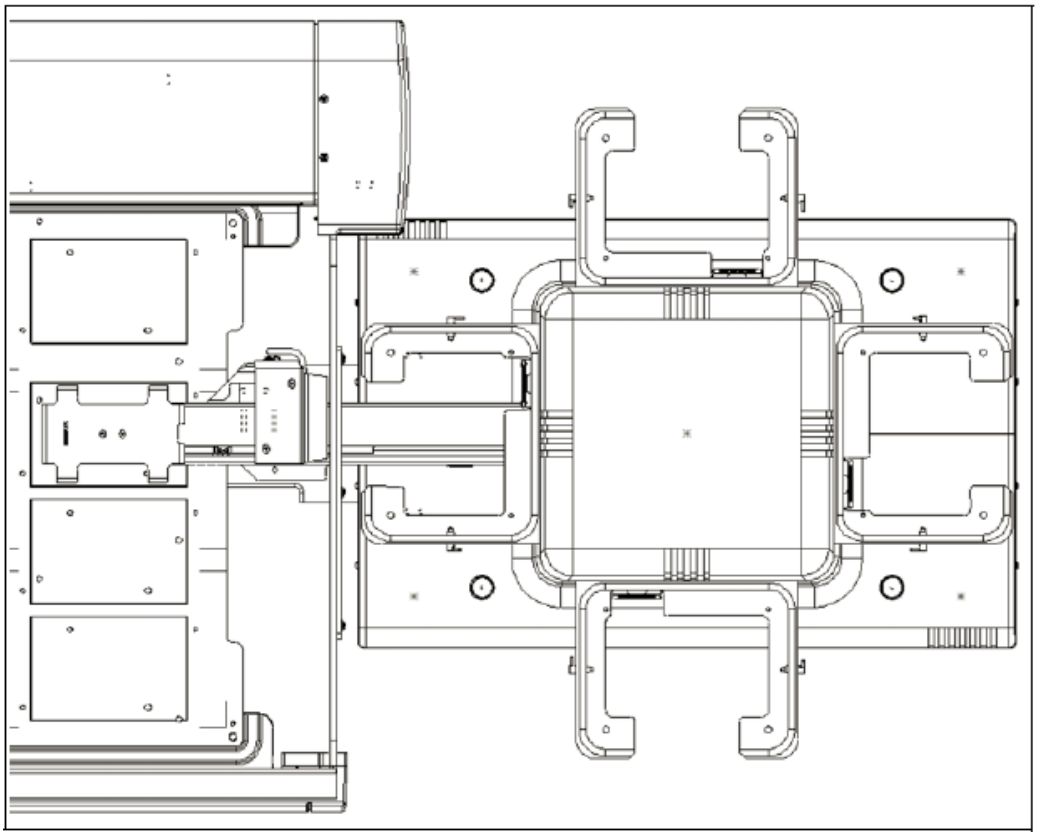


1. Bar Code Reader Laser Beam

5 Connect the Stacker Carousel (Figure B.13).

NOTE To connect the Stacker Carousel, connect the supplied serial cable from the side panel of the Stacker Carousel to a PC Controller's communication port. If more than two communication ports are required, install the extra serial ports in the PC at this time.

Figure B.13 Stacker Carousel Final Placement (Top View Rear Position, Right Side)



Operating the Stacker Carousel

To operate the Stacker Carousel, refer to the *Stacker Carousel User's Manual* (PN 148598), supplied with the Stacker Carousel.

NOTE Do not pipette liquid into labware that is on the Stacker Carousel shuttle.

NOTE The Stacker Carousel shuttle must be framed using Teach; do not use **Auto Teach** or **Manual Teach**. Refer to the *Stacker Carousel User's Manual* (PN 148598) for more information on framing the Stacker Carousel.

Preventive Maintenance and Troubleshooting

Refer to the *Stacker Carousel User's Manual* (PN 148598) for information on preventive maintenance and troubleshooting.

Integrating the Bar Code Reader

A bar code reader may be mounted to the Stacker Carousel to scan any one of the four sides of a microplate.

NOTE For maximum scanning reliability, it is recommended that labels be applied to the narrow sides of the microplate. This label orientation accommodates scanning of skewed labels and requires less adjustment of the bar code reader position.

⚠ WARNING

CLASS II LASER PRODUCT. THIS PRODUCT CONFORMS TO APPLICABLE REQUIREMENTS OF 21 CFR 1040 AT THE DATE OF MANUFACTURE.

Integrating the bar code reader requires:

- *Attaching the Bar Code Reader Bracket*
- *Attaching the Bar Code Reader to the Shuttle*
- *Positioning the Bar Code Reader*
- *Applying Power to the Bar Code Reader*
- *Aligning the Laser Beam*

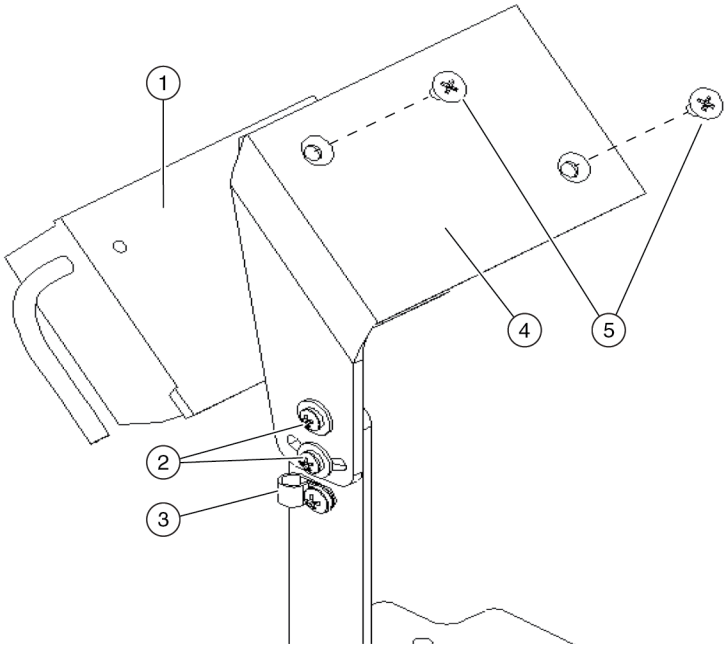
Attaching the Bar Code Reader Bracket

Attach the bar code reader mounting bracket to the bar code reader as follows:

1 Turn off the Stacker Carousel power switch.

2 Using a Phillips head screwdriver, fasten the bar code reader (Microscan MS710) to the bracket using two M4 x 6 flat head screws (Figure B.14).

Figure B.14 Bar Code Reader Bracket



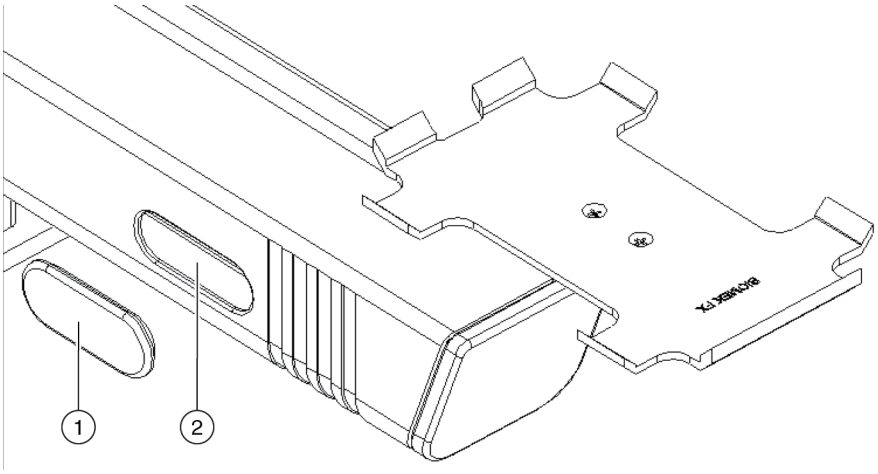
1. Bar Code Reader
2. Alignment Bracket Adjustment Screws
3. Bar Code Reader Clamp
4. Bar Code Reader Mount
5. M4 x 6 flat

Attaching the Bar Code Reader to the Shuttle

Attach the bar code reader to the Stacker Carousel shuttle as follows:

1 Remove the mount access cover (Figure B.15) and store in a safe place.

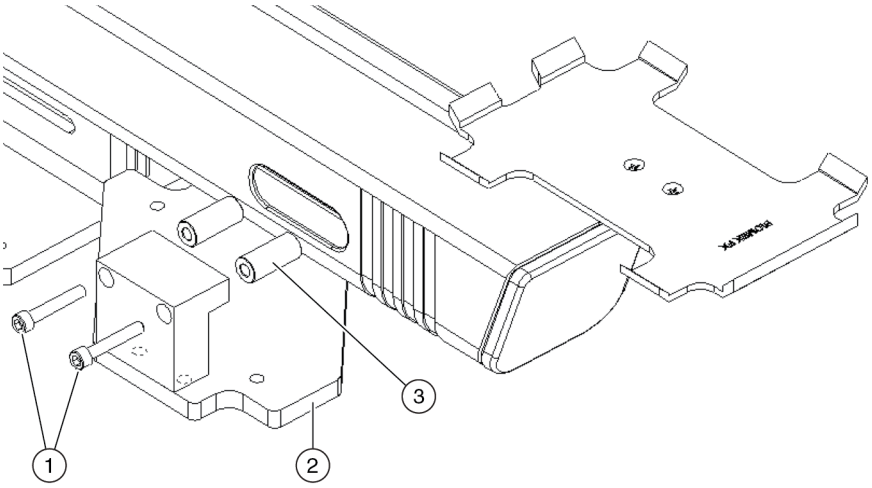
Figure B.15 Bar Code Reader Shuttle Mount Access Cover Removed



1. Shuttle Mount Access Cover
2. Bar Code Reader Shuttle Mount Access

2 Screw mount standoffs onto shuttle arm assembly mount points inside shuttle mount access (Figure B.16).

Figure B.16 Mounting Bracket Attachment

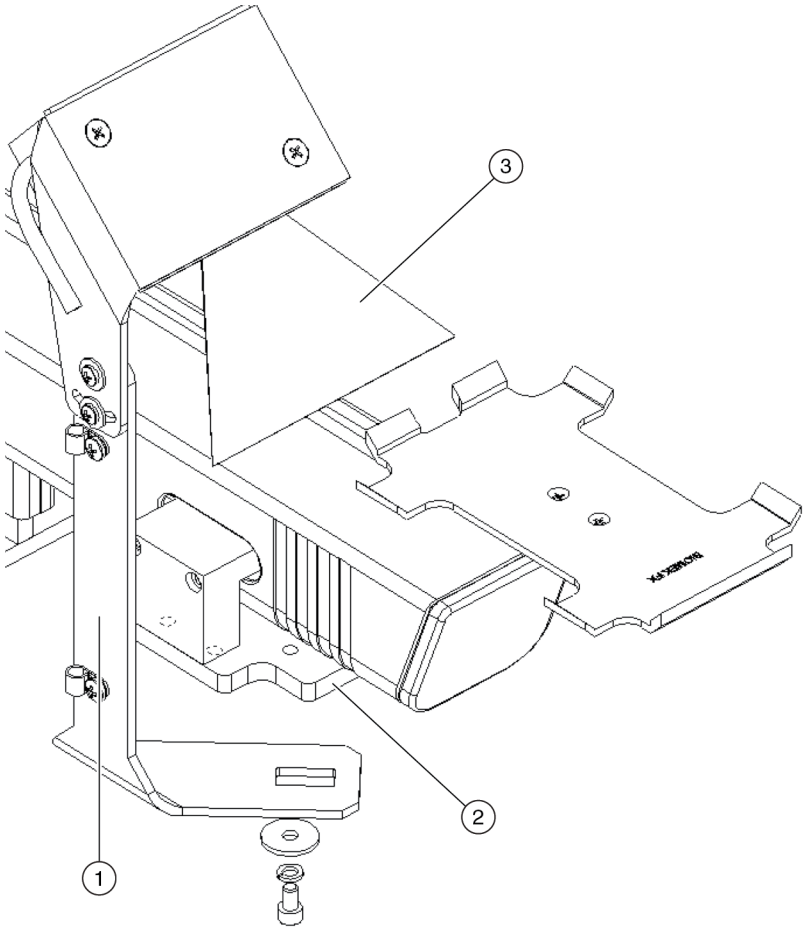


1. Fasteners
2. Mount Base
3. Mount Standoffs

3 Using the fasteners, attach mount base to standoffs.

4 Attach bar code reader bracket assembly to bar code reader mount base (Figure B.17).

Figure B.17 Mounting the Bar Code Reader



1. Bar Code Reader Bracket Assembly
2. Bar Code Reader Mount Base
3. Bar Code Reader Laser Beam

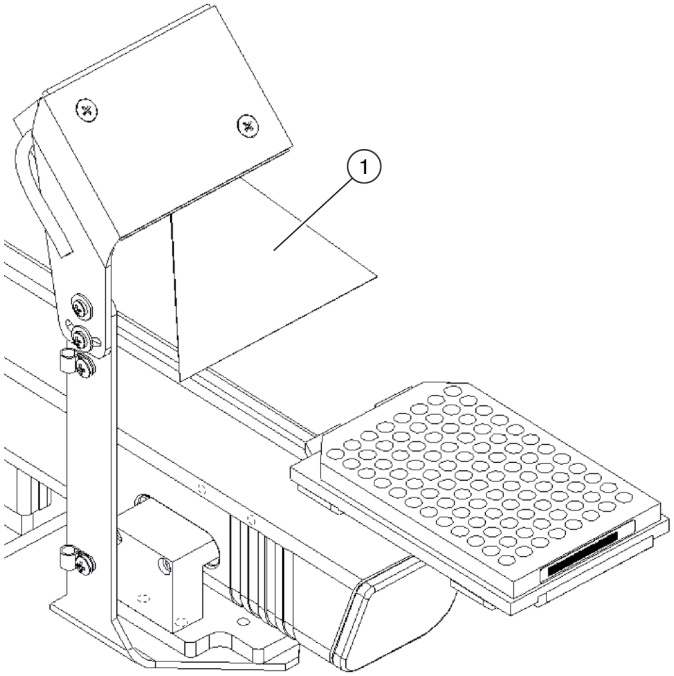
Positioning the Bar Code Reader

The Stacker Carousel bar code reader can be mounted to scan any one of the four sides of a microplate.

NOTE For maximum scanning reliability, it is recommended that labels be applied to the narrow sides of the microplate. This label orientation accommodates scanning of skewed labels and requires less adjustment of the bar code reader position

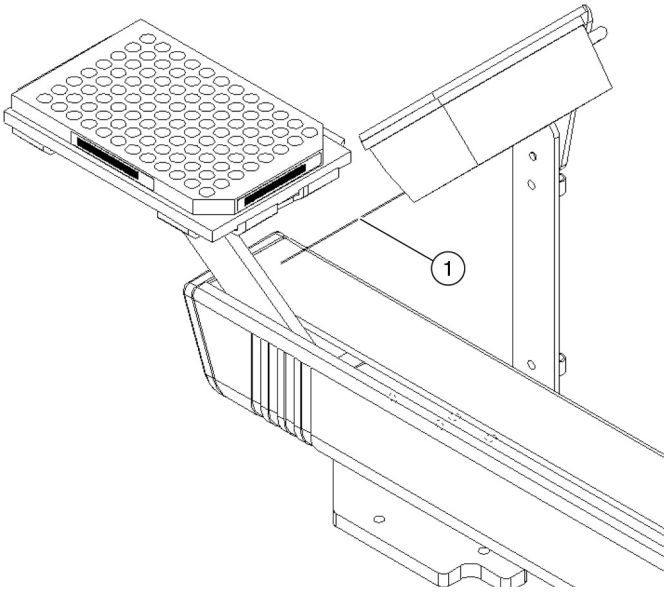
Position the bracket so the highest edge is parallel with and away from the microplate side to be scanned (Figure B.18 through Figure B.28).

Figure B.18 Bar Code Reader in Narrow Side Scanning Position



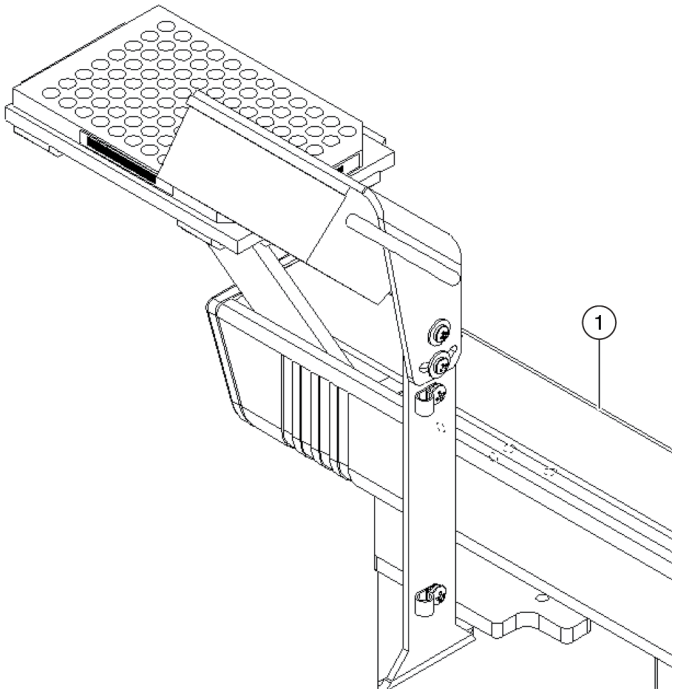
1. Laser Beam

Figure B.19 Bar Code Reader in Narrow Side Scanning Position



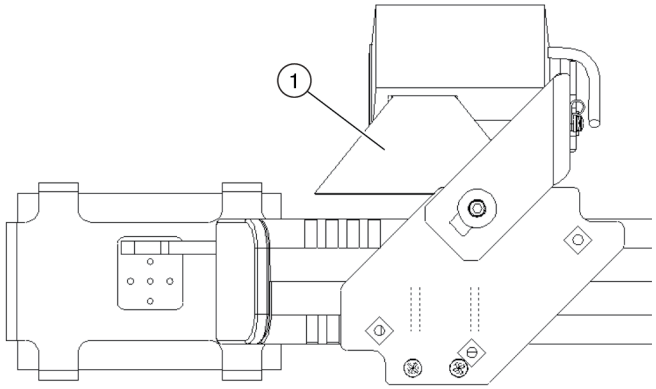
1. Laser Beam

Figure B.20 Bar Code Reader in Wide Right Side Scanning Position



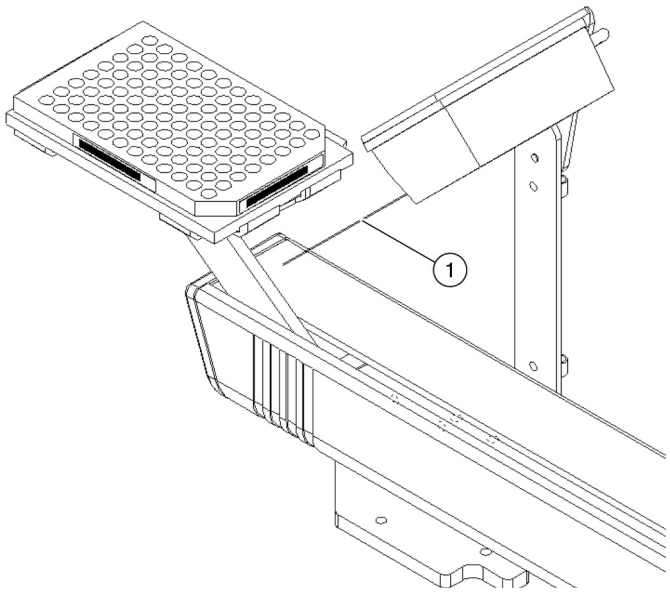
1. Laser Beam

Figure B.21 Bar Code Reader in Wide Right Side Scanning Position (Bottom View)



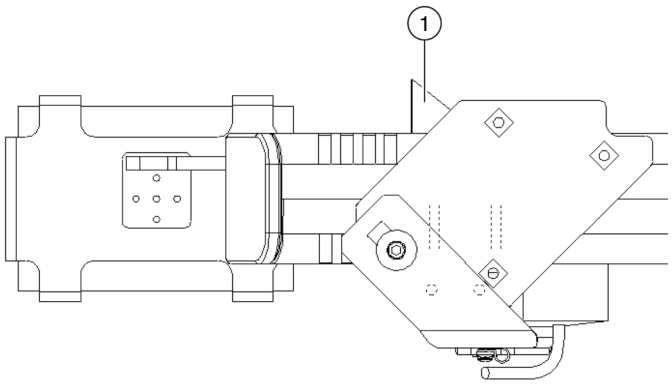
1. Laser Beam

Figure B.22 Bar Code Reader in Rear Narrow Side Scanning Position



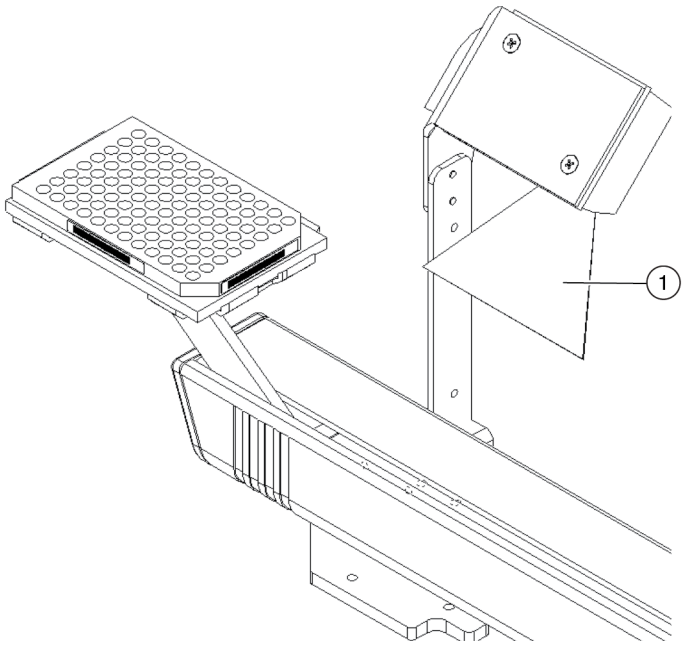
1. Laser Beam

Figure B.23 Bar Code Reader in Rear Narrow Side Scanning Position (Bottom View)



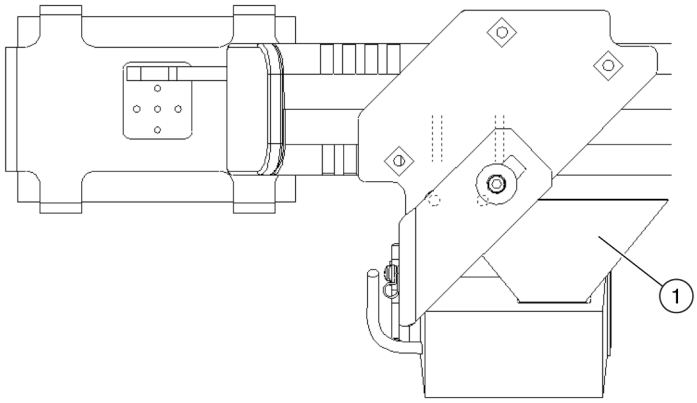
1. Laser Beam

Figure B.24 Bar Code Reader in Wide Left Side Scanning Position



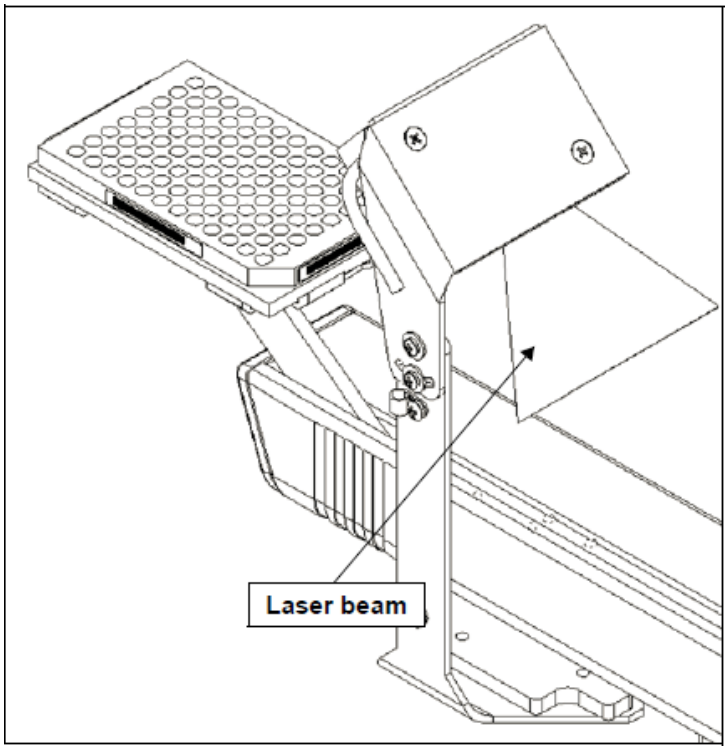
1. Laser Beam

Figure B.25 Bar Code Reader in Wide Left Side Scanning Position (Bottom View)



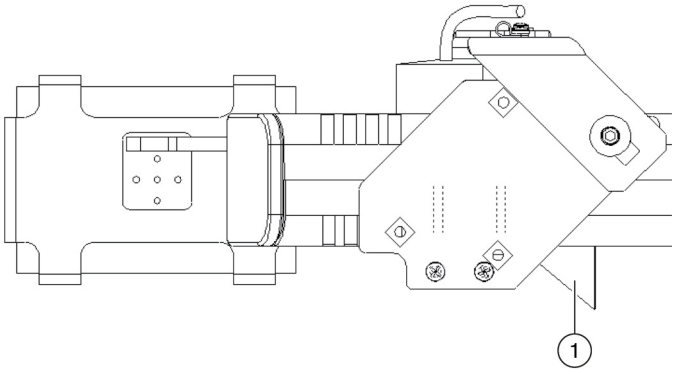
1. Laser Beam

Figure B.26 Bar Code Reader in Front Narrow Side Scanning Position



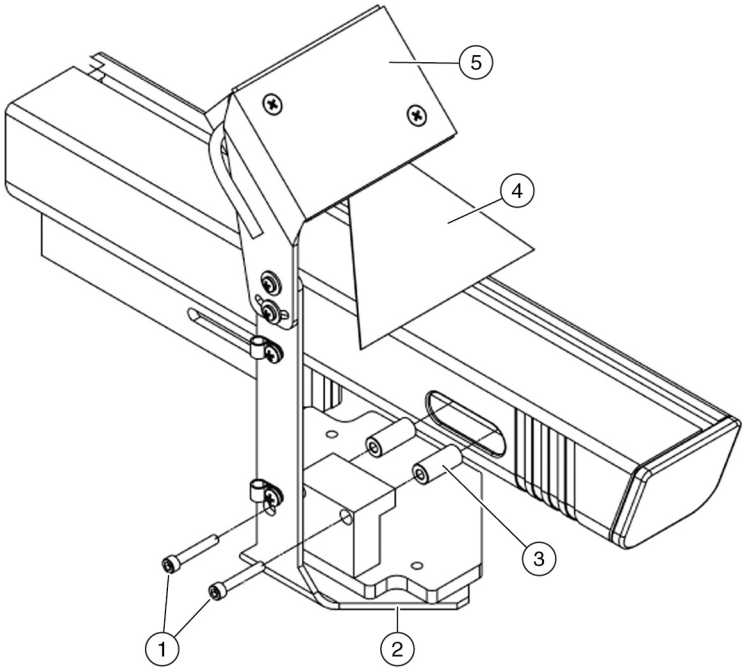
1. Laser Beam

Figure B.27 Bar Code Reader in Front Narrow Side Scanning Position (Bottom View)



1. Laser Beam

Figure B.28 Bar Code Reader Attachment Bracket



1. Bracket Fasteners
2. Bracket
3. Fastener Collars
4. Bar Code Reader Laser Beam
5. Bar Code Reader

Applying Power to the Bar Code Reader

⚠ CAUTION

To avoid serious damage to the instrument, make sure that the laboratory site voltage/frequency matches the voltage/frequency that was ordered for the instrument.

⚠ WARNING

Do not attempt to remove or replace covers while the unit is powered on. Disconnect power before removing or replacing a cover.

Apply power to the bar code reader as follows:

1 Secure the MS710 power cable to the rear panel of the Stacker Carousel.

NOTE Make sure the cable is connected to the port marked **BCR** and the cable routing does not interfere with the operation of the Stacker Carousel.

2 Turn on the Stacker Carousel power switch.

Aligning the Laser Beam

⚠ WARNING

Avoid direct exposure to the laser beam. Never look directly into the laser beam, and never leave the laser on, open, or unattended.

⚠ WARNING

Always have the laser module access cover, located on the bar code reader, in place when operating or troubleshooting the laser module.

To align the laser beam correctly:

1 Verify that the red laser beam is scanning down across the path of the shuttle. If the laser beam is not directed downward toward the shuttle, turn off the Stacker Carousel power switch.

2 Review *Positioning the Bar Code Reader*, before correcting the orientation of the MS710.

3 Visually check to make sure the red laser beam is scanning down across the path of the shuttle. If the laser beam is not directed downward toward the shuttle, turn off the Stacker Carousel power switch, and complete step 2 again. If the laser beam is scanning down across the path of the shuttle, continue to step 4.

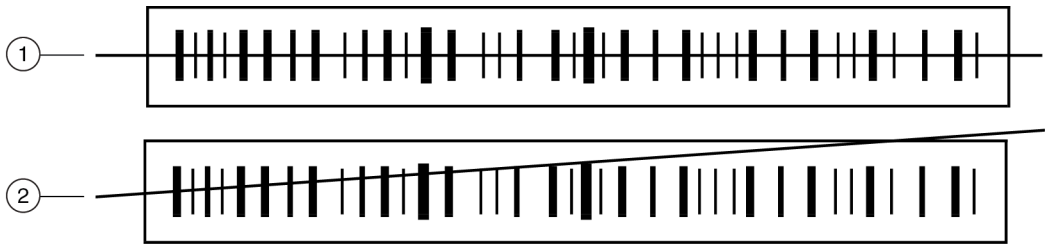
4 Make sure the laser scans down through the appropriate tunnel opening. For reading labels on the narrow side of the microplate, the laser should scan down through one of two slots in the top of the shuttle tunnel. For reading labels on the wide side of the microplate, the laser should scan down through one of the two slots in the side of the shuttle tunnel.

5 If the position of the MS710 needs to be adjusted; loosen the screw/washer assemblies that attach the bar code reader bracket (Figure B.28) to the shuttle tunnel, adjust the tilt of the bar code reader until it is aimed properly, then tighten the screw/washer assemblies.

6 To verity correct laser alignment, use the pendant to move the shuttle with the labeled microplate through the laser beam. The laser beam should pass over all vertical bars on the bar code label simultaneously.

NOTE Correct and incorrect laser/label alignments are shown in (Figure B.29).

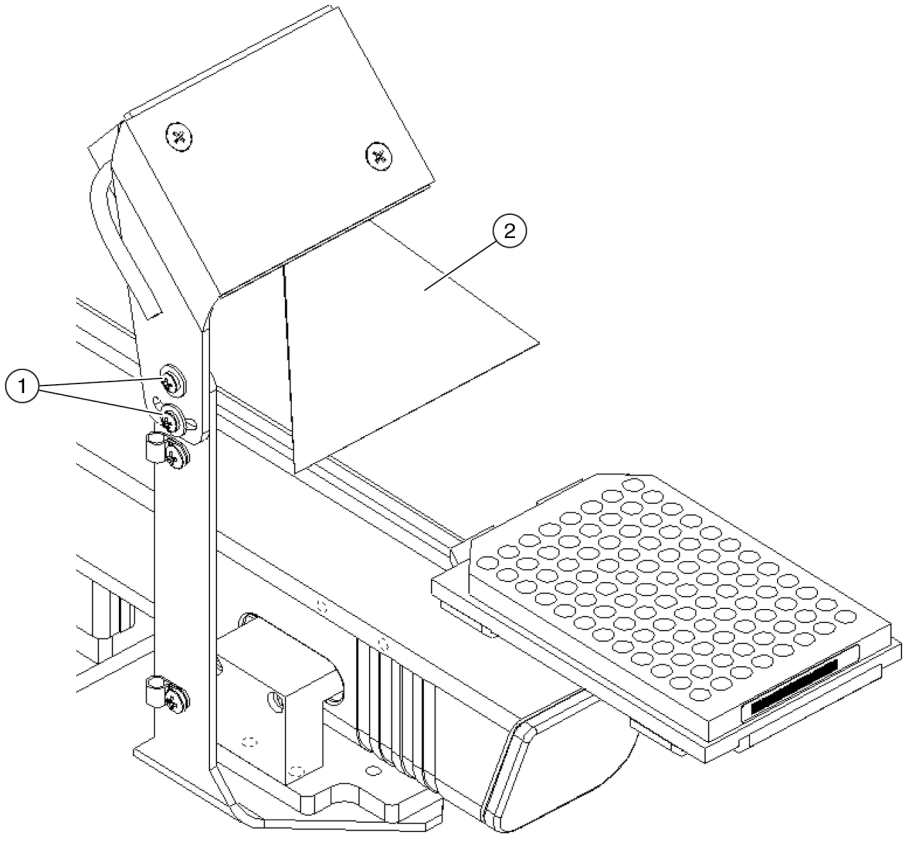
Figure B.29 Bar Code Reader — Laser Beam Position Over Bar Code Label



1. Correct Laser Alignment
2. Incorrect Laser Alignment

7 Using a Phillips head screwdriver, loosen laser alignment adjustment screws to adjust laser alignment as necessary (Figure B.30). Retighten screws when adjustment is complete.

Figure B.30 Adjust Laser Alignment as Necessary



1. Laser Alignment Adjustment Screws
2. Laser Beam

NOTE The bar code reader is pre-configured to read a variety of bar codes.

8 If the label needs to be applied to the microplate, it is recommended that a Beckman Coulter Print and Apply device be used to position the label on the microplate properly (Figure B.31).

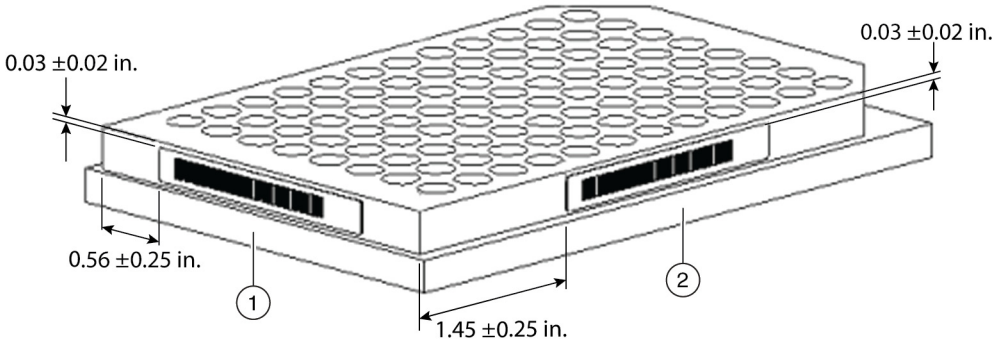
⚠ CAUTION

If labware other than that specified in the *Stacker Carousel User's Manual* (PN 148598) is used, an increase in bad reads or no reads may occur.

⚠ CAUTION

If a label is applied by any means other than the Beckman Coulter Print and Apply device, an increase in bad reads or no reads may occur.

Figure B.31 Label Positioning on Microplate



1. Narrow Side
2. Wide Side

Configuring the Stacker Carousel in Hardware Setup

Use **Hardware Setup** to install, configure, and remove Stacker Carousels. Refer to CHAPTER 3, *Configuring the Biomek FX in Hardware Setup* for more information on **Hardware Setup**.

Hardware Setup is accessed from within Biomek Software.

Installing Stacker Carousels

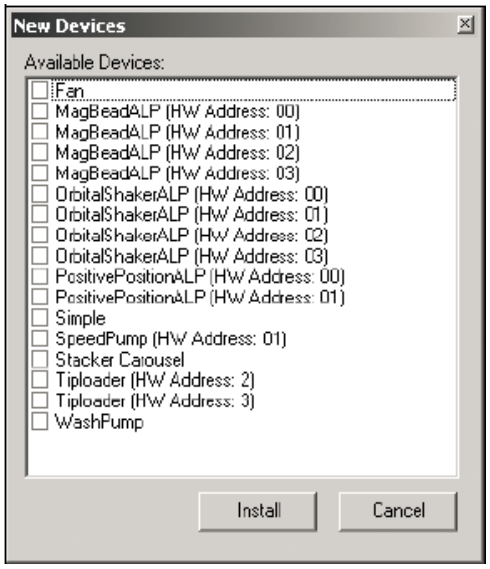
To install Stacker Carousels:

1 Choose **Start > Programs > Beckman Coulter > Biomek Software.** Biomek Software appears.

2 From the **Instrument** menu, choose **Hardware Setup**. **Hardware Setup** appears.

3 Choose **Add Device > Stacker Carousel**. **New Devices** appears (Figure B.32).

Figure B.32 New Devices



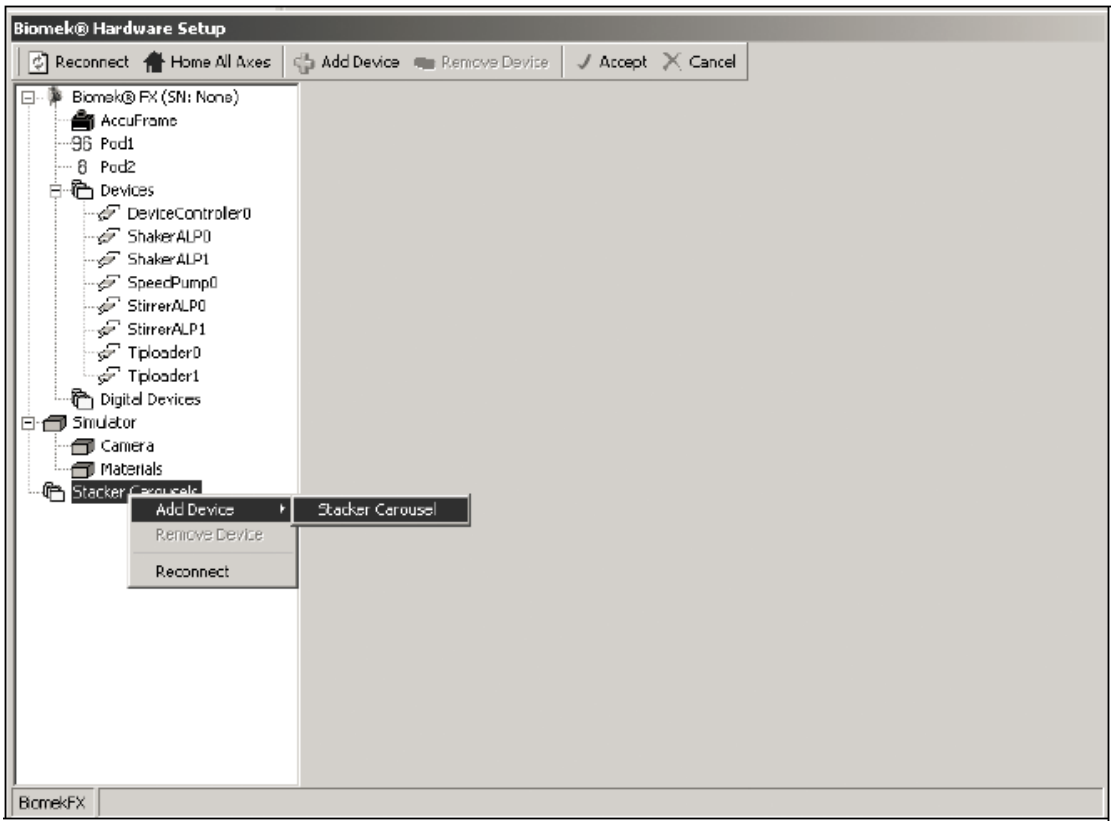
4 Check **Stacker Carousel** and choose **Install.** The device is displayed under Stacker Carousels in the left pane.

NOTE The first Stacker Carousel added to the instrument is named **Stacker1**, the second is named **Stacker2**, and so forth.

OR

Right-click **Stacker Carousel** and choose **Add Device > Stacker Carousel.** The device is displayed under **Stacker Carousels** in the left pane (Figure B.33).

Figure B.33 Adding a Stacker Carousel

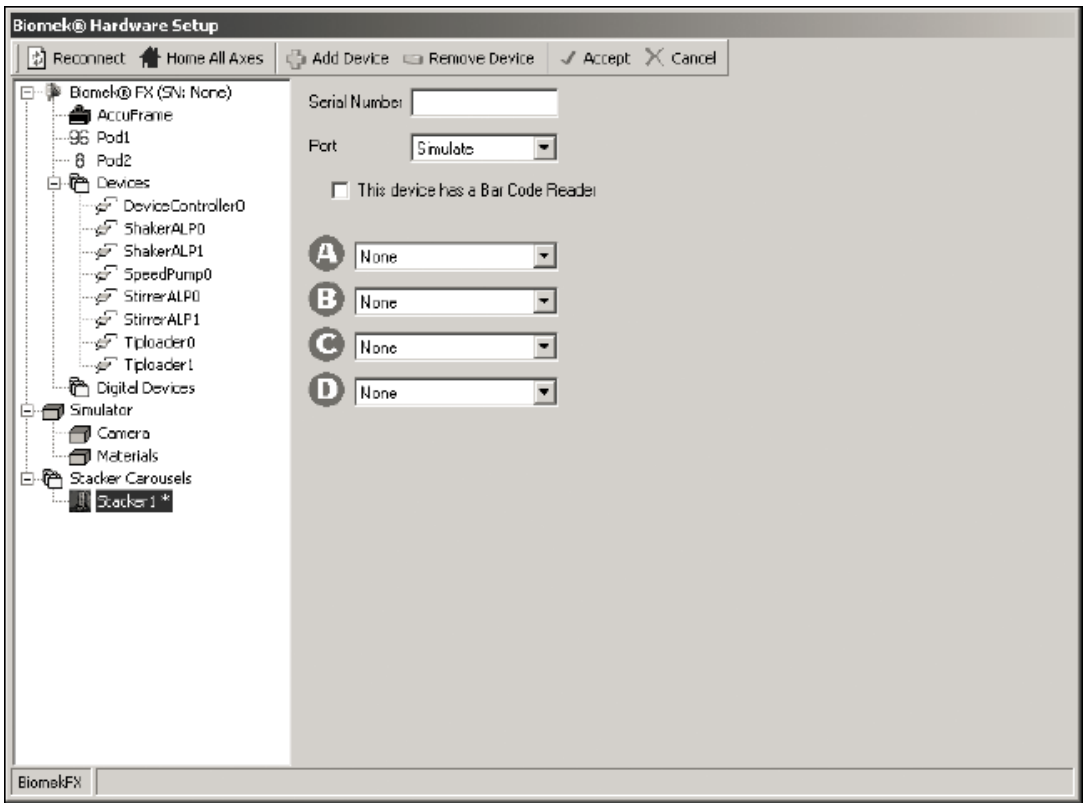


Configuring Stacker Carousels

To configure Stacker Carousels:

1 In **Hardware Setup**, select the desired stacker under Stacker Carousels in the left pane of **Hardware Setup** and the configuration view appears in the right pane (Figure B.34).

Figure B.34 Hardware Setup Showing the Configuration View for a Stacker Carousel



2 Enter the correct **Serial Number** to correspond to the serial number on the Stacker Carousel.

3 Choose the appropriate **Port**.

4 Check **This device has a Bar Code Reader** when a bar code reader has been attached to the Stacker Carousel.

5 Choose the appropriate stacker type for each stacker on the carousel.

NOTE Up to four stackers may be attached to the Stacker Carousel. Stackers are identified on the Stacker Carousel as A, B, C, or D. Make sure the correct stacker type is selected for each stacker on the carousel. Stacker types may be **Stacker 10**, **Stacker 20**, or **Stacker HD**.

6 Choose **Accept**. **Hardware Setup** closes

NOTE **Accept** must be chosen after the Stacker Carousel has been configured to allow **Hardware Setup** to accept the configuration.

Removing Stacker Carousels

To remove Stacker Carousels:

1 In **Hardware Setup**, right-click the desired device under **Stacker Carousels**.

2 Choose **Remove Device**. The device is removed from the installed stackers under **Stacker Carousels** in the left pane.

OR

1 Select the desired stacker under **Stacker Carousel**.

2 Choose **Remove Device** from the top of **Hardware Setup**. The device is removed from the installed devices under **Stacker Carousels** in the left pane.

Framing the Stacker Carousel

The Stacker Carousel is framed using the AccuFrame and the Framing Tool Adaptor.

To frame the Stacker Carousel:

1 Using the Control Pendant, choose **SHUTTLE IN** and **SHUTTLE OUT** to ensure the shuttle of the Stacker Carousel is in the correct position for framing.

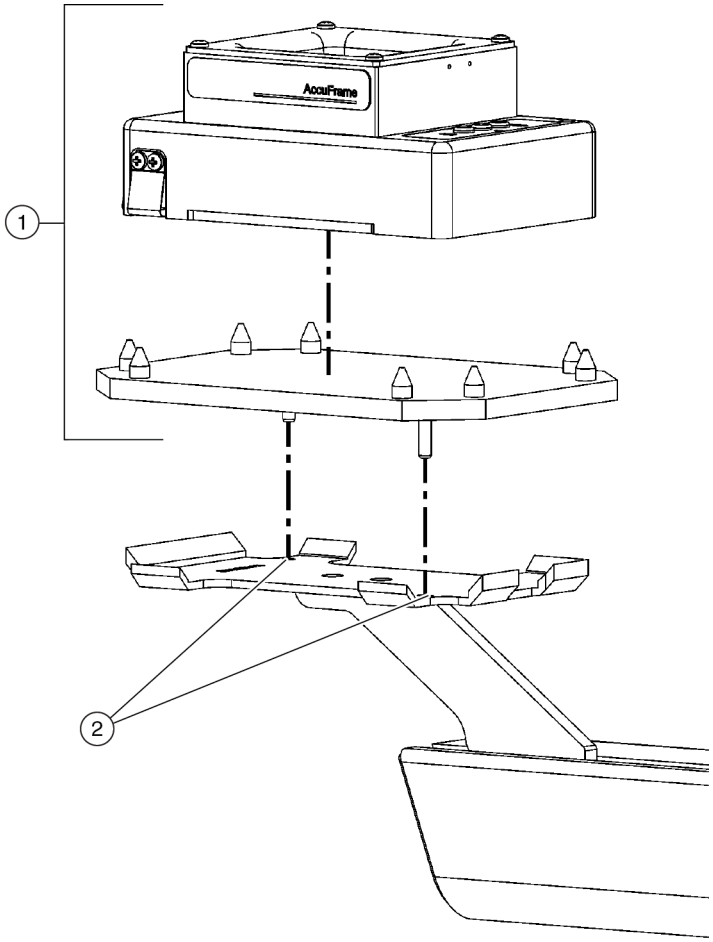
NOTE Refer to the *Stacker Carousel User's Manual* (PN 148598) for more information on using the Control Pendant.

⚠ CAUTION

To prevent damage to the shuttle, first place the AccuFrame into the Framing Tool Adaptor. Then place the AccuFrame with the attached adaptor on the shuttle.

2 Manually place the AccuFrame into the Framing Tool Adaptor by placing the front right corner first and pushing the AccuFrame gently down into the adaptor (Figure B.35).

Figure B.35 Adding the AccuFrame and Framing Tool Adaptor to the Stacker Carousel Shuttle



1. First, gently push the AccuFrame down into the adaptor.
2. Then, place the AccuFrame (with the attached adaptor) on the shuttle so the locating pins on the adaptor align with the locating holes on the shuttle.

3 Place the AccuFrame with the attached adaptor on the shuttle of the Stacker Carousel so that the locating pins on the bottom of the Framing Tool Adaptor align with the locating holes on the shuttle (Figure B.35).

4 Turn off power to main unit before connecting the AccuFrame.

⚠ CAUTION

Turn off power to the Biomek FX instrument before attaching or removing AccuFrame from the instrument deck.

5 Plug the AccuFrame into any available CAN port on the Biomek FX tower.

⚠ WARNING

Make sure the light curtain is not violated by the AccuFrame cable. If the light curtain is violated, the framing process halts immediately.

⚠ WARNING

Make sure the AccuFrame cable does not interfere with pod movement.

6 Turn on power to main unit.

7 Frame the Stacker Carousel according to procedures outlined in CHAPTER 4, *Framing the Biomek FX*.

NOTE The Stacker Carousel shuttle must be framed using **Teach**; do not use **Auto Teach** or **Manual Teach**.

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Beckman Coulter, Inc.
Warranty and Returned Goods Requirements

All standard Beckman Coulter, Inc. policies governing returned goods apply to this product. Subject to the exceptions and upon the conditions stated below, the Company warrants that the products sold under this sales agreement shall be free from defects in workmanship and materials for one year after delivery of the products to the original Purchaser by the Company, and if any such product should prove to be defective within such one year period, the Company agrees, at its option, either (1) to correct by repair or at the Company's election by replacement, any such defective product provided that investigation and factory inspection discloses that such defect developed under normal and proper use, or (2) to refund the purchase price. The exceptions and conditions mentioned above are as follows:

1. Components or accessories manufactured by the Company which by their nature are not intended to and will not function for one year are warranted only to reasonable service for a reasonable time. What constitutes a reasonable time and a reasonable service shall be determined solely by the Company. A complete list of such components and accessories is maintained at the factory.
2. The Company makes no warranty with respect to components or accessories not manufactured by it. In the event of defect in any such component or accessory, the Company will give reasonable assistance to Purchaser in obtaining the manufacturer's own warranty.
3. Any product claimed to be defective must, if required by the Company, be returned to the factory, properly decontaminated of any chemical, biological, or radioactive hazardous material, transportation charges prepaid, and will be returned to the Purchaser with transportation charges collect unless the product is found to be defective.
4. The Company shall be released from all obligations under all warranties, either expressed or implied, if any product covered hereby is repaired or modified by persons other than its own authorized service personnel, unless such repair by others is made with the written consent of the Company.
5. If the product is a reagent or the like, it is warranted only to conform to the quantity and content and for the period (but not in excess of one year) stated on the label at the time of delivery.

It is expressly agreed that the above warranty shall be in lieu of all warranties of fitness and of the warranty of merchantability, and that the company shall have no liability for special or consequential damages of any kind or from any cause whatsoever arising out of the manufacture, use, sale, handling, repair, maintenance, or replacement of any of the products sold under the sales agreement.

Representatives and warranties made by any person, including dealers and representatives of the Company, which are consistent or in conflict with the terms of this warranty, shall not be binding upon the Company unless reduced in writing and approved by an expressly authorized officer of the Company.

Parts replaced during the warranty period are warranted to the end of the instrument warranty.

NOTE
Performance characteristics and specifications are only warranted when Beckman Coulter replacement parts are used.

Except as provided in writing signed by an officer to Beckman Coulter, Inc., this system and any related documentation are provided “as is” without warranty of any kind, expressed or implied, including that the system is “error free.” This information is presented in good faith, but Beckman Coulter does not warrant, guarantee, or make any representations regarding the use or the results of the use of this system and related documentation in terms of correctness, accuracy, reliability, currentness, omissions, or otherwise. The entire risk as to the use, results, and performance of this system and related documentation is assumed by the user.

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